

Package ‘Momocs’

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Title Morphometrics using R

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Description The goal of 'Momocs' is to provide a complete, convenient, reproducible and open-source toolkit for 2D morphometrics. It includes most common 2D morphometrics approaches on outlines, open outlines, configurations of landmarks, traditional morphometrics, and facilities for data preparation, manipulation and visualization with a consistent grammar throughout. It allows reproducible, complex morphometrics analyses and other morphometrics approaches should be easy to plug in, or develop from, on top of this canvas.

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Encoding UTF-8

URL <https://github.com/MomX/Momocs/>

BugReports <https://github.com/MomX/Momocs/issues>

Depends R(>= 3.2)

LazyData true

Imports cluster, dendextend, dplyr, magrittr, geometry, geomorph, ggplot2, graphics, grDevices, jpeg, MASS, progress, RColorBrewer, rgeos, sp, utils, vegan, tibble

Suggests devtools, knitr, rmarkdown, testthat, covr, roxygen2

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add_ldk	<i>Adds new landmarks on Out and Opn objects</i>
---------	--

Description

Helps to add new landmarks on a Coo object on top of existing ones. The number of landmarks must be specified and rows indices that correspond to the nearest points clicked on every outlines are stored in the \$ldk slot of the Coo object.

Usage

```
add_ldk(Coo, nb.ldk)
```

Arguments

Coo	an Out or Opn object
nb.ldk	the number of landmarks to add on every shape

Details

Note that if no landmarks are already defined, then this function is equivalent to [def_ldk](#).

Value

an Out or an Opn object with some landmarks defined

See Also

Other ldk/slidings methods: [def_ldk\(\)](#), [def_slidings\(\)](#), [get_ldk\(\)](#), [get_slidings\(\)](#), [rearrange_ldk\(\)](#), [slidings_scheme\(\)](#)

Examples

```
## Not run:
hearts <- slice(hearts, 1:5) # to make it shorter to try
# click on 3 points, 5 times.
hearts <- def_ldk(hearts, 3)
# Don't forget to save the object returned by def_ldk...
hearts2 <- add_ldk(hearts, 3)
stack(hearts2)
hearts2$ldk

## End(Not run)
```

apodemus

Data: Outline coordinates of Apodemus (wood mouse) mandibles

Description

Data: Outline coordinates of Apodemus (wood mouse) mandibles

Format

A [Out](#) object 64 coordinates of 30 wood molar outlines.

Source

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *Journal of Biogeography* 30:1617-1628. see <https://onlinelibrary.wiley.com/doi/full/10.1046/j.1365-3113.2003.00281.x>

See Also

Other datasets: [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

arrange

Arrange rows by variables

Description

Arrange shapes by variables, from the \$fac. See examples and `?dplyr::arrange`.

Usage

```
arrange(.data, ...)
```


Arguments

.data a Coo, Coe, PCA object
 ... logical conditions

Details

dplyr verbs are maintained.

Value

a Momocs object of the same class.

See Also

Other handling functions: [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea
# we create a new column
olea %>% mutate(id=1:length(.)) %$$ fac$id
# same but now, shapes are arranged in a desc order, based on id
olea %>% mutate(id=1:length(.)) %>% arrange(desc(id)) %$$ fac$id
```

as_df

Turn Momocs objects into tidy data_frames

Description

Used in particular for compatibility with the tidyverse

Usage

```
as_df(x, ...)

## S3 method for class 'Coo'
as_df(x, ...)

## S3 method for class 'Coe'
as_df(x, ...)

## S3 method for class 'PCA'
as_df(x, retain, ...)

## S3 method for class 'LDA'
as_df(x, retain, ...)
```

Arguments

x	an object, typically a Momocs object
...	useless here
retain	numeric for use with scree methods. Default to all. If <1, enough axes to retain this proportion of variance; if >1, this number of axes.

Value

a `dplyr::tibble()`

See Also

Other bridges functions: [bridges](#), [complex](#), [export\(\)](#)

Examples

```
# first, some (baby) objects
b <- bot %>% coo_sample(12)
bf <- b %>% efourier(5, norm=TRUE)
# Coo object
b %>% as_df
# Coe object
bf %>% as_df

# PCA object
bf %>% PCA %>% as_df # all PCs by default
bf %>% PCA %>% as_df(2) # or 2
bf %>% PCA %>% as_df(0.99) # or enough for 99%

# LDA object
bf %>% LDA(~fake) %>% as_df
# same options apply
```

at_least

Retain groups with at least n shapes

Description

Examples are self-speaking.

Usage

```
at_least(x, fac, N)
```

Arguments

x	any Momocs object
fac	the id of name of the \$fac column
N	minimal number of individuals to retain the group

Note

if N is too ambitious the original object is returned with a message

See Also

Other handling functions: [arrange\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
table(trilo$onto)
at_least(trilo, "onto", 9)
at_least(trilo, "onto", 16)
at_least(trilo, "onto", 2000) # too ambitious !
```

bezier

Calculates Bezier coefficients from a shape

Description

Calculates Bezier coefficients from a shape

Usage

```
bezier(coo, n)
```

Arguments

coo a matrix or a list of (x; y) coordinates
n the degree, by default the number of coordinates.

Value

a list with components:

- \$J matrix of Bezier coefficients
- \$B matrix of Bezier vertices.

Note

Directly borrowed for Claude (2008), and also called bezier there. Not implemented for open outlines but may be useful for other purposes.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other bezier functions: [bezier_i\(\)](#)

Examples

```
set.seed(34)
x <- coo_sample(efourier_shape(), 5)
plot(x, ylim=c(-3, 3), asp=1, type='b', pch=20)
b <- bezier(x)
bi <- bezier_i(b$B)
lines(bi, col='red')
```

bezier_i

Calculates a shape from Bezier coefficients

Description

Calculates a shape from Bezier coefficients

Usage

```
bezier_i(B, nb.pts = 120)
```

Arguments

B a matrix of Bezier vertices, such as those produced by [bezier](#)
nb.pts the number of points to sample along the curve.

Value

a matrix of (x; y) coordinates

Note

Directly borrowed for Claude (2008), and called `beziercurve` there. Not implemented for open outlines but may be useful for other purposes.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other bezier functions: [bezier\(\)](#)

Examples

```

set.seed(34)
x <- coo_sample(efourier_shape(), 5)
plot(x, ylim=c(-3, 3), asp=1, type='b', pch=20)
b <- bezier(x)
bi <- bezier_i(b$B)
lines(bi, col='red')

```

bot

*Data: Outline coordinates of beer and whisky bottles.***Description**

Data: Outline coordinates of beer and whisky bottles.

Format

A **Out** object containing the outlines coordinates and a grouping factor for 20 beer and 20 whisky bottles

Source

Images have been grabbed on the internet and prepared by the package's authors. No particular choice has been made on the dimension of the original images or the brands cited here.

See Also

Other datasets: [apodemus](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

boxplot.OutCoe

*Boxplot of morphometric coefficients***Description**

Explores the distribution of coefficient values.

Usage

```

## S3 method for class 'OutCoe'
boxplot(x, ...)

```

Arguments

x the **Coe** object
... useless here

Value

a ggplot2 object

See Also

Other Coe_graphics: [hcontrib\(\)](#)

Examples

```
# on OutCoe
bot %>% efourier(9) %>% rm_harm(1) %>% boxplot()

data(olea)
op <- opoly(olea)
boxplot(op)
```

boxplot.PCA

Boxplot on PCA objects

Description

Boxplot on PCA objects

Usage

```
## S3 method for class 'PCA'
boxplot(x, fac = NULL, nax, ...)
```

Arguments

x	PCA, typically obtained with PCA
fac	factor, or a name or the column id from the \$fac slot
nax	the range of PC to plot (1 to 99pc total variance by default)
...	useless here

Value

a ggplot object

Examples

```
bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)
boxplot(bot.p)
p <- boxplot(bot.p, 1)
#p + theme_minimal() + scale_fill_grey()
#p + facet_wrap(~PC, scales = "free")
```

breed	<i>Jitters Coe (and others) objects</i>
-------	---

Description

This methods applies column-wise on the coe of any [Coe](#) object but relies on a function that can be used on any matrix. It simply uses [mnorm](#) with the mean and sd calculated for every column (or row). For a Coe object, on every colum, randomly generates coefficients values centered on the mean of the column, and with a sd equals to it standard deviates multiplied by rate.

Usage

```
breed(x, ...)
```

Default S3 method:

```
breed(x, fac, margin = 2, size, rate = 1, ...)
```

S3 method for class 'Coe'

```
breed(x, fac, size, rate = 1, ...)
```

Arguments

x	the object to permute
...	useless here
fac	a column, a formula or a column id from \$fac
margin	numeric whether 1 or 2 (rows or columns)
size	numeric the required size for the final object, same size by default
rate	numeric the number of sd for mnorm , 1 by default.

See Also

Other farming: [perm\(\)](#)

Examples

```
m <- matrix(1:12, nrow=3)
breed(m, margin=2, size=4)
breed(m, margin=1, size=10)
```

```
bot.f <- efourier(bot, 12)
bot.m <- breed(bot.f, size=80)
bot.m %>% PCA %>% plot
```

```
# breed fac wise
# bot.f %>% breed(~type, size=50) %>% PCA %>% plot(~type)
```

bridges

Convert between different classes

Description

Convert between different classes

Usage

`l2m(l)`

`m2l(m)`

`d2m(d)`

`m2d(m)`

`l2a(l)`

`a2l(a)`

`a2m(a)`

`m2a(m)`

`m2ll(m, index = NULL)`

Arguments

<code>l</code>	list with x and y coordinates as components
<code>m</code>	matrix of (x; y) coordinates
<code>d</code>	data.frame with two columns
<code>a</code>	array of (x; y) coordinates
<code>index</code>	numeric, the number of coordinates for every slice

Value

the data in the required class

Note

`a2m/m2a` change, by essence, the dimension of the data. `m2ll` is used internally to handle `coo` and `cur` in `Ldk` objects but may be useful elsewhere

See Also

Other bridges functions: [as_df\(\)](#), [complex](#), [export\(\)](#)

Examples

```

# matrix/list
wings[1] %>% coo_sample(4) %>%
  m2l() %T>% print %>%      # matrix to list
  l2m()                      # and back

# data.frame/matrix
wings[1] %>% coo_sample(4) %>%
  m2d() %T>% print %>%      # matrix to data.frame
  d2m                      # and back

# list/array
wings %>% slice(1:2) %$$
coo %>% l2a %T>% print %>%  # list to array
a2l                          # and back

# array/matrix
wings %>% slice(1:2) %$$
l2a(coo) %>%                # and array (from a list)
a2m %T>% print %>%          # to matrix
m2a                          # and back

# m2ll
m2ll(wings[1], c(6, 4, 3, 5)) # grab slices and coordinates

```

calibrate_deviations *Quantitative calibration, through deviations, for Out and Opn objects*

Description

Calculate deviations from original and reconstructed shapes using a range of harmonic number.

Usage

```

calibrate_deviations()

calibrate_deviations_efourier(
  x,
  id = 1,
  range,
  norm.centsize = TRUE,
  dist.method = edm_nearest,
  interpolate.factor = 1,
  dist.nbpts = 120,
  plot = TRUE
)

calibrate_deviations_tfourier(

```

```
x,  
id = 1,  
range,  
norm.centsize = TRUE,  
dist.method = edm_nearest,  
interpolate.factor = 1,  
dist.nbpts = 120,  
plot = TRUE  
)  
  
calibrate_deviations_rfouier(  
x,  
id = 1,  
range,  
norm.centsize = TRUE,  
dist.method = edm_nearest,  
interpolate.factor = 1,  
dist.nbpts = 120,  
plot = TRUE  
)  
  
calibrate_deviations_sfouier(  
x,  
id = 1,  
range,  
norm.centsize = TRUE,  
dist.method = edm_nearest,  
interpolate.factor = 1,  
dist.nbpts = 120,  
plot = TRUE  
)  
  
calibrate_deviations_npoly(  
x,  
id = 1,  
range,  
norm.centsize = TRUE,  
dist.method = edm_nearest,  
interpolate.factor = 1,  
dist.nbpts = 120,  
plot = TRUE  
)  
  
calibrate_deviations_opoly(  
x,  
id = 1,  
range,  
norm.centsize = TRUE,
```

```

    dist.method = edm_nearest,
    interpolate.factor = 1,
    dist.nbpts = 120,
    plot = TRUE
)

calibrate_deviations_dfourier(
  x,
  id = 1,
  range,
  norm.centsize = TRUE,
  dist.method = edm_nearest,
  interpolate.factor = 1,
  dist.nbpts = 120,
  plot = TRUE
)

```

Arguments

<code>x</code>	and Out or Opn object on which to calibrate_deviations
<code>id</code>	the shape on which to perform calibrate_deviations
<code>range</code>	vector of harmonics (or degree for opoly and npoly on Opn) on which to perform calibrate_deviations. If not provided, the harmonics corresponding to 0.9, 0.95 and 0.99% of harmonic power are used.
<code>norm.centsize</code>	logical whether to normalize deviation by the centroid size
<code>dist.method</code>	a method such as edm_nearest to calculate deviations
<code>interpolate.factor</code>	a numeric to increase the number of points on the original shape (1 by default)
<code>dist.nbpts</code>	numeric the number of points to use for deviations calculations
<code>plot</code>	logical whether to print the graph (FALSE is you just want the calculations)

Details

Note that from version 1.1, the calculation changed and fixed a problem. Before, the 'best' possible shape was calculated using the highest possible number of harmonics. This worked well for `efourier` but not for others (eg `rfourier`, `tfourier`) as they are known to be unstable with high number of harmonics. From now on, Momocs uses the 'real' shape, as it is (so it must be centered) and uses [coo_interpolate](#) to produce `interpolate.factor` times more coordinates as the shape has and using the default `dist.method`, eg [edm_nearest](#), the latter finds the euclidean distance, for each point on the reconstructed shape, the closest point on this interpolated shape. `interpolate.factor` being set to 1 by default, no interpolation will be made in you do not ask for it. Note, that interpolation to decrease artefactual errors may also be done outside `calibrate_deviations` and will be probably be removed from it in further versions.

Note also that this code is quite old now and would need a good review, planned for 2018.

For *poly methods on Opn objects, the deviations are calculated from a degree 12 polynomial.

Value

a ggplot object and the full list of intermediate results. See examples.

See Also

Other calibration: [calibrate_harmonicpower\(\)](#), [calibrate_r2\(\)](#), [calibrate_reconstructions](#)

Examples

```
b5 <- slice(bot, 1:5) #for the sake of speed
b5 %>% calibrate_deviations_efourier()
b5 %>% calibrate_deviations_rfourier()
b5 %>% calibrate_deviations_tfourier()
b5 %>% calibrate_deviations_sfourier()

o5 <- slice(olea, 1:5) #for the sake of speed
o5 %>% calibrate_deviations_opoly()
o5 %>% calibrate_deviations_npoly()
o5 %>% calibrate_deviations_dfourier()
```

calibrate_harmonicpower

Quantitative calibration, through harmonic power, for Out and Opn objects

Description

Estimates the number of harmonics required for the four Fourier methods implemented in Momocs: elliptical Fourier analysis (see [efourier](#)), radii variation analysis (see [rfourier](#)) and tangent angle analysis (see [tfourier](#)) and discrete Fourier transform (see [dfourier](#)). It returns and can plot cumulated harmonic power whether dropping the first harmonic or not, and based and the maximum possible number of harmonics on the Coo object.

Usage

```
calibrate_harmonicpower()

calibrate_harmonicpower_efourier(
  x,
  id = 1:length(x),
  nb.h,
  drop = 1,
  thresh = c(90, 95, 99, 99.9),
  plot = TRUE
)

calibrate_harmonicpower_rfourier(
```

```

    x,
    id = 1:length(x),
    nb.h,
    drop = 1,
    thresh = c(90, 95, 99, 99.9),
    plot = TRUE
)

calibrate_harmonicpower_tfourier(
  x,
  id = 1:length(x),
  nb.h,
  drop = 1,
  thresh = c(90, 95, 99, 99.9),
  plot = TRUE
)

calibrate_harmonicpower_sfourier(
  x,
  id = 1:length(x),
  nb.h,
  drop = 1,
  thresh = c(90, 95, 99, 99.9),
  plot = TRUE
)

calibrate_harmonicpower_dfourier(
  x,
  id = 1:length(x),
  nb.h,
  drop = 1,
  thresh = c(90, 95, 99, 99.9),
  plot = TRUE
)

```

Arguments

x	a Coo of Opn object
id	the shapes on which to perform calibrate_harmonicpower. All of them by default
nb.h	numeric the maximum number of harmonic, on which to base the cumsum
drop	numeric the number of harmonics to drop for the cumulative sum
thresh	vector of numeric for drawing horizontal lines, and also used for minh below
plot	logical whether to plot the result or simply return the matrix Silent message and progress bars (if any) with options("verbose"=FALSE).

Details

The power of a given harmonic n is calculated as follows for elliptical Fourier analysis and the n -th harmonic: $HarmonicPower_n = \frac{A_n^2 + B_n^2 + C_n^2 + D_n^2}{2}$ and as follows for radii variation and tangent angle:
 $HarmonicPower_n = \frac{A_n^2 + B_n^2 + C_n^2 + D_n^2}{2}$

Value

returns a list with component:

- gg a ggplot object, q the quantile matrix
- minh a quick summary that returns the number of harmonics required to achieve a certain proportion of the total harmonic power.

See Also

Other calibration: [calibrate_deviations\(\)](#), [calibrate_r2\(\)](#), [calibrate_reconstructions](#)

Examples

```
b5 <- bot %>% slice(1:5)
b5 %>% calibrate_harmonicpower_efourier(nb.h=12)
b5 %>% calibrate_harmonicpower_rfouier(nb.h=12)
b5 %>% calibrate_harmonicpower_tfourier(nb.h=12)
b5 %>% calibrate_harmonicpower_sfourier(nb.h=12)

# on Opn
olea %>% slice(1:5) %>%
  calibrate_harmonicpower_dfourier(nb.h=12)
## Not run:
# let customize the ggplot
library(ggplot2)
cal <- b5 %>% calibrate_harmonicpower_efourier(nb.h=12)
cal$gg + theme_minimal() +
  coord_cartesian(xlim=c(3.5, 12.5), ylim=c(90, 100)) +
  ggtitle("Harmonic power calibration")

## End(Not run)
```

calibrate_r2

Quantitative r2 calibration for Opn objects

Description

Estimates the r2 to calibrate the degree for [npoly](#) and [opoly](#) methods. Also returns a plot

Usage

```

calibrate_r2()

calibrate_r2_opoly(
  Opn,
  id = 1:length(Opn),
  degree.range = 1:8,
  thresh = c(0.9, 0.95, 0.99, 0.999),
  plot = TRUE,
  ...
)

calibrate_r2_npoly(
  Opn,
  id = 1:length(Opn),
  degree.range = 1:8,
  thresh = c(0.9, 0.95, 0.99, 0.999),
  plot = TRUE,
  ...
)

```

Arguments

Opn	an Opn object
id	the ids of shapes on which to calculate r2 (all by default)
degree.range	on which to calculate r2
thresh	the threshold to return diagnostic
plot	logical whether to print the plot
...	useless here

Details

May be long, so you can estimate it on a sample either with id here, or one of [sample_n](#) or [sample_frac](#)

Note

Silent message and progress bars (if any) with options("verbose"=FALSE).

See Also

Other calibration: [calibrate_deviations\(\)](#), [calibrate_harmonicpower\(\)](#), [calibrate_reconstructions](#)

Examples

```

## Not run:
olea %>% slice(1:5) %>% #for the sake of speed
  calibrate_r2_opoly(degree.range=1:5, thresh=c(0.9, 0.99))

```

```

olea %>% slice(1:5) %>% #for the sake of speed
  calibrate_r2_npoly(degree.range=1:5, thresh=c(0.9, 0.99))

## End(Not run)

```

calibrate_reconstructions

Calibrate using reconstructed shapes

Description

Calculate and displays reconstructed shapes using a range of harmonic number. Compare them visually with the maximal fit. This explicitly demonstrates how robust efourier is compared to tfourier and rfourier.

Usage

```
calibrate_reconstructions_efourier(x, id, range = 1:9)
```

```
calibrate_reconstructions_rfourier(x, id, range = 1:9)
```

```
calibrate_reconstructions_tfourier(x, id, range = 1:9)
```

```
calibrate_reconstructions_sfourier(x, id, range = 1:9)
```

```
calibrate_reconstructions_npoly(
  x,
  id,
  range = 2:10,
  baseline1 = c(-1, 0),
  baseline2 = c(1, 0)
)
```

```
calibrate_reconstructions_opoly(
  x,
  id,
  range = 2:10,
  baseline1 = c(-1, 0),
  baseline2 = c(1, 0)
)
```

```
calibrate_reconstructions_dfourier(
  x,
  id,
  range = 2:10,
```



```

    baseline1 = c(-1, 0),
    baseline2 = c(1, 0)
  )

```

Arguments

x	the Coo object on which to calibrate_reconstructions
id	the shape on which to perform calibrate_reconstructions
range	vector of harmonics on which to perform calibrate_reconstructions
baseline1	(<i>x</i> ; <i>y</i>) coordinates for the first point of the baseline
baseline2	(<i>x</i> ; <i>y</i>) coordinates for the second point of the baseline

Value

a ggplot object and the full list of intermediate results. See examples.

See Also

Other calibration: [calibrate_deviations\(\)](#), [calibrate_harmonicpower\(\)](#), [calibrate_r2\(\)](#)

Examples

```

### On Out
shapes %>%
  calibrate_reconstructions_efourier(id=1, range=1:6)

# you may prefer efourier...
shapes %>%
  calibrate_reconstructions_tfourier(id=1, range=1:6)

#' you may prefer efourier...
shapes %>%
  calibrate_reconstructions_rfourier(id=1, range=1:6)

#' you may prefer efourier... # todo
#shapes %>%
#  calibrate_reconstructions_sfourier(id=5, range=1:6)

### On Opn
olea %>%
  calibrate_reconstructions_opoly(id=1)

olea %>%
  calibrate_reconstructions_npoly(id=1)

olea %>%
  calibrate_reconstructions_dfourier(id=1)

```

chaff

Data: Landmark and semilandmark coordinates on cereal glumes

Description

Data: Landmark and semilandmark coordinates on cereal glumes

Format

An [Ldk](#) object with 21 configurations of landmarks and semi-landmarks (4 partitions) sampled on cereal glumes

Source

Research support was provided by the European Research Council (Evolutionary Origins of Agriculture (grant no. 269830-EOA) PI: Glynis Jones, Dept of Archaeology, Sheffield, UK. Data collected by Emily Forster.

See Also

Other datasets: [apodemus](#), [bot](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

charring

Data: Outline coordinates from an experimental charring on cereal grains

Description

Data: Outline coordinates from an experimental charring on cereal grains

Format

An [Out](#) object with 18 grains, 3 views on each, for 2 cereal species, charred at different temperatures for 6 hours (0C (no charring), 230C and 260C).

Source

Research support was provided by the European Research Council (Evolutionary Origins of Agriculture (grant no. 269830-EOA) PI: Glynis Jones, Dept of Archaeology, Sheffield, UK. Data collected by Emily Forster.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

`chop`*Split to several objects based on a factor*

Description

Rougher slicing that accepts a classifier ie a column name from the `$fac` on Momocs classes. Returns a named (after every level) list that can be lapply-ed and combined. See examples.

Usage

```
chop(.data, fac)
```

Arguments

<code>.data</code>	a Coo or Coe object
<code>fac</code>	a column name from the <code>\$fac</code>

Value

a named list of Coo or Coe objects

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea %>%
  filter(var == "Aglan") %>% # to have a balanced nb of 'view'
  chop(~view) %>%          # split into a list of 2
  npoly %>%                # separately apply npoly
                           # strict equivalent to lapply(npoly)
  combine %>%              # recombine
  PCA %>% plot             # an illustration of the 2 views
                           # treated separately
```

`classification_metrics`*Calculate classification metrics on a confusion matrix*

Description

In some cases, the class correctness or the proportion of correctly classified individuals is not enough, so here are more detailed metrics when working on classification.

Usage`classification_metrics(x)`**Arguments**

`x` a table or an [LDA](#) object

Value

a list with the following components is returned:

1. `accuracy` the fraction of instances that are correctly classified
2. `macro_prf` data.frame containing precision (the fraction of correct predictions for a certain class); recall, the fraction of instances of a class that were correctly predicted; `f1` the harmonic mean (or a weighted average) of precision and recall.
3. `macro_avg`, just the average of the three `macro_prf` indices
4. `ova` a list of one-vs-all confusion matrices for each class
5. `ova_sum` a single of all ova matrices
6. `kappa` measure of agreement between the predictions and the actual labels

See Also

The pages below are of great interest to understand these metrics. The code used is partly derived from the Revolution Analytics blog post (with their authorization). Thanks to them!

1. https://en.wikipedia.org/wiki/Precision_and_recall
2. https://blog.revolutionanalytics.com/2016/03/com_class_eval_metrics_r.html
3. <https://www.r-bloggers.com/2016/03/is-your-classification-model-making-lucky-guesses/>

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#)

Examples

```
# some morphometrics on 'hearts'
hearts %>% fgProcrustes(tol=1) %>%
  coo_slide(ldk=1) %>% efourier(norm=FALSE) %>% PCA() %>%
# now the LDA and its summary
LDA(~aut) %>% classification_metrics()
```

CLUST *Hierarchical clustering*

Description

Performs hierarchical clustering through [dist](#) and [hclust](#). So far it is mainly a wrapper around these two functions, plus plotting using the [dendextend](#) package facilities.

Usage

```
CLUST(x, ...)

## Default S3 method:
CLUST(x, ...)

## S3 method for class 'Coe'
CLUST(
  x,
  fac,
  type = c("horizontal", "vertical", "fan")[1],
  k,
  dist_method = "euclidean",
  hclust_method = "complete",
  retain = 0.99,
  labels,
  lwd = 1/4,
  cex = 1/2,
  palette = pal_qual,
  ...
)
```

Arguments

x	a Coe or PCA object
...	useless here
fac	factor specification for fac_dispatcher
type	character one of c("horizontal", "vertical", "fan") (default: horizontal)
k	numeric if provided and greater than 1, cut the tree into this number of groups
dist_method	to feed dist 's method argument, that is one of euclidean (default), maximum, manhattan, canberra, binary or minkowski.
hclust_method	to feed hclust 's method argument, one of ward.D, ward.D2, single, complete (default), average, mcquitty, median or centroid.
retain	number of axis to retain if a PCA object is passed. If a number < 1 is passed, then the number of PCs retained will be enough to capture this proportion of variance via scree_min

labels	factor specification for labelling tips and to feed fac_dispatcher
lwd	for branches (default: 0.25)
cex	for labels (default: 1)
palette	one of available palettes

Value

a ggplot plot

See Also

Other multivariate: [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
# On Coe
bf <- bot %>% efourier(6)
CLUST(bf)
# with a factor and vertical
CLUST(bf, ~type, "v")
# with some cutting and different dist/hclust methods
CLUST(bf,
      dist_method="maximum", hclust_method="average",
      labels=~type, k=3, lwd=1, cex=1, palette=pal_manual(c("green", "yellow", "red")))

# On PCA
bf %>% PCA %>% CLUST
```

Coe

Coe "super" class

Description

Coe class is the 'parent' or 'super' class of [OutCoe](#), [OpnCoe](#), [LdkCoe](#) and [TraCoe](#) classes.

Usage

```
Coe(...)
```

Arguments

... anything and, anyway, this function will simply returns a message.

Details

Useful shortcuts are described below. See `browseVignettes("Momocs")` for a detail of the design behind Momocs' classes.

Coe class is the 'parent' class of the following 'child' classes

- `OutCoe` for coefficients from closed **out**lines morphometrics
- `OpnCoe` for coefficients from **open** outlines morphometrics
- `LdkCoe` for coefficients from configuration of **landmarks** morphometrics.

In other words, `OutCoe`, `OpnCoe` and `LdkCoe` classes are all, primarily, Coe objects on which we define generic *and* specific methods. See their respective help pages for more help.

You can access all the methods available for Coe objects with `methods(class=Coe)`.

See Also

Other classes: `Coo()`, `Ldk()`, `OpnCoe()`, `Opn()`, `OutCoe()`, `Out()`, `TraCoe()`

Examples

```
## Not run:
# to see all methods for Coe objects.
methods(class='Coe')
# to see all methods for OutCoe objects.
methods(class='OutCoe') # same for OpnCoe, LdkCoe, TraCoe

bot.f <- efourier(bot, 12)
bot.f
class(bot.f)
inherits(bot.f, "Coe")

# if you want to work directly on the matrix of coefficients
bot.f$coe

#getters
bot.f[1]
bot.f[1:5]

#setters
bot.f[1] <- 1:48
bot.f[1]

bot.f[1:5] <- matrix(1:48, nrow=5, ncol=48, byrow=TRUE)
bot.f[1:5]

# An illustration of Momocs design. See also browseVignettes("Momocs")
op <- opoly(olea, 5)
op
class(op)
op$coe # same thing
```

```

wp <- fgProcrustes(wings, tol=1e-4)
wp
class(wp) # for Ldk methods, LdkCoe objects can also be considered as Coe objects
# so you can apply all Ldk methods available.
wp$coe # Procrustes aligned coordinates

## End(Not run)

```

coeff_rearrange

Rearrange a matrix of (typically Fourier) coefficients

Description

Momocs uses colnamed matrices to store (typically) Fourier coefficients in [Coe](#) objects (typically [OutCoe](#)). They are arranged as rank-wise: A1, A2, ..., An, B1, ..., Bn, C1, ..., Cn, D1, ..., Dn. From other softwares they may arrive as A1, B1, C1, D1, ..., An, Bn, Cn, Dn, this functions helps to go from one to the other format. In short, this function rearranges column order. See examples.

Usage

```
coeff_rearrange(x, by = c("name", "rank")[1])
```

Arguments

x	matrix (with colnames)
by	character either "name" (A1, A2, ..) or "rank" (A1, B1, ...)

Examples

```

m_name <- m_rank <- matrix(1:32, 2, 16)
# this one is ordered by name
colnames(m_name) <- paste0(rep(letters[1:4], each=4), 1:4)
# this one is ordered by rank
colnames(m_rank) <- paste0(letters[1:4], rep(1:4, each=4))

m_rank
m_rank %>% coeff_rearrange(by="name")
m_rank %>% coeff_rearrange(by="rank") #no change

m_name
m_name %>% coeff_rearrange(by="name") # no change
m_name %>% coeff_rearrange(by="rank")

```

coeff_sel	<i>Helps to select a given number of harmonics from a numerical vector.</i>
-----------	---

Description

coeff_sel helps to select a given number of harmonics by returning their indices when arranged as a numeric vector. For instance, harmonic coefficients are arranged in the \$coe slot of Coe-objects in that way: $A_1, \dots, A_n, B_1, \dots, B_n, C_1, \dots, C_n, D_1, \dots, D - n$ after an elliptical Fourier analysis (see [efourier](#) and [efourier](#)) while C_n and D_n harmonic are absent for radii variation and tangent angle approaches (see [rfourier](#) and [tfourier](#) respectively). . This function is used internally but might be of interest elsewhere.

Usage

```
coeff_sel(retain = 8, drop = 0, nb.h = 32, cph = 4)
```

Arguments

retain	numeric. The number of harmonics to retain.
drop	numeric. The number of harmonics to drop
nb.h	numeric. The maximum harmonic rank.
cph	numeric. Must be set to 2 for rfourier and tfourier were used.

Value

coeff_sel returns indices that can be used to select columns from an harmonic coefficient matrix.
coeff_split returns a named list of coordinates.

Examples

```
bot.f <- efourier(bot, 32)
coe <- bot.f$coe # the raw matrix
coe
# if you want, say the first 8 harmonics but not the first one
retain <- coeff_sel(retain=8, drop=1, nb.h=32, cph=4)
head(coe[, retain])
```

coeff_split	<i>Converts a numerical description of harmonic coefficients to a named list.</i>
-------------	---

Description

coeff_split returns a named list of coordinates from a vector of harmonic coefficients. For instance, harmonic coefficients are arranged in the \$coe slot of Coe-objects in that way: $A_1, \dots, A_n, B_1, \dots, B_n, C_1, \dots, C_n, D_1, \dots, D_n$ after an elliptical Fourier analysis (see [efourier](#) and [efourier](#)) while C_n and D_n harmonic are absent for radii variation and tangent angle approaches (see [rfourier](#) and [tfourier](#) respectively). This function is used internally but might be of interest elsewhere.

Usage

```
coeff_split(cs, nb.h = 8, cph = 4)
```

Arguments

cs	A vector of harmonic coefficients.
nb.h	numeric. The maximum harmonic rank.
cph	numeric. Must be set to 2 for rfourier and tfourier were used.

Value

Returns a named list of coordinates.

Examples

```
coeff_split(1:128, nb.h=32, cph=4) # efourier
coeff_split(1:64, nb.h=32, cph=2) # t/r fourier
```

color_palettes	<i>Some color palettes</i>
----------------	----------------------------

Description

Colors, colors, colors.

Usage

```
col_summer(n)
col_summer2(n)
col_spring(n)
col_autumn(n)
col_black(n)
col_solarized(n)
col_gallus(n)
col_qual(n)
col_heat(n)
col_hot(n)
col_cold(n)
col_sari(n)
col_india(n)
col_bw(n)
col_grey(n)
```

Arguments

n the number of colors to generate from the color palette

Value

colors (hexadecimal format)

Note

Among available color palettes, `col_solarized` is based on Solarized: <https://ethanschoonover.com/solarized/>; `col_div`, `col_qual`, `col_heat`, `col_cold` and `col_gallus` are based on on ColorBrewer2: <https://colorbrewer2.org/>.

Examples

```
wheel <- function(palette, n=10){
```

```

op <- par(mar=rep(0, 4)) ; on.exit(par(op))
pie(rep(1, n), col=palette(n), labels=NA, clockwise=TRUE)}

# Qualitative
wheel(col_qual)
wheel(col_solarized)
wheel(col_summer)
wheel(col_summer2)
wheel(col_spring)
wheel(col_autumn)

# Divergent
wheel(col_gallus)
wheel(col_india)

# Sequential
wheel(col_heat)
wheel(col_hot)
wheel(col_cold)
wheel(col_sari)
wheel(col_bw)
wheel(col_grey)

# Black only for pubs
wheel(col_black)

```

col_transp

Transparency helpers and palettes

Description

To ease transparency handling.

Usage

```
col_transp(n, col = "#000000", ceiling = 1)
```

```
col_alpha(cols, transp = 0)
```

Arguments

n	the number of colors to generate
col	a color in hexadecimal format on which to generate levels of transparency
ceiling	the maximal opacity (from 0 to 1)
cols	on or more colors, provided as hexadecimal values
transp	numeric between 0 and 1, the value of the transparency to obtain

Examples

```
x <- col_transp(10, col='#000000')
x
barplot(1:10, col=x, main='a transparent black is grey')

summer10 <- col_summer(10)
summer10
summer10.transp8 <- col_alpha(summer10, 0.8)
summer10.transp8
summer10.transp2 <- col_alpha(summer10, 0.8)
summer10.transp2
x <- 1:10
barplot(x, col=summer10.transp8)
barplot(x/2, col=summer10.transp2, add=TRUE)
```

 combine

Combine several objects

Description

Combine Coo objects after a slicing, either manual or using [slice](#) or [chop](#). Note that on Coe object, it combines row-wise (ie, merges shapes as a c would do) ; but on Coe it combines column-wise (merges coefficients). In the latter case, Coe must have the same number of shapes (not necessarily the same number of coefficients). Also the `$fac` of the first Coe is retrieved. A separate version may come at some point.

Usage

```
combine(...)
```

Arguments

... a list of Out(Coe), Opn(Coe), Ldk objects (but of the same class)

Note

Note that the order of shapes or their coefficients is not checked, so anything with the same number of rows will be merged.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsize\(\)](#)

Examples

```

w <- filter(bot, type=="whisky")
b <- filter(bot, type=="beer")
combine(w, b)
# or, if you have many levels
bot_s <- chop(bot, ~type)
bot_s$whisky
# note that you can apply something (single function or a more
# complex pipe) then combine everyone, since combine also works on lists
# eg:
# bot_s2 <- efourier(bot_s, 10) # equivalent to lapply(bot_s, efourier, 10)
# bot_sf <- combine(bot_s2)

# pipe style
efourier(bot_s, 10) %>% combine()

```

complex

Convert complex to/from cartesian coordinates

Description

Convert complex to/from cartesian coordinates

Usage

```

cpx2coo(Z)

coo2cpx(coo)

```

Arguments

Z	coordinates expressed in the complex form
coo	coordinates expressed in the cartesian form

Value

coordinates expressed in the cartesian/complex form

See Also

Other bridges functions: [as_df\(\)](#), [bridges](#), [export\(\)](#)

Examples

```

shapes[4] %>% # from cartesian
  coo_sample(24) %>%
  coo2cpx() %T>% # to complex
  cpx2coo() # and back

```

Coo

*Coo "super" class***Description**

Coo class is the 'parent' or 'super' class of [Out](#), [Opn](#) and [Ldk](#) classes.

Usage

```
Coo(...)
```

Arguments

... anything and, anyway, this function will simply returns a message.

Details

Useful shortcuts are described below. See `browseVignettes("Momocs")` for a detail of the design behind Momocs' classes.

Coo class is the 'parent' class of the following 'child' classes

- [Out](#) for closed **out**lines
- [Opn](#) for **open** outlines
- [Ldk](#) for configuration of **landmarks**

Since all 'child classes' of them handle $(x; y)$ coordinates among other generic methods, but also all have their specificity, this architecture allow to recycle generic methods and to use specific methods.

In other words, [Out](#), [Opn](#) and [Ldk](#) classes are all, primarily, Coo objects on which we define generic *and* specific methods. See their respective help pages for more help.

Coo objects all have the following components:

- `$coo` which is a list of matrices for coordinates
- `$fac` a `data_frame` for covariates (if any). You can provide this `data_frame` directly, as long as it has as many rows as there are matrices in `$coo` (see examples), or use an helper function such as [lf_structure](#).

You can access all the methods available for Coo objects with `methods(class=Coo)`.

See Also

Other classes: [Coe\(\)](#), [Ldk\(\)](#), [OpnCoe\(\)](#), [Opn\(\)](#), [OutCoe\(\)](#), [Out\(\)](#), [TraCoe\(\)](#)

Examples

```

## Not run:
# to see all methods for Coo objects.
methods(class='Coo')

# to see all methods for Out objects.
methods(class='Out') # same for Opn and Ldk

# Let's take an Out example. But all methods shown here
# work on Ldk (try on 'wings') and on Opn ('olea')
bot

# Primarily a 'Coo' object, but also an 'Out'
class(bot)
inherits(bot, "Coo")
panel(bot)
stack(bot)
plot(bot)

# Getters (you can also use it to set data)
bot[1] %>% coo_plot()
bot[1:5] %>% str()

# Setters
bot[1] <- shapes[4]
panel(bot)

bot[1:5] <- shapes[4:8]
panel(bot)

# access the different components
# $coo coordinates
head(bot$coo)
# $fac grouping factors
head(bot$fac)
# or if you know the name of the column of interest
bot$type
# table
table(bot$fac)
# an internal view of an Out object
str(bot)

# subsetting
# see ?filter, ?select, and their 'see also' section for the
# complete list of dplyr-like verbs implemented in Momocs

length(bot) # the number of shapes
names(bot) # access all individual names
bot2 <- bot
names(bot2) <- paste0('newnames', 1:length(bot2)) # define new names

# Add a $fac from scratch

```



```

coo <- bot[1:5] # a list of five matrices
length(coo)
sapply(coo, class)

fac <- data.frame(name=letters[1:5], value=c(5:1))
# Then you have to define the subclass using the right builder
# here we have outlines, so we use Out
x <- Out(coo, fac)
x$coo
x$fac

## End(Not run)

```

coo_align

Aligns coordinates

Description

Aligns the coordinates along their longer axis using var-cov matrix and eigen values.

Usage

```
coo_align(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other aligning functions: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```

coo_plot(bot[1])
coo_plot(coo_align(bot[1]))

# on a Coo
b <- bot %>% slice(1:5) # for speed sake
stack(coo_align(b))

```

coo_aligncalliper *Aligns shapes along their 'calliper length'*

Description

And returns them registered on bookstein coordinates. See [coo_bookstein](#).

Usage

```
coo_aligncalliper(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or any [Coo](#) object.

See Also

Other aligning functions: [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#)

Other coo_ utilities: [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```

## Not run:
b <- bot[1]
coo_plot(b)
coo_plot(coo_aligncalliper(b))

b <- bot %>% slice(1:5) # for speed sake
bot.al <- coo_aligncalliper(b)

```

```
stack(bot.al)
## End(Not run)
```

coo_alignminradius *Aligns shapes using their shortest radius*

Description

And returns them slided with the first coordinate on the east. May be used as an aligning strategy on shapes with a clear 'invaginate' part.

Usage

```
coo_alignminradius(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other aligning functions: [coo_aligncalliper\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
b <- bot %>% slice(1:5) # for speed sake
stack(coo_alignminradius(b))
```

 coo_alignxax

Aligns shapes along the x-axis

Description

Align the longest axis of a shape along the x-axis.

Usage

```
coo_alignxax(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Details

If some shapes are upside-down (or mirror of each others), try redefining a new starting point (eg with `coo_slidedirection`) before the alignment step. This may solve your problem because `coo_calliper` orders the `$arr.ind` used by `coo_aligncalliper`.

Value

a matrix of (x; y) coordinates, or any [Coo](#) object.

See Also

Other aligning functions: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_align\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samplerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
## Not run:
b <- bot[1]
coo_plot(b)
coo_plot(coo_alignxax(b))

## End(Not run)
```

coo_angle_edges	<i>Calculates the angle of every edge of a shape</i>
-----------------	--

Description

Returns the angle (in radians) of every edge of a shape,

Usage

```
coo_angle_edges(coo, method = c("atan2", "acos")[1])

## Default S3 method:
coo_angle_edges(coo, method = c("atan2", "acos")[1])

## S3 method for class 'Coo'
coo_angle_edges(coo, method = c("atan2", "acos")[1])
```

Arguments

coo	a matrix or a list of (x; y) coordinates or any Coo
method	'atan2' (or 'acos') for a signed (or not) angle.

Value

numeric the angles in radians for every edge.

Note

coo_thetapts is deprecated and will be removed in future releases.

See Also

Other coo_ descriptors: [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
b <- coo_sample(bot[1], 64)
coo_angle_edges(b)
```

coo_angle_tangent	<i>Calculates the tangent angle along the perimeter of a shape</i>
-------------------	--

Description

Calculated using complex numbers and returned in radians minus the first one (modulo 2π).

Usage

```
coo_angle_tangent(coo)

## Default S3 method:
coo_angle_tangent(coo)

## S3 method for class 'Coo'
coo_angle_tangent(coo)

coo_tangle(coo)
```

Arguments

coo a matrix of coordinates or any Coo

Value

numeric, the tangent angle along the perimeter, or a list of those for Coo

See Also

[tfourier](#)

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
b <- bot[1]
phi <- coo_angle_tangent(b)
phi2 <- coo_angle_tangent(coo_smooth(b, 2))
plot(phi, type='l')
plot(phi2, type='l', col='red') # ta is very sensible to noise

# on Coo
bot %>% coo_angle_tangent
```

coo_area	<i>Calculates the area of a shape</i>
----------	---------------------------------------

Description

Calculates the area for a (non-crossing) shape.

Usage

```
coo_area(coo)
```

Arguments

coo a matrix of (x; y) coordinates.

Value

numeric, the area.

Note

Using `area.poly` in `gpc` package is a good idea, but their licence impedes Momocs to rely on it. but here is the function to do it, once `gpc` is loaded: `area.poly(as(coo, 'gpc.poly'))`

See Also

Other `coo_` descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_area(bot[1])  
# for the distribution of the area of the bottles dataset  
hist(sapply(bot$coo, coo_area), breaks=10)
```

coo_arrows	<i>Plots (lollipop) differences between two configurations</i>
------------	--

Description

Draws 'arrows' between two configurations.

Usage

```
coo_arrows(coo1, coo2, length = coo_centsize(coo1)/15, angle = 20, ...)
```

Arguments

coo1	A list or a matrix of coordinates.
coo2	A list or a matrix of coordinates.
length	a length for the arrows.
angle	an angle for the arrows
...	optional parameters to feed arrows .

See Also

Other plotting functions: [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Examples

```
coo_arrows(coo_sample(olea[3], 50), coo_sample(olea[6], 50))
title("Hi there !")
```

coo_baseline	<i>Register new baselines</i>
--------------	-------------------------------

Description

A non-exact baseline registration on t1 and t2 coordinates, for the ldk1-th and ldk2-th points. By default it returns Bookstein's coordinates.

Usage

```
coo_baseline(coo, ldk1, ldk2, t1, t2)
```


Arguments

coo	matrix of (x; y) coordinates or any Coo object.
ldk1	numeric the id of the first point of the new baseline
ldk2	numeric the id of the second point of the new baseline
t1	numeric the (x; y) coordinates of the 1st point of the new baseline
t2	numeric the (x; y) coordinates of the 2nd point of the new baseline

Value

a matrix of (x; y) coordinates or a [Coo](#) object.

See Also

Other baselining functions: [coo_bookstein\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
h <- hearts %>% slice(1:5) # for speed sake
stack(h)
stack(coo_baseline(h, 2, 4, c(-1, 0), c(1, 1)))
```

coo_bookstein

Register Bookstein's coordinates

Description

Registers a new baseline for the shape, with the `ldk1`-th and `ldk2`-th points being set on $(x = -0.5; y = 0)$ and $(x = 0.5; y = 0)$, respectively.

Usage

```
coo_bookstein(coo, ldk1, ldk2)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
ldk1	numeric the id of the first point of the new baseline (the first, by default)
ldk2	numeric the id of the second point of the new baseline (the last, by default)

Details

For **Out**, it tries to do it using \$1dk slot. Also the case for **Opn**, but if no landmark is defined, it will do it on the first and the last point of the shape.

For **Out** and **Opn** defines the first landmark as the first point of the new shapes with [coo_slide](#).

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other baselining functions: [coo_baseline\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
h <- hearts %>% slice(1:5) # for the sake of speed
stack(h)
stack(coo_bookstein(h, 2, 4))
h <- hearts[1]
coo_plot(h)
coo_plot(coo_bookstein(h, 20, 57), border='red')
```

coo_boundingbox

Calculates coordinates of the bounding box

Description

Calculates coordinates of the bounding box

Usage

```
coo_boundingbox(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

Value

data.frame with coordinates of the bounding box

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Other `coo_` descriptors: `coo_angle_edges()`, `coo_angle_tangent()`, `coo_area()`, `coo_chull()`, `coo_circularity()`, `coo_convexity()`, `coo_eccentricity`, `coo_elongation()`, `coo_length()`, `coo_lw()`, `coo_rectangularity()`, `coo_rectilinearity()`, `coo_scalars()`, `coo_solidity()`, `coo_tac()`, `coo_width()`

Examples

```
bot[1] %>% coo_boundingbox()
bot %>% coo_boundingbox()
```

<code>coo_calliper</code>	<i>Calculates the calliper length</i>
---------------------------	---------------------------------------

Description

Also called the Feret's diameter, the longest distance between two points of the shape provided.

Usage

```
coo_calliper(coo, arr.ind = FALSE)
```

Arguments

<code>coo</code>	a matrix of (x; y) coordinates or any <code>Coo</code>
<code>arr.ind</code>	logical, see below.

Value

numeric, the centroid size. If `arr.ind=TRUE`, a `data_frame`.

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```

b <- bot[1]
coo_calliper(b)
p <- coo_calliper(b, arr.ind=TRUE)
p
p$length
ids <- p$arr_ind[[1]]
coo_plot(b)
segments(b[ids[1], 1], b[ids[1], 2], b[ids[2], 1], b[ids[2], 2], lty=2)

# on a Coo
bot %>%
coo_sample(32) %>% # for speed sake
coo_calliper()

bot %>%
coo_sample(32) %>% # for speed sake
coo_calliper(arr.ind=TRUE)

```

coo_centdist

Returns the distance between everypoints and the centroid

Description

For every point of the shape, returns the (centroid-points) distance.

Usage

```
coo_centdist(coo)
```

Arguments

coo a matrix of (x; y) coordinates.

Value

a matrix of (x; y) coordinates.

See Also

Other centroid functions: [coo_centpos\(\)](#), [coo_centsize\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- coo_sample(bot[1], 64)
d <- coo_centdist(b)
barplot(d, xlab="Points along the outline", ylab="Distance to the centroid (pixels)")
```

coo_center	<i>Centers coordinates</i>
------------	----------------------------

Description

Returns a shape centered on the origin. The two functions are strictly equivalent.

Usage

```
coo_center(coo)
```

```
coo_centre(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
coo_plot(bot[1])
# same as
coo_plot(coo_centre(bot[1]))
# this
coo_plot(coo_center(bot[1]))

# on Coo objects
b <- slice(bot, 1:5) # speed sake
stack(slice(b, 1:5))
stack(coo_center(b))
```

coo_centpos	<i>Calculate centroid coordinates</i>
-------------	---------------------------------------

Description

Returns the (x; y) centroid coordinates of a shape.

Usage

```
coo_centpos(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

(x; y) coordinates of the centroid as a vector or a matrix.

See Also

Other centroid functions: [coo_centdist\(\)](#), [coo_centsize\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignnax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- bot[1]
coo_plot(b)
xy <- coo_centpos(b)
points(xy[1], xy[2], cex=2, col='blue')
# on a Coo
coo_centpos(bot)
```

coo_centsize	<i>Calculates centroid size</i>
--------------	---------------------------------

Description

Calculates centroid size

Usage

```
coo_centsize(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Details

This function can be used to integrate size - if meaningful - to Coo objects. See also [coo_length](#) and [rescale](#).

Value

numeric, the centroid size.

See Also

Other centroid functions: [coo_centdist\(\)](#), [coo_centpos\(\)](#)

Examples

```
coo_centsize(bot[1])  
# on a Coo  
coo_centsize(bot)  
# add it to $fac  
mutate(bot, size=coo_centsize(bot))
```

coo_check	<i>Checks shapes</i>
-----------	----------------------

Description

A simple utility, used internally, mostly in the coo functions and methods. Returns a matrix of coordinates, when passed with either a list or a matrix of coordinates.

Usage

```
coo_check(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

matrix of (x; y) coordinates or a [Coo](#) object.

Examples

```
#coo_check('Not a shape')
#coo_check(iris)
#coo_check(matrix(1:10, ncol=2))
#coo_check(list(x=1:5, y=6:10))
```

coo_chull	<i>Calculates the (recursive) convex hull of a shape</i>
-----------	--

Description

coo_chull returns the ids of points that define the convex hull of a shape. A simple wrapper around [chull](#), mainly used in graphical functions.

Usage

```
coo_chull(coo)

## Default S3 method:
coo_chull(coo)

## S3 method for class 'Coo'
coo_chull(coo)

coo_chull_onion(coo, close = TRUE)

## Default S3 method:
coo_chull_onion(coo, close = TRUE)

## S3 method for class 'Coo'
coo_chull_onion(coo, close = TRUE)
```

Arguments

coo a matrix of (x; y) coordinates or any [Coo](#).

close logical whether to close onion rings (TRUE by default)

Details

coo_chull_onion recursively find their convex hull, remove them, until less than 3 points are left.

Value

coo_chull returns a matrix of points defining the convex hull of the shape; a list for Coo.
 coo_chull_onion returns a list of successive onions rings, and a list of lists for Coo.

See Also

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
# coo_chull
h <- coo_sample(hearts[4], 32)
coo_plot(h)
ch <- coo_chull(h)
lines(ch, col='red', lty=2)

bot %>% coo_chull

coo_chull_onion
x <- bot %>% efourier(6) %>% PCA
all_whisky_points <- x %>% as_df() %>% filter(type=="whisky") %>% select(PC1, PC2)
plot(x, ~type, eig=FALSE)
peeling_the_whisky_onion <- all_whisky_points %>% as.matrix %>% coo_chull_onion()
# you may need to par(xpd=NA) to ensure all segments
# even those outside the graphical window are drawn
peeling_the_whisky_onion$coo %>% lapply(coo_draw)
# simulated data
xy <- replicate(2, rnorm(50))
coo_plot(xy, poly=FALSE)
xy %>% coo_chull_onion() %$% coo %>%
lapply(polygon, col="#00000022")
```

 coo_circularity

Calculates the Haralick's circularity of a shape

Description

coo_circularity calculates the 'circularity measure'. Also called 'compactness' and 'shape factor' sometimes. coo_circularityharalick calculates Haralick's circularity which is less sensible to digitalization noise than coo_circularity. coo_circularitynorm calculates 'circularity', also called compactness and shape factor, but normalized to the unit circle.

Usage

```
coo_circularity(coo)

## Default S3 method:
coo_circularity(coo)

## S3 method for class 'Coo'
coo_circularity(coo)

coo_circularityharalick(coo)

## Default S3 method:
coo_circularityharalick(coo)

## S3 method for class 'Coo'
coo_circularityharalick(coo)

coo_circularitynorm(coo)

## Default S3 method:
coo_circularitynorm(coo)

## S3 method for class 'Coo'
coo_circularitynorm(coo)
```

Arguments

`coo` a matrix of (x; y) coordinates or any Coo

Value

numeric for single shapes, list for Coo of the corresponding circularity measurement.

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

Other `coo_` descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
# coo_circularity
```

```

bot[1] %>% coo_circularity()
bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularity

# coo_circularityharalick
bot[1] %>% coo_circularityharalick()
bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularityharalick

# coo_circularitynorm
bot[1] %>% coo_circularitynorm()
bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularitynorm

```

coo_close	<i>Closes/uncloses shapes</i>
-----------	-------------------------------

Description

Returns a closed shape from (un)closed shapes. See also [coo_unclose](#).

Returns a unclosed shape from (un)closed shapes. See also [coo_close](#).

Usage

```
coo_close(coo)
```

```
coo_unclose(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#),

coo_slidedirection(), coo_slidegap(), coo_slide(), coo_smoothcurve(), coo_smooth(),
 coo_template(), coo_trans(), coo_trimbottom(), coo_trimtop(), coo_trim(), coo_untiltx(),
 coo_up(), is_equallyspacedradii()

Other coo_utilities: coo_aligncalliper(), coo_alignminradius(), coo_alignxax(), coo_align(),
 coo_baseline(), coo_bookstein(), coo_boundingbox(), coo_calliper(), coo_centdist(),
 coo_center(), coo_centpos(), coo_down(), coo_dxy(), coo_extract(), coo_flipx(), coo_force2close(),
 coo_interpolate(), coo_is_closed(), coo_jitter(), coo_left(), coo_likely_clockwise(),
 coo_nb(), coo_perim(), coo_range(), coo_rev(), coo_right(), coo_rotatecenter(), coo_rotate(),
 coo_sample_prop(), coo_samplerr(), coo_sample(), coo_scale(), coo_shearx(), coo_slice(),
 coo_slidedirection(), coo_slidegap(), coo_slide(), coo_smoothcurve(), coo_smooth(),
 coo_template(), coo_trans(), coo_trimbottom(), coo_trimtop(), coo_trim(), coo_untiltx(),
 coo_up(), is_equallyspacedradii()

Examples

```
x <- (matrix(1:10, ncol=2))
x2 <- coo_close(x)
x3 <- coo_unclose(x2)
x
coo_is_closed(x)
x2
coo_is_closed(x2)
x3
coo_is_closed(x3)
x <- (matrix(1:10, ncol=2))
x2 <- coo_close(x)
x3 <- coo_unclose(x2)
x
coo_is_closed(x)
x2
coo_is_closed(x2)
x3
coo_is_closed(x3)
```

coo_convexity

Calculates the convexity of a shape

Description

Calculated using a ratio of the eigen values (inertia axis)

Usage

```
coo_convexity(coo)
```

Arguments

coo a matrix of (x; y) coordinates.

Value

numeric for a single shape, list for a Coo

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

Other coo_descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_convexity(bot[1])
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_convexity()
```

coo_down

coo_down Retains coordinates with negative y-coordinates

Description

Useful when shapes are aligned along the x-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the lower side.

Usage

```
coo_down(coo, slidegap = FALSE)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
slidegap logical whether to apply [coo_slidegap](#) after `coo_down`

Value

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

Note

When shapes are "sliced" along the x-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo_slidegap](#). See examples there.

Also, when apply a `coo_left/right/up/down` on an **Out** object, you then obtain an **Opn** object, which is done automatically.

See Also

Other opening functions: [coo_left\(\)](#), [coo_right\(\)](#), [coo_up\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- coo_alignxax(bot[1])
coo_plot(b)
coo_draw(coo_down(b), border='red')
```

coo_draw

Adds a shape to the current plot

Description

`coo_draw` is simply a [coo_plot](#) with `plot.new=FALSE`, ie that adds a shape on the active plot.

Usage

```
coo_draw(coo, ...)
```

Arguments

`coo` a list or a matrix of coordinates.
`...` optional parameters for [coo_plot](#)

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Examples

```
b1 <- bot[4]
b2 <- bot[5]
coo_plot(b1)
coo_draw(b2, border='red') # all coo_plot arguments will work for coo_draw
```

coo_draw_rads	<i>Draw radii to the current plot</i>
---------------	---------------------------------------

Description

Given a shape, all centroid-points radii are drawn using [segments](#) that can be passed with options

Usage

```
coo_draw_rads(coo, ...)
```

Arguments

coo	a shape
...	arguments to feed segments

Examples

```
shp <- shapes[4] %>% coo_sample(24) %T>% coo_plot
coo_draw_rads(shp, col=col_summer(24))
```

coo_dxy	<i>Calculate abscissa and ordinate on a shape</i>
---------	---

Description

A simple wrapper to calculate dxi - dx1 and dyi - dx1.

Usage

```
coo_dxy(coo)
```

Arguments

coo	a matrix (or a list) of (x; y) coordinates or any Coo
-----	---

Value

a data.frame with two components dx and dy for single shapes or a list of such data.frames for Coo

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```
coo_dxy(coo_sample(bot[1], 12))

bot %>%
  slice(1:5) %>% coo_sample(12) %>% # for readability and speed only
  coo_dxy()
```

<code>coo_eccentricity</code>	<i>Calculates the eccentricity of a shape</i>
-------------------------------	---

Description

`coo_eccentricityeigen` uses the ratio of the eigen values (inertia axes of coordinates). `coo_eccentricityboundingbox` uses the width/length ratio (see `coo_lw`).

Usage

```
coo_eccentricityeigen(coo)

## Default S3 method:
coo_eccentricityeigen(coo)

## S3 method for class 'Coo'
coo_eccentricityeigen(coo)

coo_eccentricityboundingbox(coo)

## Default S3 method:
coo_eccentricityboundingbox(coo)

## S3 method for class 'Coo'
coo_eccentricityboundingbox(coo)
```

Arguments

`coo` a matrix of (x; y) coordinates or any `Coo`

Value

numeric for single shapes, list for Coos.

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

[coo_eccentricityboundingbox](#)

Other coo_descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
# coo_eccentricityeigen
bot[1] %>% coo_eccentricityeigen()
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_eccentricityeigen()

# coo_eccentricityboundingbox
bot[1] %>% coo_eccentricityboundingbox()
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_eccentricityboundingbox()
```

<code>coo_elongation</code>	<i>Calculates the elongation of a shape</i>
-----------------------------	---

Description

Calculates the elongation of a shape

Usage

```
coo_elongation(coo)
```

Arguments

`coo` a matrix of (x; y) coordinates.

Value

numeric, the eccentricity of the bounding box

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

Other `coo_` descriptors: `coo_angle_edges()`, `coo_angle_tangent()`, `coo_area()`, `coo_boundingbox()`, `coo_chull()`, `coo_circularity()`, `coo_convexity()`, `coo_eccentricity`, `coo_length()`, `coo_lw()`, `coo_rectangularity()`, `coo_rectilinearity()`, `coo_scalars()`, `coo_solidity()`, `coo_tac()`, `coo_width()`

Examples

```
coo_elongation(bot[1])
# on Coo
# for speed sake
bot %>% slice(1:3) %>% coo_elongation
```

coo_extract

Extract coordinates from a shape

Description

Extract ids coordinates from a single shape or a Coo object.

Usage

```
coo_extract(coo, ids)
```

Arguments

`coo` either a matrix of (x; y) coordinates or a `Coo` object.
`ids` integer, the ids of points to sample.

Details

It probably only make sense for Coo objects with the same number of coordinates and them being homologous, typically on Ldk.

Value

a matrix of (x; y) coordinates, or a `Coo` object.

See Also

Other sampling functions: [coo_interpolate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
coo_extract(bot[1], c(3, 9, 12)) # or :
bot[1] %>% coo_extract(c(3, 9, 12))
```

coo_flipx

Flips shapes

Description

coo_flipx flips shapes about the x-axis; coo_flipy about the y-axis.

Usage

```
coo_flipx(coo)
```

```
coo_flipy(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates

See Also

Other transforming functions: [coo_shearx\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#),

```
coo_slidedirection(), coo_slidegap(), coo_slide(), coo_smoothcurve(), coo_smooth(),
coo_template(), coo_trans(), coo_trimbottom(), coo_trimtop(), coo_trim(), coo_untiltx(),
coo_up(), is_equallyspacedradii()
```

Examples

```
cat <- shapes[4]
cat <- coo_center(cat)
coo_plot(cat)
coo_draw(coo_flipx(cat), border="red")
coo_draw(coo_flipy(cat), border="blue")

#' # to flip an entire Coo:
shapes2 <- shapes
shapes2$coo <- lapply(shapes2$coo, coo_flipx)
```

coo_force2close	<i>Forces shapes to close</i>
-----------------	-------------------------------

Description

An exotic function that distribute the distance between the first and the last points of unclosed shapes, so that they become closed. May be useful (?) e.g. for *t/rfourier* methods where reconstructed shapes may not be closed.

Usage

```
coo_force2close(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- coo_sample(bot[1], 64)
b <- b[1:40,]
coo_plot(b)
coo_draw(coo_force2close(b), border='red')
```

coo_interpolate	<i>Interpolates coordinates</i>
-----------------	---------------------------------

Description

Interpolates n coordinates 'among existing points' between existing points, along the perimeter of the coordinates provided and keeping the first point

Usage

```
coo_interpolate(coo, n)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
n	codeinteger, the number fo points to interpolate.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other sampling functions: [coo_extract\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b5 <- bot %>% slice(1:5) # for speed sake
stack(b5)
stack(coo_scale(b5))
stack(b5)
stack(coo_interpolate(coo_sample(b5, 12), 120))
coo_plot(bot[1])
coo_plot(coo_interpolate(coo_sample(bot[1], 12), 120))
```

coo_intersect_angle *Nearest intersection between a shape and a segment specified with an angle*

Description

Take a shape, and segment starting on the centroid and having a particular angle, which point is the nearest where the segment intersects with the shape?

Usage

```
coo_intersect_angle(coo, angle = 0)

coo_intersect_direction(coo, direction = c("down", "left", "up", "right")[4])

## Default S3 method:
coo_intersect_direction(coo, direction = c("down", "left", "up", "right")[4])

## S3 method for class 'Coo'
coo_intersect_direction(coo, direction = c("down", "left", "up", "right")[4])
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
angle numeric an angle in radians (0 by default).
direction character one of "down", "left", "up", "right" ("right" by default)

Value

numeric the id of the nearest point or a list for Coo See examples.

Note

shapes are always centered before this operation. If you need a simple direction such as (down, left, up, right)ward, then use [coo_intersect_direction](#) which does not need to find an intersection but relies on coordinates and is about 1000.

See Also

Other coo_ intersect: [coo_intersect_segment\(\)](#)

Examples

```
coo <- bot[1] %>% coo_center %>% coo_scale
coo_plot(coo)
coo %>% coo_intersect_angle(pi/7) %>%
  coo[., , drop=FALSE] %>% points(col="red")
```

```
# many angles
coo_plot(coo)
sapply(seq(0, pi, pi/12),
  function(x) coo %>% coo_intersect_angle(x)) -> ids
coo[ids, ] %>% points(col="blue")

coo %>%
  coo_intersect_direction("down") %>%
  coo[., , drop=FALSE] %>% points(col="orange")
```

coo_intersect_segment *Nearest intersection between a shape and a segment*

Description

Take a shape, and an intersecting segment, which point is the nearest of where the segment intersects with the shape? Most of the time, centering before makes more sense.

Usage

```
coo_intersect_segment(coo, seg, center = TRUE)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
seg	a 2x2 matrix defining the starting and ending points; or a list or a numeric of length 4.
center	logical whether to center the shape (TRUE by default)

Value

numeric the id of the nearest point, a list for Coo. See examples.

See Also

Other coo_ intersect: [coo_intersect_angle\(\)](#)

Examples

```
coo <- bot[1] %>% coo_center %>% coo_scale
seg <- c(0, 0, 2, 2) # passed as a numeric of length(4)
coo_plot(coo)
segments(seg[1], seg[2], seg[3], seg[4])
coo %>% coo_intersect_segment(seg) %T>% print %>%
# prints on the console and draw it
  coo[., , drop=FALSE] %>% points(col="red")

# on Coo
```

```

bot %>%
  slice(1:3) %>% # for the sake of speed
  coo_center %>%
  coo_intersect_segment(matrix(c(0, 0, 1000, 1000), ncol=2, byrow=TRUE))

```

coo_is_closed	<i>Test if shapes are closed</i>
---------------	----------------------------------

Description

Returns TRUE/FALSE whether the last coordinate of the shapes is the same as the first one.

Usage

```

coo_is_closed(coo)

is_open(coo)

```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a single or a vector of logical.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```

coo_is_closed(matrix(1:10, ncol=2))
coo_is_closed(coo_close(matrix(1:10, ncol=2)))
coo_is_closed(bot)
coo_is_closed(coo_close(bot))

```

coo_jitter	<i>Jitters shapes</i>
------------	-----------------------

Description

A simple wrapper around [jitter](#).

Usage

```
coo_jitter(coo, ...)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
...	additional parameter for jitter

Value

a matrix of (x; y) coordinates or a [Coo](#) object

See Also

[get_pairs](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <-bot[1]
coo_plot(b, zoom=0.2)
coo_draw(coo_jitter(b, amount=3), border="red")

# for a Coo example, see \link{get_pairs}
```

coo_ldk	<i>Defines landmarks interactively</i>
---------	--

Description

Allows to interactively define a `nb.ldk` number of landmarks on a shape. Used in other facilities to acquire/manipulate data.

Usage

```
coo_ldk(coo, nb.ldk, close = FALSE, points = TRUE)
```

Arguments

<code>coo</code>	a matrix or a list of (x; y) coordinates.
<code>nb.ldk</code>	integer, the number of landmarks to define
<code>close</code>	logical whether to close (typically for outlines)
<code>points</code>	logical whether to display points

Value

numeric that corresponds to the closest ids, on the shape, from clicked points.

Examples

```
## Not run:  
b <- bot[1]  
coo_ldk(b, 3) # run this, and click 3 times  
coo_ldk(bot, 2) # this also works on Out  
  
## End(Not run)
```

coo_left	<i>Retains coordinates with negative x-coordinates</i>
----------	--

Description

Useful when shapes are aligned along the y-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the lower side.

Usage

```
coo_left(coo, slidegap = FALSE)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
 slidegap logical whether to apply [coo_slidegap](#) after [coo_left](#)

Value

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

Note

When shapes are "sliced" along the y-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo_slidegap](#). See examples there.

Also, when apply a [coo_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

See Also

Other opening functions: [coo_down\(\)](#), [coo_right\(\)](#), [coo_up\(\)](#)

Other [coo_](#) utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trintop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- coo_center(bot[1])
coo_plot(b)
coo_draw(coo_left(b), border='red')
```

coo_length	<i>Calculates the length of a shape</i>
------------	---

Description

Nothing more than `coo_lw(coo)[1]`.

Usage

```
coo_length(coo)
```

Arguments

coo a matrix of (x; y) coordinates or a Coo object

Details

This function can be used to integrate size - if meaningful - to Coo objects. See also [coo_centsize](#) and [rescale](#).

Value

the length (in pixels) of the shape

See Also

[coo_lw](#), [coo_width](#)

Other coo_descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_length(bot[1])
coo_length(bot)
mutate(bot, size=coo_length(bot))
```

coo_likely_clockwise *Tests if shapes are (likely) developing clockwise or anticlockwise*

Description

Tests if shapes are (likely) developing clockwise or anticlockwise

Usage

```
coo_likely_clockwise(coo)

## Default S3 method:
coo_likely_clockwise(coo)

## S3 method for class 'Coo'
coo_likely_clockwise(coo)

coo_likely_anticlockwise(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

a single or a vector of logical.

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```
shapes[4] %>% coo_sample(64) %>% coo_plot() #clockwise cat
shapes[4] %>% coo_likely_clockwise()
shapes[4] %>% coo_rev() %>% coo_likely_clockwise()

# on Coo
shapes %>% coo_likely_clockwise %>% `[`(4)
```

coo_listpanel

Plots sets of shapes.

Description

`coo_listpanel` plots a list of shapes if passed with a list of coordinates. Mainly used by `panel.Coo` functions. If used outside the latter, shapes must be "templated", see `coo_template`. If you want to reorder shapes according to a factor, use `arrange`.

Usage

```
coo_listpanel(
  coo.list,
  dim,
  byrow = TRUE,
  fromtop = TRUE,
  cols,
  borders,
  poly = TRUE,
  points = FALSE,
  points.pch = 3,
  points.cex = 0.2,
  points.col = "#333333",
  ...
)
```

Arguments

<code>coo.list</code>	A list of coordinates
<code>dim</code>	A vector of the form <code>(nb.row, nb.cols)</code> to specify the panel display. If missing, shapes are arranged in a square.
<code>byrow</code>	logical. Whether to draw successive shape by row or by col.
<code>fromtop</code>	logical. Whether to display shapes from the top of the plotting region.
<code>cols</code>	A vector of colors to fill shapes.
<code>borders</code>	A vector of colors to draw shape borders.
<code>poly</code>	logical whether to use polygon or lines to draw shapes. mainly for use for outlines and open outlines.
<code>points</code>	logical if <code>poly</code> is set to FALSE whether to add points
<code>points.pch</code>	if <code>points</code> is TRUE, a <code>pch</code> for these points
<code>points.cex</code>	if <code>points</code> is TRUE, a <code>cex</code> for these points
<code>points.col</code>	if <code>points</code> is TRUE, a <code>col</code> for these points
<code>...</code>	additional arguments to feed generic plot

Value

Returns (invisibly) a `data.frame` with position of shapes that can be used for other sophisticated plotting design.

See Also

Other plotting functions: `coo_arrows()`, `coo_draw()`, `coo_lolli()`, `coo_plot()`, `coo_ruban()`, `ldk_chull()`, `ldk_confell()`, `ldk_contour()`, `ldk_labels()`, `ldk_links()`, `plot_devsegments()`, `plot_table()`

Examples

```
coo_listpanel(bot$coo) # equivalent to panel(bot)
```

`coo_lolli`

Plots (lollipop) differences between two configurations

Description

Draws 'lollipops' between two configurations.

Usage

```
coo_lolli(coo1, coo2, pch = NA, cex = 0.5, ...)
```

Arguments

coo1	A list or a matrix of coordinates.
coo2	A list or a matrix of coordinates.
pch	a pch for the points (default to NA)
cex	a cex for the points
...	optional parameters to fed points and segments .

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Examples

```
coo_lolli(coo_sample(olea[3], 50), coo_sample(olea[6], 50))
title("A nice title !")
```

coo_lw

Calculates length and width of a shape

Description

Returns the length and width of a shape based on their inertia axis i.e. alignment to the x-axis. The length is defined as the range along the x-axis; the width as the range on the y-axis.

Usage

```
coo_lw(coo)
```

Arguments

coo	a matrix of (x; y) coordinates or Coo object
-----	--

Value

a vector of two numeric: the length and the width.

See Also

[coo_length](#), [coo_width](#).

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_lw(bot[1])
```

coo_nb	<i>Counts coordinates</i>
--------	---------------------------

Description

Returns the number of coordinates, for a single shape or a Coo object

Usage

```
coo_nb(coo)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.

Value

either a single numeric or a vector of numeric

See Also

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
# single shape
coo_nb(bot[1])
# Coo object
coo_nb(bot)
```

coo_oscillo

Momocs' 'oscilloscope' for Fourier-based approaches

Description

Shape analysis deals with curve fitting, whether $x(t)$ and $y(t)$ positions along the curvilinear abscissa and/or radius/tangent angle variation. These functions are mainly intended for (self-)teaching of Fourier-based methods.

Usage

```
coo_oscillo(
    coo,
    method = c("efourier", "rfourier", "tfourier", "all")[4],
    shape = TRUE,
    nb.pts = 12
)
```

Arguments

coo	A list or a matrix of coordinates.
method	character among c('efourier', 'rfourier', 'tfourier', 'all'). 'all' by default
shape	logical whether to plot the original shape
nb.pts	integer. The number or reference points, sampled equidistantly along the curvilinear abscissa and added on the oscillo curves.

Value

the plotted values

See Also

exemplifying functions

Examples

```
coo_oscillo(shapes[4])
coo_oscillo(shapes[4], 'efourier')
coo_oscillo(shapes[4], 'rfourier')
coo_oscillo(shapes[4], 'tfourier')
#tfourier is prone to high-frequency noise but smoothing can help
coo_oscillo(coo_smooth(shapes[4], 10), 'tfourier')
```

`coo_perim`*Calculates perimeter and variations*

Description

`coo_perim` calculates the perimeter; `coo_perimpts` calculates the euclidean distance between every points of a shape; `coo_perimcum` does the same and calculates and cumulative sum.

Usage

```
coo_perimpts(coo)

## Default S3 method:
coo_perimpts(coo)

## S3 method for class 'Coo'
coo_perimpts(coo)

coo_perimcum(coo)

## Default S3 method:
coo_perimcum(coo)

## S3 method for class 'Coo'
coo_perimcum(coo)

coo_perim(coo)

## Default S3 method:
coo_perim(coo)

## S3 method for class 'Coo'
coo_perim(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any `Coo`

Value

numeric the distance between every point or a list of those.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#),

```

coo_force2close(), coo_interpolate(), coo_is_closed(), coo_jitter(), coo_left(), coo_likely_clockwise(),
coo_nb(), coo_range(), coo_rev(), coo_right(), coo_rotatecenter(), coo_rotate(), coo_sample_prop(),
coo_samlerr(), coo_sample(), coo_scale(), coo_shearx(), coo_slice(), coo_slidedirection(),
coo_slidegap(), coo_slide(), coo_smoothcurve(), coo_smooth(), coo_template(), coo_trans(),
coo_trimbottom(), coo_trimtop(), coo_trim(), coo_untiltx(), coo_up(), is_equallyspacedradii()

```

Examples

```

# for speed sake
b1 <- coo_sample(bot[1], 12)
b5 <- bot %>% slice(1:5) %>% coo_sample(12)

# coo_perim
coo_perim(b1)
coo_perim(b5)

# coo_perimpts
coo_perimpts(b1)
b5 %>% coo_perimpts()

# coo_perimcum
b1 %>% coo_perimcum()
b5 %>% coo_perimcum()

```

coo_plot

Plots a single shape

Description

A simple wrapper around `plot` for plotting shapes. Widely used in Momocs in other graphical functions, in methods, etc.

Usage

```

coo_plot(
  coo,
  xlim,
  ylim,
  border = "#333333",
  col = NA,
  lwd = 1,
  lty = 1,
  points = FALSE,
  first.point = TRUE,
  cex.first.point = 0.5,
  centroid = TRUE,
  xy.axis = TRUE,
  pch = 1,

```

```

    cex = 0.5,
    main = NA,
    poly = TRUE,
    plot.new = TRUE,
    plot = TRUE,
    zoom = 1,
    ...
)

ldk_plot(coo, ...)

```

Arguments

coo	A list or a matrix of coordinates.
xlim	If coo_plot is called and coo is missing, then a vector of length 2 specifying the xlim of the plotting area.
ylim	If coo_plot is called and coo is missing, then a vector of length 2 specifying the ylim of the plotting area.
border	A color for the shape border.
col	A color to fill the shape polygon.
lwd	The lwd for drawing shapes.
lty	The lty for drawing shapes.
points	logical. Whether to display points. If missing and number of points is < 100, then points are plotted.
first.point	logical whether to plot or not the first point.
cex.first.point	numeric size of this first point
centroid	logical. Whether to display centroid.
xy.axis	logical. Whether to draw the xy axis.
pch	The pch for points.
cex	The cex for points.
main	character. A title for the plot.
poly	logical whether to use polygon and lines to draw the shape, or just points . In other words, whether the shape should be considered as a configuration of landmarks or not (eg a closed outline).
plot.new	logical whether to plot or not a new frame.
plot	logical whether to plot something or just to create an empty plot.
zoom	a numeric to take your distances.
...	further arguments for use in coo_plot methods. See examples.

Value

No returned value.

See Also

Other plotting functions: `coo_arrows()`, `coo_draw()`, `coo_listpanel()`, `coo_lolli()`, `coo_ruban()`, `ldk_chull()`, `ldk_confell()`, `ldk_contour()`, `ldk_labels()`, `ldk_links()`, `plot_devsegments()`, `plot_table()`

Examples

```
b <- bot[1]
coo_plot(b)
coo_plot(bot[2], plot.new=FALSE) # equivalent to coo_draw(bot[2])
coo_plot(b, zoom=2)
coo_plot(b, border='blue')
coo_plot(b, first.point=FALSE, centroid=FALSE)
coo_plot(b, points=TRUE, pch=20)
coo_plot(b, xy.axis=FALSE, lwd=2, col='#F2F2F2')
```

coo_range

Calculate coordinates range

Description

`coo_range` simply returns the range, `coo_range_enlarge` enlarges it by a `k` proportion. `coo_diffrange` return the amplitude (ie diff after `coo_range`)

Usage

```
coo_range(coo)

## Default S3 method:
coo_range(coo)

## S3 method for class 'Coo'
coo_range(coo)

coo_range_enlarge(coo, k)

## Default S3 method:
coo_range_enlarge(coo, k = 0)

## S3 method for class 'Coo'
coo_range_enlarge(coo, k = 0)

## S3 method for class 'list'
coo_range_enlarge(coo, k = 0)

coo_diffrange(coo)
```

```
## Default S3 method:
coo_diffrange(coo)

## S3 method for class 'Coo'
coo_diffrange(coo)

## S3 method for class 'list'
coo_diffrange(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.
`k` numeric proportion by which to enlarge it

Value

a matrix of range such as (min, max) x (x, y)

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trintop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
bot[1] %>% coo_range # single shape
bot    %>% coo_range # Coo object

bot[1] %>% coo_range_enlarge(1/50) # single shape
bot    %>% coo_range_enlarge(1/50) # Coo object
```

`coo_rectangularity` *Calculates the rectangularity of a shape*

Description

Calculates the rectangularity of a shape

Usage

```
coo_rectangularity(coo)
```

Arguments

coo a matrix of (x; y) coordinates or any Coo

Value

numeric for a single shape, list for Coo

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_rectangularity(bot[1])

bot %>%
  slice(1:3) %>% # for speed sake only
  coo_rectangularity
```

coo_rectilinearity *Calculates the rectilinearity of a shape*

Description

As proposed by Zunic and Rosin (see below). May need some testing/review.

Usage

```
coo_rectilinearity(coo)
```

Arguments

coo a matrix of (x; y) coordinates or any Coo

Value

numeric for a single shape, list for Coo

Note

due to the laborious nature of the algorithm (in nb.pts^2), and of its implementation, it may be very long to compute.

Source

Zunic J, Rosin PL. 2003. Rectilinearity measurements for polygons. IEEE Transactions on Pattern Analysis and Machine Intelligence 25: 1193-1200.

See Also

Other `coo_` descriptors: `coo_angle_edges()`, `coo_angle_tangent()`, `coo_area()`, `coo_boundingbox()`, `coo_chull()`, `coo_circularity()`, `coo_convexity()`, `coo_eccentricity`, `coo_elongation()`, `coo_length()`, `coo_lw()`, `coo_rectangularity()`, `coo_scalars()`, `coo_solidity()`, `coo_tac()`, `coo_width()`

Examples

```
bot[1] %>%
  coo_sample(32) %>% # for speed sake only
  coo_rectilinearity

bot %>%
  slice(1:3) %>% coo_sample(32) %>% # for speed sake only
  coo_rectilinearity
```

`coo_rev`*Reverses coordinates*

Description

Returns the reverse suite of coordinates, i.e. change shape's orientation

Usage

```
coo_rev(coo)
```

Arguments

`coo` matrix of (x; y) coordinates or any `Coo` object.

Value

a matrix of (x; y) coordinates or a `Coo` object

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```
b <- coo_sample(bot[1], 4)
b
coo_rev(b)
```

coo_right

Retains coordinates with positive x-coordinates

Description

Useful when shapes are aligned along the y-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the upper side.

Usage

```
coo_right(coo, slidegap = FALSE)
```

Arguments

`coo` matrix of (x; y) coordinates or any `Coo` object.
`slidegap` logical whether to apply `coo_slidegap` after `coo_right`

Value

a matrix of (x; y) coordinates or a `Coo` object (`Out` are returned as `Opn`)

Note

When shapes are "sliced" along the y-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with `coo_slidegap`. See examples there.

Also, when apply a `coo_left/right/up/down` on an `Out` object, you then obtain an `Opn` object, which is done automatically.

See Also

Other opening functions: `coo_down()`, `coo_left()`, `coo_up()`

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samplerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```
b <- coo_center(bot[1])
coo_plot(b)
coo_draw(coo_right(b), border='red')
```

coo_rotate

Rotates coordinates

Description

Rotates the coordinates by a 'theta' angle (in radians) in the trigonometric direction (anti-clockwise). If not provided, assumed to be the centroid size. It involves three steps: centering from current position, dividing coordinates by 'scale', translating to the original position.

Usage

```
coo_rotate(coo, theta = 0)
```

Arguments

`coo` either a matrix of (x; y) coordinates, or any `Coo` object.
`theta` numericthe angle (in radians) to rotate shapes.

Value

a matrix of (x; y) coordinates, or a `Coo` object.

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_sample_prop()`, `coo_samplerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`,

[coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)
 Other rotation functions: [coo_rotatecenter\(\)](#)

Examples

```
coo_plot(bot[1])
coo_plot(coo_rotate(bot[1], pi/2))

# on Coo
b <- bot %>% slice(1:5) # for speed sake
stack(b)
stack(coo_rotate(b, pi/2))
```

coo_rotatecenter	<i>Rotates shapes with a custom center</i>
------------------	--

Description

rotates a shape of 'theta' angles (in radians) and with a (x; y) 'center'.

Usage

```
coo_rotatecenter(coo, theta, center = c(0, 0))
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
theta	numeric the angle (in radians) to rotate shapes.
center	numeric the (x; y) position of the center

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other rotation functions: [coo_rotate\(\)](#)

Other [coo_](#) utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Other rotation functions: [coo_rotate\(\)](#)

Examples

```
b <- bot[1]
coo_plot(b)
coo_draw(coo_rotatecenter(b, -pi/2, c(200, 200)), border='red')
```

coo_ruban

Plots differences as (colored) segments aka a ruban

Description

Useful to display differences between shapes

Usage

```
coo_ruban(coo, dev, palette = col_heat, normalize = TRUE, ...)
```

Arguments

coo	a shape, typically a mean shape
dev	numeric a vector of distances or anything relevant
palette	the color palette to use or any palette
normalize	logical whether to normalize (TRUE by default) distances
...	other parameters to feed segments, eg lwd (see examples)

Value

nothing

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Examples

```
ms <- MSHAPES(efourier(bot , 10), "type")
b <- ms$shp$beer
w <- ms$shp$whisky
# we obtain the mean shape, then euclidean distances between points
m <- MSHAPES(list(b, w))
d <- edm(b, w)
# First plot
coo_plot(m, plot=FALSE)
```

```

coo_draw(b)
coo_draw(w)
coo_ruban(m, d, lwd=5)

#Another example
coo_plot(m, plot=FALSE)
coo_ruban(m, d, palette=col_summer2, lwd=5)

#If you want linewidth rather than color
coo_plot(m, plot=FALSE)
coo_ruban(m, d, palette=col_black)

```

coo_sample	<i>Sample coordinates (among points)</i>
------------	--

Description

Sample n coordinates among existing points.

Usage

```
coo_sample(coo, n)
```

Arguments

coo	either a matrix of (x; y) coordinates or an Out or an Opn object.
n	integer, the number fo points to sample.

Details

For the [Out](#) an [Opn](#) methods (pointless for [Ldk](#)), in an `$ldk` component is defined, it is changed accordingly by multiplying the ids by n over the number of coordinates.

Value

a matrix of (x; y) coordinates, or an [Out](#) or an [Opn](#) object.

See Also

Other sampling functions: [coo_extract\(\)](#), [coo_interpolate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```

b <- bot[1]
stack(bot)
stack(coo_sample(bot, 24))
coo_plot(b)
coo_plot(coo_sample(b, 24))

```

coo_samlerr

Samples coordinates (regular radius)

Description

Samples n coordinates with a regular angle.

Usage

```
coo_samlerr(coo, n)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
n integer, the number of points to sample.

Details

By design, this function samples among existing points, so using [coo_interpolate](#) prior to it may be useful to have more homogeneous angles. See examples.

Value

a matrix of (x; y) coordinates or a [Coo](#) object.

See Also

Other sampling functions: [coo_extract\(\)](#), [coo_interpolate\(\)](#), [coo_sample_prop\(\)](#), [coo_sample\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```

stack(bot)
bot <- coo_center(bot)
stack(coo_samlerr(bot, 12))
coo_plot(bot[1])
coo_plot(rr <- coo_samlerr(bot[1], 12))
cpos <- coo_centpos(bot[1])
segments(cpos[1], cpos[2], rr[, 1], rr[, 2])

# Sometimes, interpolating may be useful:
shp <- hearts[1] %>% coo_center

# given a shp, draw segments from each points on it, to its centroid
draw_rads <- function(shp, ...){
  segments(shp[, 1], shp[, 2], coo_centpos(shp)[1], coo_centpos(shp)[2], ...)
}

# calculate the sd of argument difference in successive points,
# in other words a proxy for the homogeneity of angles
sd_theta_diff <- function(shp)
  shp %>% complex(real=.[, 1], imaginary=.[, 2]) %>%
  Arg %>% `\[(-1) %>% diff %>% sd

# no interpolation: all points are sampled from existing points but the
# angles are not equal
shp %>% coo_plot(points=TRUE, main="no interpolation")
shp %>% coo_samlerr(64) %T>% draw_rads(col="red") %>% sd_theta_diff
# with interpolation: much more homogeneous angles
shp %>% coo_plot(points=TRUE)
shp %>% coo_interpolate(360) %>% coo_samlerr(64) %T>% draw_rads(col="blue") %>% sd_theta_diff

```

coo_sample_prop	<i>Sample a proportion of coordinates (among points)</i>
-----------------	--

Description

A simple wrapper around [coo_sample](#)

Usage

```
coo_sample_prop(coo, prop = 1)
```

Arguments

coo	either a matrix of (x; y) coordinates or an Out or an Opn object.
prop	numeric, the proportion of points to sample

Details

As for [coo_sample](#) if an `$ldk` component is defined, it is changed accordingly by multiplying the `ids` by `n` over the number of coordinates.

Value

a matrix of (x; y) coordinates, or an [Out](#) or an [Opn](#) object.

See Also

Other sampling functions: [coo_extract\(\)](#), [coo_interpolate\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
# single shape
bot[1] %>% coo_nb()
bot[1] %>% coo_sample_prop(0.5) %>% coo_nb()
```

coo_scalars

Calculates all scalar descriptors of shape

Description

See examples for the full list.

Usage

```
coo_scalars(coo, rectilinearity = FALSE)
```

Arguments

`coo` a matrix of (x; y) coordinates or any `Coo`
`rectilinearity` logical whether to include rectilinearity using [coo_rectilinearity](#)

Details

[coo_rectilinearity](#) being not particularly optimized, it takes around 30 times more time to include it than to calculate *all* others and is thus not included by default. by default.

Value

data_frame

See Also

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
df <- bot %>% coo_scalars() # pass bot %>% coo_scalars(TRUE) if you want rectilinearity
colnames(df) %>% cat(sep="\n") # all scalars used
```

```
# a PCA on all these descriptors
TraCoe(coo_scalars(bot), fac=bot$fac) %>% PCA %>% plot_PCA(~type)
```

coo_scale

Scales coordinates

Description

`coo_scale` scales the coordinates by a 'scale' factor. If not provided, assumed to be the centroid size. It involves three steps: centering from current position, dividing coordinates by 'scale', pushing back to the original position. `coo_scalex` applies a scaling (or shrinking) parallel to the x-axis, `coo_scaley` does the same for the y axis.

Usage

```
coo_scale(coo, scale)

## Default S3 method:
coo_scale(coo, scale = coo_centsize(coo))

## S3 method for class 'Coo'
coo_scale(coo, scale)

coo_scalex(coo, scale = 1)

## Default S3 method:
coo_scalex(coo, scale = 1)

## S3 method for class 'Coo'
coo_scalex(coo, scale = 1)
```

```

coo_scaley(coo, scale = 1)

## Default S3 method:
coo_scaley(coo, scale = 1)

## S3 method for class 'Coo'
coo_scaley(coo, scale = 1)

```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

`scale` the scaling factor, by default, the centroid size for `coo_scale`; 1 for `scalex` and `scaley`.

Value

a single shape or a `Coo` object

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignnax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Other scaling functions: [coo_template\(\)](#)

Examples

```

# on a single shape
b <- bot[1] %>% coo_center %>% coo_scale
coo_plot(b, lwd=2)
coo_draw(coo_scalex(b, 1.5), bor="blue")
coo_draw(coo_scaley(b, 0.5), bor="red")

# this also works on Coo objects:
b <- slice(bot, 5) # for speed sake
stack(b)
b %>% coo_center %>% coo_scale %>% stack
b %>% coo_center %>% coo_scaley(0.5) %>% stack
#equivalent to:
#b %>% coo_center %>% coo_scalex(2) %>% stack

```

 coo_shearx

Shears shapes

Description

coo_shearx applies a shear mapping on a matrix of (x; y) coordinates (or a list), parallel to the x-axis (i.e. $x' = x + ky$; $y' = y + kx$). coo_sheary does it parallel to the y-axis.

Usage

```
coo_shearx(coo, k)
```

```
coo_sheary(coo, k)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
 k numeric shear factor

Value

a matrix of (x; y) coordinates.

See Also

Other transforming functions: [coo_flipx\(\)](#)

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
coo <- coo_template(shapes[11])
coo_plot(coo)
coo_draw(coo_shearx(coo, 0.5), border="blue")
coo_draw(coo_sheary(coo, 0.5), border="red")
```

coo_slice

*Slices shapes between successive coordinates***Description**

Takes a shape with n coordinates. When you pass this function with at least two ids ($\leq n$), the shape will be open on the corresponding coordinates and slices returned as a list

Usage

```
coo_slice(coo, ids, ldk)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
ids	numeric of length ≥ 2 , where to slice the shape(s)
ldk	numeric the id of the ldk to use as ids, only on <code>Out</code> and <code>Opn</code> . If provided, ids will be ignored.

Value

a list of shapes or a list of [Opn](#)

See Also

Have a look to [coo_slidegap](#) if you have problems with gaps after slicing around landmarks and/or starting points.

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
h <- slice(hearts, 1:5) # speed purpose only
# single shape, a list of matrices is returned
sh <- coo_slice(h[1], c(12, 24, 36, 48))
coo_plot(sh[[1]])
panel(Opn(sh))
# on a Coo, a list of Opn is returned
# makes no sense if shapes are not normalized first
sh2 <- coo_slice(h, c(12, 24, 36, 48))
panel(sh2[[1]])
```

```

# Use coo_slice with `ldk` instead:
# hearts as an example
x <- h %>% fgProcrustes(tol=1)
# 4 landmarks
stack(x)
x$ldk[1:5]

# here we slice
y <- coo_slice(x, ldk=1:4)

# plotting
stack(y[[1]])
stack(y[[2]])

# new ldk from tipping points, new ldk from angle
olea %>% slice(1:5) %>% # for the sake of speed
def_ldk_tips %>%
def_ldk_angle(0.75*pi) %>% def_ldk_angle(0.25*pi) %>%
coo_slice(ldk =1:4) -> oleas
oleas[[1]] %>% stack
oleas[[2]] %>% stack # etc.

# domestic operations
y[[3]] %>% coo_area()
# shape analysis of a slice
y[[1]] %>% coo_bookstein() %>% npoly %>% PCA %>% plot(~aut)

```

coo_slide

Slides coordinates

Description

Slides the coordinates so that the id-th point become the first one.

Usage

```
coo_slide(coo, id, ldk)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
id	numeric the id of the point that will become the new first point. See details below for the method on Coo objects.
ldk	numeric the id of the ldk to use as id, only on Out

Details

For Coo objects, and in particular for Out and Opn three different ways of `coo_sliding` are available:

- **no ldk passed and a single id is passed:** all id-th points within the shapes will become the first points. \$ldk will be slided accordingly.
- **no ldk passed and a vector of ids matching the length of the Coo:** for every shape, the id-th point will be used as the id-th point. \$ldk will be slided accordingly.
- **a single ldk is passed:** the ldk-th ldk will be used to slide every shape. If an id is (also) passed, it is ignored with a message.

See examples.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

[coo_slice](#) and friends.

Other sliding functions: [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samplerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
h <- hearts %>% slice(1:5) # for speed sake
stack(h)
# set the first landmark as the starting point
stack(coo_slide(h, ldk=1))
# set the 50th point as the starting point (everywhere)
stack(coo_slide(h, id=50))
# set the id-random-th point as the starting point (everywhere)
set.seed(123) # just for the reproducibility
id_random <- sample(x=min(sapply(h$coo, nrow)), size=length(h),
replace=TRUE)
stack(coo_slide(h, id=id_random))
```

coo_slidedirection	<i>Slides coordinates in a particular direction</i>
--------------------	---

Description

Shapes are centered and then, according to direction, the point northwards, southwards, eastwards or westwards the centroid, becomes the first point with `coo_slide`. 'right' is possibly the most sensible option (and is by default), since 0 radians points eastwards, relatively to the origin. This should be followed by a `coo_untiltx` in most cases to remove any rotational dephasing/bias.

Usage

```
coo_slidedirection(
  coo,
  direction = c("down", "left", "up", "right")[4],
  center,
  id
)
```

Arguments

coo	matrix of (x; y) coordinates or any <code>Coo</code> object.
direction	character one of "down", "left", "up", "right" ("right" by default)
center	logical whether to center or not before sliding
id	numeric whether to return the id of the point or the slided shapes

Value

a matrix of (x; y) coordinates, or a `Coo` object.

See Also

Other sliding functions: `coo_slidegap()`, `coo_slide()`

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_allyspacedradii()`

Examples

```

b <- coo_rotate(bot[1], pi/6) # dummy example just to make it obvious
coo_plot(b) # not the first point
coo_plot(coo_slidedirection(b, "up"))
coo_plot(coo_slidedirection(b, "right"))
coo_plot(coo_slidedirection(b, "left"))
coo_plot(coo_slidedirection(b, "down"))

# on Coo objects
b <- bot %>% slice(1:5) # for speed sake
stack(b)
stack(coo_slidedirection(b, "right"))

# This should be followed by a [coo_untiltx] in most (if not all) cases
stack(coo_slidedirection(b, "right") %>% coo_untiltx)

```

coo_slidegap

Slides coordinates using the widest gap

Description

When slicing a shape using two landmarks, or functions such as `coo_up`, an open curve is obtained and the rank of points make wrong/artefactual results. If the widest gap is $> 5 * \text{median of other gaps}$, then the couple of coordinates forming this widest gap is used as starting and ending points. This switch helps to deal with open curves. Examples are self-speaking. Use `force=TRUE` to bypass this check

Usage

```
coo_slidegap(coo, force)
```

Arguments

`coo` matrix of (x; y) coordinates or any `Coo` object.
`force` logical whether to use the widest gap, with no check, as the real gap

Value

a matrix of (x; y) coordinates or a `Coo` object.

See Also

Other sliding functions: `coo_slidedirection()`, `coo_slide()`

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`,


```
coo_nb(), coo_perim(), coo_range(), coo_rev(), coo_right(), coo_rotatecenter(), coo_rotate(),
coo_sample_prop(), coo_samlerr(), coo_sample(), coo_scale(), coo_shearx(), coo_slice(),
coo_slidedirection(), coo_slide(), coo_smoothcurve(), coo_smooth(), coo_template(),
coo_trans(), coo_trimbottom(), coo_trimtop(), coo_trim(), coo_untiltx(), coo_up(), is_equallyspacedradii()
```

Examples

```
cat <- coo_center(shapes[4])
coo_plot(cat)

# we only retain the bottom of the cat
cat_down <- coo_down(cat, slidegap=FALSE)

# see? the segment on the x-axis coorespond to the widest gap.
coo_plot(cat_down)

# that's what we meant
coo_plot(coo_slidegap(cat_down))
```

coo_smooth

Smoothes coordinates

Description

Smoothes coordinates using a simple moving average. May be useful to remove digitization noise, mainly on outlines and open outlines.

Usage

```
coo_smooth(coo, n)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
n integer the number of smoothing iterations

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other smoothing functions: [coo_smoothcurve\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#),

[coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
b5 <- slice(bot, 1:5) # for speed sake
stack(b5)
stack(coo_smooth(b5, 10))
coo_plot(b5[1])
coo_plot(coo_smooth(b5[1], 30))
```

coo_smoothcurve	<i>Smooths coordinates on curves</i>
-----------------	--------------------------------------

Description

Smooths coordinates using a simple moving average but let the first and last points unchanged. May be useful to remove digitization noise on curves.

Usage

```
coo_smoothcurve(coo, n)
```

Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.
`n` integer to specify the number of smoothing iterations

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

Other smoothing functions: [coo_smooth\(\)](#)

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_allyspacedradii\(\)](#)

Examples

```
o <- olea[1]
coo_plot(o, border='grey50', points=FALSE)
coo_draw(coo_smooth(o, 24), border='blue', points=FALSE)
coo_draw(coo_smoothcurve(o, 24), border='red', points=FALSE)
```

coo_solidity	<i>Calculates the solidity of a shape</i>
--------------	---

Description

Calculated using the ratio of the shape area and the convex hull area.

Usage

```
coo_solidity(coo)
```

Arguments

coo a matrix of (x; y) coordinates or any Coo

Value

numeric for a single shape, list for Coo

Source

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

See Also

Other coo_ descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_tac\(\)](#), [coo_width\(\)](#)

Examples

```
coo_solidity(bot[1])

bot %>%
  slice(1:3) %>% # for speed sake only
  coo_solidity
```

coo_tac	<i>Calculates the total absolute curvature of a shape</i>
---------	---

Description

Calculated using the sum of the absolute value of the second derivative of the `smooth.spline` prediction for each defined point.

Usage

```
coo_tac(coo)
```

Arguments

`coo` a matrix of (x; y) coordinates or any `Coo`

Value

numeric for a single shape and for `Coo`

Source

Siobhan Braybrook.

See Also

Other `coo_` descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_width\(\)](#)

Examples

```
coo_tac(bot[1])

bot %>%
  slice(1:3) %>% # for speed sake only
  coo_tac
```

coo_template	<i>'Templates' shapes</i>
--------------	---------------------------

Description

coo_template returns shape centered on the origin and inscribed in a size-side square. coo_template_relatively does the same but the biggest shape (as prod(coo_diffrange)) will be of size=size and consequently not defined on single shapes.

Usage

```
coo_template(coo, size)

## Default S3 method:
coo_template(coo, size = 1)

## S3 method for class 'list'
coo_template(coo, size = 1)

## S3 method for class 'Coo'
coo_template(coo, size = 1)

coo_template_relatively(coo, size = 1)

## S3 method for class 'list'
coo_template_relatively(coo, size = 1)

## S3 method for class 'Coo'
coo_template_relatively(coo, size = 1)
```

Arguments

coo	A list or a matrix of coordinates.
size	numeric. Indicates the length of the side 'inscribing' the shape.

Details

See [coo_listpanel](#) for an illustration of this function. The morphospaces functions also take profit of this function. May be useful to develop other graphical functions.

Value

Returns a matrix of (x; y)coordinates.

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Other scaling functions: `coo_scale()`

Examples

```
coo <- bot[1]
coo_plot(coo_template(coo), xlim=c(-1, 1), ylim=c(-1, 1))
rect(-0.5, -0.5, 0.5, 0.5)

s <- 0.01
coo_plot(coo_template(coo, s))
rect(-s/2, -s/2, s/2, s/2)
```

`coo_trans`

Translates coordinates

Description

Translates the coordinates by a 'x' and 'y' value

Usage

```
coo_trans(coo, x = 0, y = 0)
```

Arguments

<code>coo</code>	matrix of (x; y) coordinates or any <code>Coo</code> object.
<code>x</code>	numeric translation along the x-axis.
<code>y</code>	numeric translation along the y-axis.

Value

a matrix of (x; y) coordinates, or a `Coo` object.

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_trim()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Examples

```
coo_plot(bot[1])
coo_plot(coo_trans(bot[1], 50, 100))

# on Coo
b <- bot %>% slice(1:5) # for speed sake
stack(b)
stack(coo_trans(b, 50, 100))
```

coo_trim

Trims both ends coordinates from shape

Description

Removes trim coordinates at both ends of a shape, ie from top and bottom of the shape matrix.

Usage

```
coo_trim(coo, trim = 1)
```

Arguments

`coo` matrix of (x; y) coordinates or any `Coo` object.
`trim` numeric, the number of coordinates to trim

See Also

Other `coo_` utilities: `coo_aligncalliper()`, `coo_alignminradius()`, `coo_alignxax()`, `coo_align()`, `coo_baseline()`, `coo_bookstein()`, `coo_boundingbox()`, `coo_calliper()`, `coo_centdist()`, `coo_center()`, `coo_centpos()`, `coo_close()`, `coo_down()`, `coo_dxy()`, `coo_extract()`, `coo_flipx()`, `coo_force2close()`, `coo_interpolate()`, `coo_is_closed()`, `coo_jitter()`, `coo_left()`, `coo_likely_clockwise()`, `coo_nb()`, `coo_perim()`, `coo_range()`, `coo_rev()`, `coo_right()`, `coo_rotatecenter()`, `coo_rotate()`, `coo_sample_prop()`, `coo_samlerr()`, `coo_sample()`, `coo_scale()`, `coo_shearx()`, `coo_slice()`, `coo_slidedirection()`, `coo_slidegap()`, `coo_slide()`, `coo_smoothcurve()`, `coo_smooth()`, `coo_template()`, `coo_trans()`, `coo_trimbottom()`, `coo_trimtop()`, `coo_untiltx()`, `coo_up()`, `is_equallyspacedradii()`

Other `coo_` trimming functions: `coo_trimbottom()`, `coo_trimtop()`

Examples

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trim(1) %T>% print() %>% points(col="red")
```

coo_trimbottom	<i>Trims bottom coordinates from shape</i>
----------------	--

Description

Removes trim coordinates from the bottom of a shape.

Usage

```
coo_trimbottom(coo, trim = 1)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
trim	numeric, the number of coordinates to trim

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Other `coo_` trimming functions: [coo_trimtop\(\)](#), [coo_trim\(\)](#)

Examples

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trimbottom(4) %T>% print() %>% points(col="red")
```

coo_trimtop	<i>Trims top coordinates from shape</i>
-------------	---

Description

Removes trim coordinates from the top of a shape.

Usage

```
coo_trimtop(coo, trim = 1)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
trim	numeric, the number of coordinates to trim

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Other `coo_` trimming functions: [coo_trimbottom\(\)](#), [coo_trim\(\)](#)

Examples

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trimtop(4) %T>% print() %>% points(col="red")
```

coo_truss	<i>Truss measurement</i>
-----------	--------------------------

Description

A method to calculate on shapes or on [Coo](#) truss measurements, that is all pairwise combinations of euclidean distances

Usage

```
coo_truss(x)
```

Arguments

x a shape or an Ldk object

Value

a named numeric or matrix

Note

Mainly implemented for historical/didactical reasons.

See Also

Other premodern: [measure\(\)](#)

Examples

```
# example on a single shape
cat <- coo_sample(shapes[4], 6)
coo_truss(cat)

# example on wings dataset
tx <- coo_truss(wings)
dim(tx)
# we normalize and plot an heatmap
txn <- apply(tx$coe, 2, .normalize)
# heatmap(txn)

txp <- PCA(tx, scale. = TRUE, center=TRUE, fac=wings$fac)
plot(txp, 1)
```

coo_untiltx	<i>Removes rotation so that the centroid and a given point are parallel to the x-axis</i>
-------------	---

Description

Rotationnal biases appear after [coo_slidedirection](#) (and friends). Typically useful for outline analysis where phasing matters. See examples.

Usage

```
coo_untiltx(coo, id, ldk)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
id numeric the id of the point that will become the new first point. See details below for the method on [Coo](#) objects.
ldk numeric the id of the [Ldk](#) to use as id, only on [Out](#)

Details

For Coo objects, and in particular for Out and Opn two different ways of coo_sliding are available:

- **no ldk passed and an id is passed:** all id-th points within the shapes will become the first points.
- **a single ldk is passed:** the ldk-th ldk will be used to slide every shape. If an id is (also) passed, id is ignored with a message.

Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

See Also

[coo_slide](#) and friends.

Other coo_ utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_up\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
# on a single shape
bot[1] %>% coo_center %>% coo_align %>%
  coo_sample(12) %>% coo_slidedirection("right") %T>%
  coo_plot() %>% # the first point is not on the x-axis
  coo_untiltx() %>%
  coo_draw(border="red") # this (red) one is

# on an Out
# prepare bot
prebot <- bot %>% coo_center %>% coo_scale %>%
  coo_align %>% coo_slidedirection("right")
prebot %>% stack # some dephasing remains
prebot %>% coo_slidedirection("right") %>% coo_untiltx() %>% stack # much better
# _here_ there is no change but the second, untitled, is correct
prebot %>% efourier(8, norm=FALSE) %>% PCA %>% plot_PCA(~type)
prebot %>% coo_untiltx %>% efourier(8, norm=FALSE) %>% PCA %>% plot_PCA(~type)

# an example using ldk:
# the landmark #2 is on the x-axis
hearts %>%
  slice(1:5) %>% fgProcrustes(tol=1e-3) %>% # for speed sake
  coo_center %>% coo_untiltx(ldk=2) %>% stack
```

coo_up	<i>Retains coordinates with positive y-coordinates</i>
--------	--

Description

Useful when shapes are aligned along the x-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the upper side.

Usage

```
coo_up(coo, slidegap = FALSE)
```

Arguments

coo	matrix of (x; y) coordinates or any Coo object.
slidegap	logical whether to apply coo_slidegap after coo_down

Value

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

Note

When shapes are "sliced" along the x-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo_slidegap](#). See examples there.

Also, when apply a [coo_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

See Also

Other opening functions: [coo_down\(\)](#), [coo_left\(\)](#), [coo_right\(\)](#)

Other [coo_](#) utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [is_equallyspacedradii\(\)](#)

Examples

```
b <- coo_alignxax(bot[1])
coo_plot(b)
coo_draw(coo_up(b), border='red')
```

coo_width	<i>Calculates the width of a shape</i>
-----------	--

Description

Nothing more than `coo_lw(coo)[2]`.

Usage

```
coo_width(coo)
```

Arguments

`coo` a matrix of (x; y) coordinates or Coo object

Value

the width (in pixels) of the shape

See Also

[coo_lw](#), [coo_length](#).

Other `coo_` descriptors: [coo_angle_edges\(\)](#), [coo_angle_tangent\(\)](#), [coo_area\(\)](#), [coo_boundingbox\(\)](#), [coo_chull\(\)](#), [coo_circularity\(\)](#), [coo_convexity\(\)](#), [coo_eccentricity](#), [coo_elongation\(\)](#), [coo_length\(\)](#), [coo_lw\(\)](#), [coo_rectangularity\(\)](#), [coo_rectilinearity\(\)](#), [coo_scalars\(\)](#), [coo_solidity\(\)](#), [coo_tac\(\)](#)

Examples

```
coo_width(bot[1])
```

<code>d</code>	<i>A wrapper to calculates euclidean distances between two points</i>
----------------	---

Description

The main advantage over [ed](#) is that it is a method that can be passed to different objects and used in combination with [measure](#). See examples.

Usage

```
d(x, id1, id2)
```

Arguments

x	a Ldk (typically), an Out or a matrix
id1	id of the 1st row
id2	id of the 2nd row

Note

On Out objects, we first [get_ldk](#).

See Also

if you want all pairwise combinations, see [coo_truss](#)

Examples

```
# single shape
d(wings[1], 1, 4)
# Ldk object
d(wings, 1, 4)
# Out object
d(hearts, 2, 4)
```

def_ldk

Defines new landmarks on Out and Opn objects

Description

Helps to define landmarks on a Coo object. The number of landmarks must be specified and rows indices that correspond to the nearest points clicked on every outlines are stored in the \$ldk slot of the Coo object.

Usage

```
def_ldk(Coo, nb.ldk, close, points)
```

Arguments

Coo	an Out or Opn object
nb.ldk	the number of landmarks to define on every shape
close	logical whether to close (typically for outlines)
points	logical whether to display points

Value

an Out or an Opn object with some landmarks defined

See Also

Other ldk/slidings methods: [add_ldk\(\)](#), [def_slidings\(\)](#), [get_ldk\(\)](#), [get_slidings\(\)](#), [rearrange_ldk\(\)](#), [slidings_scheme\(\)](#)

Examples

```
## Not run:
bot <- bot[1:5] # to make it shorter to try
# click on 3 points, 5 times.
# Don't forget to save the object returned by def_ldk...
bot2 <- def_ldk(bot, 3)
stack(bot2)
bot2$ldk

## End(Not run)
```

def_ldk_angle	<i>Add new landmarks based on angular positions</i>
---------------	---

Description

A wrapper on [coo_intersect_angle](#) and [coo_intersect_direction](#) for [Out](#) and [Opn](#) objects.

Usage

```
def_ldk_angle(coo, angle)

def_ldk_direction(coo, direction = c("down", "left", "up", "right")[4])

## Default S3 method:
def_ldk_direction(coo, direction = c("down", "left", "up", "right")[4])

## S3 method for class 'Out'
def_ldk_direction(coo, direction = c("down", "left", "up", "right")[4])

## S3 method for class 'Opn'
def_ldk_direction(coo, direction = c("down", "left", "up", "right")[4])
```

Arguments

coo	a codeOut or Opn object
angle	numeric an angle in radians (0 by default).
direction	character one of "down", "left", "up", "right" ("right" by default)

Note

any existing ldk will be preserved.

See Also

Typically used before [coo_slice](#) and [coo_slide](#). See [def_ldk_tips](#) as well.

Examples

```
# adds a new landmark towards south east
hearts %>%
  slice(1:5) %>% # for speed purpose only
  def_ldk_angle(-pi/6) %>%
stack()
```

```
# on Out and towards NW and NE here
olea %>%
  slice(1:5) %>% #for speed purpose only
  def_ldk_angle(3*pi/4) %>%
  def_ldk_angle(pi/4) %>%
stack
```

def_ldk_tips	<i>Define tips as new landmarks</i>
--------------	-------------------------------------

Description

On [Opn](#) objects, this can be used before [coo_slice](#). See examples.

Usage

```
def_ldk_tips(coo)
```

Arguments

coo Opn object

Note

any existing ldk will be preserved.

Examples

```
is_ldk(olea) # no ldk for olea
olea %>%
slice(1:3) %>% #for the sake of speed
def_ldk_tips %>%
def_ldk_angle(3*pi/4) %>% def_ldk_angle(pi/4) %T>% stack %>%
coo_slice(ldk=1:4) -> oleas
stack(oleas[[1]])
stack(oleas[[2]]) # etc.
```

def_links	<i>Defines links between landmarks</i>
-----------	--

Description

Works on Ldk objects, on 2-cols matrices, 3-dim arrays ([MSHAPES](#) turns it into a matrix).

Usage

```
def_links(x, nb.ldk)
```

Arguments

x	Ldk, matric or array
nb.ldk	numeric the iterative procedure is stopped when the user click on the top of the graphical window.

See Also

Other ldk helpers: [ldk_check\(\)](#), [links_all\(\)](#), [links_delaunay\(\)](#)

Examples

```
## Not run:
wm <- MSHAPES(wings)
links <- def_links(wm, 3) # click to define pairs of landmarks
ldk_links(wm, links)

## End(Not run)
```

def_slidings	<i>Defines sliding landmarks matrix</i>
--------------	---

Description

Defines sliding landmarks matrix

Usage

```
def_slidings(Coo, slidings)
```

Arguments

Coo	an Ldk object
slidings	a matrix, a numeric or a list of numeric. See Details

Details

\$slidings in **Ldk** must be a 'valid' matrix: containing ids of coordinates, none of them being lower than 1 and higher the number of coordinates in \$coo.

slidings matrix contains 3 columns (before, slide, after). It is inspired by geomorph and should be compatible with it.

This matrix can be passed directly if the slidings argument is a matrix. Of course, it is strictly equivalent to `Ldk$slidings <- slidings`.

slidings can also be passed as "partition(s)", when sliding landmarks identified by their ids (which are a row number) are consecutive in the \$coo.

A single partition can be passed either as a numeric (eg 4:12), if points 5 to 11 must be considered as sliding landmarks (4 and 12 being fixed); or as a list of numeric.

See examples below.

See Also

Other ldk/slidings methods: [add_ldk\(\)](#), [def_ldk\(\)](#), [get_ldk\(\)](#), [get_slidings\(\)](#), [rearrange_ldk\(\)](#), [slidings_scheme\(\)](#)

Examples

```
#waiting for a sliding dataset...
```

dfourier

Discrete cosinus transform

Description

Calculates discrete cosine transforms, as introduced by Dommergues and colleagues, on a shape (mainly open outlines).

Usage

```
dfourier(coo, nb.h)
```

```
## Default S3 method:
```

```
dfourier(coo, nb.h)
```

```
## S3 method for class 'Opn'
```

```
dfourier(coo, nb.h)
```

```
## S3 method for class 'list'
```

```
dfourier(coo, nb.h)
```

```
## S3 method for class 'Coo'
```

```
dfourier(coo, nb.h)
```

Arguments

coo a matrix (or a list) of (x; y) coordinates
 nb.h numeric the number of harmonics to calculate

Value

a list with the following components:

- an the A harmonic coefficients
- bn the B harmonic coefficients
- mod the modules of the points
- arg the arguments of the points

Note

This method has been only poorly tested in Momocs and should be considered as experimental. Yet improved by a factor 10, this method is still long to execute. It will be improved in further releases but it should not be so painful right now. It also explains the progress bar. Shapes should be aligned before performing the dct transform.

Silent message and progress bars (if any) with options("verbose"=FALSE).

References

- Dommergues, C. H., Dommergues, J.-L., & Verrecchia, E. P. (2007). The Discrete Cosine Transform, a Fourier-related Method for Morphometric Analysis of Open Contours. *Mathematical Geology*, 39(8), 749-763. doi:10.1007/s11004-007-9124-6
- Many thanks to Remi Laffont for the translation in R).

See Also

Other dfourier: [dfourier_i\(\)](#), [dfourier_shape\(\)](#)

Examples

```
## Not run: # because it's long
od <- dfourier(olea)
od
op <- PCA(od)
plot(op, 1)

## End(Not run)
# dfourier and inverse dfourier
o <- olea[1]
o <- coo_bookstein(o)
coo_plot(o)
o.dfourier <- dfourier(o, nb.h=12)
o.dfourier
o.i <- dfourier_i(o.dfourier)
o.i <- coo_bookstein(o.i)
```

```

coo_draw(o.i, border='red')

#future calibrate_reconstructions
o <- olea[1]
h.range <- 2:13
coo <- list()
for (i in seq(along=h.range)){
  coo[[i]] <- dfourier_i(dfourier(o, nb.h=h.range[i]))}
names(coo) <- paste0('h', h.range)
panel(Open(coo), borders=col_india(12), names=TRUE)
title('Discrete Cosine Transforms')

```

dfourier_i

Investe discrete cosinus transform

Description

Calculates inverse discrete cosine transforms (see [dfourier](#)), given a list of A and B harmonic coefficients, typically such as those produced by [dfourier](#).

Usage

```
dfourier_i(df, nb.h, nb.pts = 60)
```

Arguments

df	a list with \$A and \$B components, containing harmonic coefficients.
nb.h	a custom number of harmonics to use
nb.pts	numeric the number of pts for the shape reconstruction

Value

a matrix of (x; y) coordinates

Note

Only the core functions so far. Will be implemented as an [Open](#) method soon.

References

- Dommergues, C. H., Dommergues, J.-L., & Verrecchia, E. P. (2007). The Discrete Cosine Transform, a Fourier-related Method for Morphometric Analysis of Open Contours. *Mathematical Geology*, 39(8), 749-763. doi:10.1007/s11004-007-9124-6
- Many thanks to Remi Laffont for the translation in R).

See Also

Other dfourier: [dfourier_shape\(\)](#), [dfourier\(\)](#)

Examples

```

# dfourier and inverse dfourier
o <- olea[1]
o <- coo_bookstein(o)
coo_plot(o)
o.dfourier <- dfourier(o, nb.h=12)
o.dfourier
o.i <- dfourier_i(o.dfourier)
o.i <- coo_bookstein(o.i)
coo_draw(o.i, border='red')

o <- olea[1]
h.range <- 2:13
coo <- list()
for (i in seq(along=h.range)){
  coo[[i]] <- dfourier_i(dfourier(o, nb.h=h.range[i]))}
names(coo) <- paste0('h', h.range)
panel(Open(coo), borders=col_india(12), names=TRUE)
title('Discrete Cosine Transforms')

```

dfourier_shape

*Calculates and draws 'dfourier' shapes***Description**

Calculates shapes based on 'Discrete cosine transforms' given harmonic coefficients (see [dfourier](#)) or can generate some random 'dfourier' shapes. Mainly intended to generate shapes and/or to understand how dfourier works.

Usage

```
dfourier_shape(A, B, nb.h, nb.pts = 60, alpha = 2, plot = TRUE)
```

Arguments

A	vector of harmonic coefficients
B	vector of harmonic coefficients
nb.h	if A and/or B are not provided, the number of harmonics to generate
nb.pts	if A and/or B are not provided, the number of points to use to reconstruct the shapes
alpha	The power coefficient associated with the (usually decreasing) amplitude of the harmonic coefficients (see efourier_shape)
plot	logical whether to plot the shape

See Also

Other dfourier: [dfourier_i\(\)](#), [dfourier\(\)](#)

Examples

```
# some signatures
panel(coo_align(Opn(replicate(48, dfourier_shape(alpha=0.5, nb.h=6))))))
# some worms
panel(coo_align(Opn(replicate(48, dfourier_shape(alpha=2, nb.h=6))))))
```

dissolve

*Dissolve Coe objects***Description**

the opposite of combine, typically used after it. Note that the \$fac slot may be wrong since combine...well combines... this \$fac. See examples.

Usage

```
dissolve(x, retain)
```

Arguments

x	a Coe object
retain	the partition id to retain. Or their name if the partitions are named (see x\$method) eg after a chop

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsize\(\)](#)

Examples

```
data(bot)
w <- filter(bot, type=="whisky")
b <- filter(bot, type=="beer")
wf <- efourier(w, 10)
bf <- efourier(b, 10)
wbf <- combine(wf, bf)
dissolve(wbf, 1)
dissolve(wbf, 2)

# or using chop (yet combine here makes no sense)
bw <- bot %>% chop(~type) %>% lapply(efourier, 10) %>% combine
bw %>% dissolve(1)
bw %>% dissolve(2)
```

drawers *grindr drawers for shape plots*

Description

Useful drawers for building custom shape plots using the grindr approach. See examples and vignettes.

Usage

```
draw_polygon(  
  coo,  
  f,  
  col = par("fg"),  
  fill = NA,  
  lwd = 1,  
  lty = 1,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)
```

```
draw_outline(  
  coo,  
  f,  
  col = par("fg"),  
  fill = NA,  
  lwd = 1,  
  lty = 1,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)
```

```
draw_outlines(  
  coo,  
  f,  
  col = par("fg"),  
  fill = NA,  
  lwd = 1,  
  lty = 1,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)
```

```
draw_points(  
  ...  
)
```

```
    coo,  
    f,  
    col = par("fg"),  
    cex = 1/2,  
    pch = 20,  
    transp = 0,  
    pal = pal_qual,  
    ...  
  )  
  
draw_landmarks(  
  coo,  
  f,  
  col = par("fg"),  
  cex = 1/2,  
  pch = 20,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)  
  
draw_lines(  
  coo,  
  f,  
  col = par("fg"),  
  lwd = 1,  
  lty = 1,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)  
  
draw_centroid(  
  coo,  
  f,  
  col = par("fg"),  
  pch = 3,  
  cex = 0.5,  
  transp = 0,  
  pal = pal_qual,  
  ...  
)  
  
draw_curve(  
  coo,  
  f,  
  col = par("fg"),  
  lwd = 1,
```



```
    lty = 1,
    transp = 0,
    pal = pal_qual,
    ...
)

draw_curves(
  coo,
  f,
  col = par("fg"),
  lwd = 1,
  lty = 1,
  transp = 0,
  pal = pal_qual,
  ...
)

draw_firstpoint(
  coo,
  f,
  label = "^",
  col = par("fg"),
  cex = 3/4,
  transp = 0,
  pal = pal_qual,
  ...
)

draw_axes(coo, col = "#999999", lwd = 1/2, ...)

draw_ticks(coo, col = "#333333", cex = 3/4, lwd = 3/4, ...)

draw_labels(coo, labels = 1:nrow(coo), cex = 1/2, d = 1/20, ...)

draw_links(
  coo,
  f,
  links,
  col = "#99999955",
  lwd = 1/2,
  lty = 1,
  transp = 0,
  pal = pal_qual,
  ...
)

draw_title(
  coo,
```

```

    main = "",
    sub = "",
    cex = c(1, 3/4),
    font = c(2, 1),
    padding = 1/200,
    ...
)

```

Arguments

coo	matrix of 2 columns for (x, y) coordinates
f	an optionnal factor specification to feed. See examples and vignettes.
col	color (hexadecimal) to draw components
fill	color (hexadecimal) to draw components
lwd	to draw components
lty	to draw components
transp	numeric transparency (default:0, min:0, max:1)
pal	a palette to use if no col/border/etc. are provided. See [palettes]
...	additional options to feed core functions for each drawer
cex	to draw components ((c(2, 1) by default) for draw_title)
pch	to draw components
label	to indicate first point
labels	character name of labels to draw (defaut to 1:nrow(coo))
d	numeric proportion of d(centroid-each_point) to add when centrifugating landmarks
links	matrix of links to use to draw segments between landmarks. See wings\$ldk for an example
main	character title (empty by default)
sub	character subtitle (empty by default)
font	numeric to feed <code>text</code> (c(2, 1) by default)
padding	numeric a fraction of the graphical window (1/200 by default)

Note

This approach will (soon) replace `coo_plot` and friends in further versions. All comments are welcome.

See Also

`grindr_layers`

Other `grindr`: `layers_morphospace`, `layers`, `mosaic_engine()`, `papers`, `pile()`, `plot_LDA()`, `plot_NMDS()`, `plot_PCA()`

Examples

```
bot[1] %>% paper_grid() %>% draw_polygon()
olea %>% paper_chess %>% draw_lines(~var)

hearts[240] %>% paper_white() %>% draw_outline() %>%
  coo_sample(24) %>% draw_landmarks %>% draw_labels() %>%
  draw_links(links=replicate(2, sample(1:24, 8)))

bot %>%
  paper_grid() %>%
  draw_outlines() %>%
  draw_title("Alcohol abuse \nis dangerous for health", "Drink responsibly")
```

ed

Calculates euclidean distance between two points.

Description

ed simply calculates euclidean distance between two points defined by their (x; y) coordinates.

Usage

```
ed(pt1, pt2)
```

Arguments

pt1	(x; y) coordinates of the first point.
pt2	(x; y) coordinates of the second point.

Value

Returns the euclidean distance between the two points.

See Also

[edm](#), [edm_nearest](#), [dist](#).

Examples

```
ed(c(0,1), c(1,0))
```

edi *Calculates euclidean intermediate between two points.*

Description

edi simply calculates coordinates of a points at the relative distance r on the $pt1$ - $pt2$ defined by their $(x; y)$ coordinates. This function is used internally but may be of interest for other analyses.

Usage

```
edi(pt1, pt2, r = 0.5)
```

Arguments

pt1 $(x; y)$ coordinates of the first point.
 pt2 $(x; y)$ coordinates of the second point.
 r the relative distance from pt1 to pt2.

Value

returns the $(x; y)$ interpolated coordinates.

See Also

[ed](#), [edm](#).

Examples

```
edi(c(0,1), c(1,0), r = 0.5)
```

edm *Calculates euclidean distance every pairs of points in two matrices.*

Description

edm returns the euclidean distances between points $1 - > n$ of two 2-col matrices of the same dimension. This function is used internally but may be of interest for other analyses.

Usage

```
edm(m1, m2)
```

Arguments

m1 The first matrix of coordinates.
 m2 The second matrix of coordinates.

Details

If one wishes to align two (or more shapes) Procrustes surimposition may provide a better solution.

Value

Returns a vector of euclidean distances between pairwise coordinates in the two matrices.

See Also

[ed](#), [edm_nearest](#), [dist](#).

Examples

```
x <- matrix(1:10, nc=2)
edm(x, x)
edm(x, x+1)
```

edm_nearest

Calculates the shortest euclidean distance found for every point of one matrix among those of a second.

Description

edm_nearest calculates the shortest euclidean distance found for every point of one matrix among those of a second. In other words, if m_1 , m_2 have n rows, the result will be the shortest distance for the first point of m_1 to any point of m_2 and so on, n times. This function is used internally but may be of interest for other analyses.

Usage

```
edm_nearest(m1, m2, full = FALSE)
```

Arguments

m1	The first list or matrix of coordinates.
m2	The second list or matrix of coordinates.
full	logical. Whether to return a condensed version of the results.

Details

So far this function is quite time consuming since it performs $n \times n$ euclidean distance computation. If one wishes to align two (or more shapes) Procrustes surimposition may provide a better solution.

Value

If `full` is `TRUE`, returns a list with two components: `d` which is for every point of `m1` the shortest distance found between it and any point in `m2`, and `pos` the (`m2`) row indices of these points. Otherwise returns `d` as a numeric vector of the shortest distances.

See Also

[ed](#), [edm](#), [dist](#).

Examples

```
x <- matrix(1:10, nc=2)
edm_nearest(x, x+rnorm(10))
edm_nearest(x, x+rnorm(10), full=TRUE)
```

 efourier

Elliptical Fourier transform (and its normalization)

Description

efourier computes Elliptical Fourier Analysis (or Transforms or EFT) from a matrix (or a list) of (`x`; `y`) coordinates. `efourier_norm` normalizes Fourier coefficients. Read Details carefully.

Usage

```
efourier(x, ...)

## Default S3 method:
efourier(x, nb.h, smooth.it = 0, ...)

## S3 method for class 'Out'
efourier(x, nb.h, smooth.it = 0, norm = TRUE, start = FALSE, ...)

## S3 method for class 'list'
efourier(x, ...)

efourier_norm(ef, start = FALSE)
```

Arguments

<code>x</code>	A list or a matrix of coordinates or a <code>Out</code> object
<code>...</code>	useless here
<code>nb.h</code>	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on <code>Out</code> objects, both with messages.
<code>smooth.it</code>	integer. The number of smoothing iterations to perform.
<code>norm</code>	whether to normalize the coefficients using efourier_norm

start	logical. For <code>efourier</code> whether to consider the first point as homologous; for <code>efourier_norm</code> whether to conserve the position of the first point of the outline.
ef	list with <code>a_n</code> , <code>b_n</code> , <code>c_n</code> and <code>d_n</code> Fourier coefficients, typically returned by <code>efourier</code>

Details

For the maths behind see the paper in JSS.

Normalization of coefficients has long been a matter of trouble, and not only for newcomers. There are two ways of normalizing outlines: the first, and by far the most used, is to use a "numerical" alignment, directly on the matrix of coefficients. The coefficients of the first harmonic are consumed by this process but harmonics of higher rank are normalized in terms of size and rotation. This is sometimes referred as using the "first ellipse", as the harmonics define an ellipse in the plane, and the first one is the mother of all ellipses, on which all others "roll" along. This approach is really convenient as it is done easily by most software (if not the only option) and by Momocs too. It is the default option of `efourier`.

But here is the pitfall: if your shapes are prone to bad alignments among all the first ellipses, this will result in poorly (or even not at all) "homologous" coefficients. The shapes particularly prone to this are either (at least roughly) circular and/or with a strong bilateral symmetry. You can try to use `stack` on the `Coe` object returned by `efourier`. Also, and perhaps more explicitly, morphospace usually show a mirroring symmetry, typically visible when calculated in some couple of components (usually the first two).

If you see these upside-down (or 180 degrees rotated) shapes on the morphospace, you should seriously consider aligning your shapes **before** the `efourier` step, and performing the latter with `norm = FALSE`.

Such a pitfall explains the (quite annoying) message when passing `efourier` with just the `Out`.

You have several options to align your shapes, using control points (or landmarks), by far the most time consuming (and less reproducible) but possibly the best one too when alignment is too tricky to automate. You can also try Procrustes alignment (see `fgProcrustes`) through their calliper length (see `coo_aligncalliper`), etc. You should also make the first point homologous either with `coo_slide` or `coo_slidedirection` to minimize any subsequent problems.

I will dedicate (some day) a vignette or a paper to this problem.

Value

For `efourier`, a list with components: `an`, `bn`, `cn`, `dn` harmonic coefficients, plus `ao` and `co`. The latter should have been named `a0` and `c0` in Claude (2008) but I (intentionnaly) propagated the error.

For `efourier_norm`, a list with components: `A`, `B`, `C`, `D` for harmonic coefficients, plus `size`, the magnitude of the semi-major axis of the first fitting ellipse, `theta` angle, in radians, between the starting and the semi-major axis of the first fitting ellipse, `psi` orientation of the first fitting ellipse, `ao` and `do`, same as above, and `lnef` that is the concatenation of coefficients.

Note

Directly borrowed for Claude (2008).

Silent message and progress bars (if any) with options(`"verbose"=FALSE`).

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp. Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

See Also

Other efourier: [efourier_i\(\)](#), [efourier_shape\(\)](#)

Examples

```
# single shape
coo <- bot[1]
coo_plot(coo)
ef <- efourier(coo, 12)
# same but silent
efourier(coo, 12, norm=TRUE)
# inverse EFT
efi <- efourier_i(ef)
coo_draw(efi, border='red', col=NA)

# on Out
bot %>% slice(1:5) %>% efourier
```

efourier_i

Inverse elliptical Fourier transform

Description

`efourier_i` uses the inverse elliptical Fourier transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [efourier](#).

Usage

```
efourier_i(ef, nb.h, nb.pts = 120)
```

Arguments

<code>ef</code>	list. A list containing a_n , b_n , c_n and d_n Fourier coefficients, such as returned by <code>efourier</code> .
<code>nb.h</code>	integer. The number of harmonics to use. If not specified, <code>length(ef\$an)</code> is used.
<code>nb.pts</code>	integer. The number of points to calculate.

Details

See [efourier](#) for the mathematical background.

Value

A matrix of (x; y) coordinates.

Note

Directly borrowed for Claude (2008), and also called iefourier there.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp. Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

See Also

Other efourier: [efourier_shape\(\)](#), [efourier\(\)](#)

Examples

```
coo <- bot[1]
coo_plot(coo)
ef <- efourier(coo, 12)
ef
efi <- efourier_i(ef)
coo_draw(efi, border='red', col=NA)
```

efourier_shape	<i>Calculates and draw 'efourier' shapes.</i>
----------------	---

Description

efourier_shape calculates a 'Fourier elliptical shape' given Fourier coefficients (see Details) or can generate some 'efourier' shapes. Mainly intended to generate shapes and/or to understand how efourier works.

Usage

```
efourier_shape(an, bn, cn, dn, nb.h, nb.pts = 60, alpha = 2, plot = TRUE)
```

Arguments

an	numeric. The a_n Fourier coefficients on which to calculate a shape.
bn	numeric. The b_n Fourier coefficients on which to calculate a shape.
cn	numeric. The c_n Fourier coefficients on which to calculate a shape.
dn	numeric. The d_n Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.

alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see Details).
plot	logical. Whether to plot or not the shape.

Details

efourier_shape can be used by specifying nb.h and alpha. The coefficients are then sampled in an uniform distribution $(-\pi; \pi)$ and this amplitude is then divided by $harmonicrank^{\alpha}$. If alpha is lower than 1, consecutive coefficients will thus increase. See [efourier](#) for the mathematical background.

Value

A list with components:

- x vector of x-coordinates
- y vector of y-coordinates.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

See Also

Other efourier: [efourier_i\(\)](#), [efourier\(\)](#)

Examples

```
ef <- efourier(bot[1], 24)
efourier_shape(ef$an, ef$bn, ef$cn, ef$dn) # equivalent to efourier_i(ef)
efourier_shape() # is autonomous

panel(Out(a2l(replicate(100,
efourier_shape(nb.h=6, alpha=2.5, plot=FALSE)))))) # Bubble family
```

export

Exports Coe objects and shapes

Description

Writes a .txt or .xls or whatever readable from a single shape, a [Coe](#), or a [PCA](#) object, along with individual names and \$fac.

Usage

```
export(x, file, sep, dec)
```

Arguments

x	a Coe or PCA object
file	the filenames data.txt by default
sep	the field separator string to feed write.table . (default to tab) tab by default
dec	the string to feed write.table (default ".") by default.

Note

This is a simple wrapper around [write.table](#).

Default parameters will write a .txt file, readable by foreign programs. With default parameters, numbers will use dots as decimal points, which is considered as a character chain in Excel in many countries (locale versions). This can be solved by using `dec=','` as in the examples below.

If you are looking for your file, and did not specified file, `getwd()` will help.

I have to mention that everytime you use this function, and cowardly run from R to Excel and do 'statistics' there, an innocent and adorable kitten is probably murdered somewhere. Use R!

See Also

Other bridges functions: [as_df\(\)](#), [bridges](#), [complex](#)

Examples

```
## Not run:
# Will write files on your machine!
bf <- efourier(bot, 6)
# Export Coe (here Fourier coefficients)
export(bf) # data.txt which can be opened by every software including MS Excel

# If you come from a country that uses comma as decimal separator (not recommended, but...)
export(bf, dec=',')
export(bf, file='data.xls', dec=',')

# Export PCA scores
bf %>% PCA %>% export()

# for shapes (matrices)
export(bot[1], file='bot1.txt')

# remove these files from your machine
file.remove("coefficients.txt", "data.xls", "scores.txt")

## End(Not run)
```

`fac_dispatcher`*Brew and serve fac from Momocs object*

Description

Ease various specifications for fac specification when passed to Momocs objects. Intensively used (internally).

Usage

```
fac_dispatcher(x, fac)
```

Arguments

<code>x</code>	a Momocs object (any <code>Coo</code> , <code>Coe</code> , <code>PCA</code> , etc.)
<code>fac</code>	a specification to extract from <code>fac</code>

Details

`fac` can be:

- a factor, passed on the fly
- a column id from `$fac`
- a column name from `fac`; if not found, return `NULL` with a message
- a formula in the form: `~column_name` (from `$fac`, no quotes). It expresses more in a concise way. Also allows interacting on the fly. See examples.
- a `NULL` returns a `NULL`, with a message

Value

a prepared factor (or a numeric). See examples

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
bot <- mutate(bot, s=rnorm(40), fake=factor(rep(letters[1:4], 10)))

# factor, on the fly
fac_dispatcher(bot, factor(rep(letters[1:4], 10)))

# column id
```

```

fac_dispatcher(bot, 1)

# column name
fac_dispatcher(bot, "type")
# same, numeric case
fac_dispatcher(bot, "s")

# formula interface
fac_dispatcher(bot, ~type)

# formula interface + interaction on the fly
fac_dispatcher(bot, ~type+fake)

# when passing NULL or non existing column
fac_dispatcher(42, NULL)
fac_dispatcher(bot, "loser")

```

fgProcrustes

Full Generalized Procrustes alignment between shapes

Description

Directly borrowed from Claude (2008), called there the fgpa2 function.

Usage

```
fgProcrustes(x, tol, coo)
```

Arguments

x	an array, a list of configurations, or an Out , Opn or Ldk object
tol	numeric when to stop iterations
coo	logical, when working on Out or Opn , whether to use \$coo rather than \$ldk

Details

If performed on an [Out](#) or an [Opn](#) object, will try to use the \$ldk slot, if landmarks have been previously defined, then (with a message) on the \$coo slot, but in that case, all shapes must have the same number of coordinates ([coo_sample](#) may help).

Value

a list with components:

- rotated array of superimposed configurations
- iterationnumber number of iterations
- Q convergence criterion
- Qi full list of Q

- Qd difference between successive Q
- `interproc.dist` minimal sum of squared norms of pairwise differences between all shapes in the superimposed sample
- `mshape` mean shape configuration
- `cent.size` vector of centroid sizes.

or an [Out](#), [Opn](#) or an [Ldk](#) object.

Note

Slightly less optimized than `procGPA` in the `shapes` package (~20% on my machine). Will be optimized when performance will be the last thing to improve! Silent message and progress bars (if any) with `options("verbose"=FALSE)`.

References

Claude, J. (2008). *Morphometrics with R. Analysis* (p. 316). Springer.

See Also

Other procrustes functions: [fProcrustes\(\)](#), [fgsProcrustes\(\)](#), [pProcrustes\(\)](#)

Examples

```
## Not run:
# on Ldk
stack(wings)
fgProcrustes(wings, tol=0.1) %>% stack()

# on Out
stack(hearts)
fgProcrustes(hearts) %>% stack()

## End(Not run)
```

fgsProcrustes	<i>Full Generalized Procrustes alignment between shapes with sliding landmarks</i>
---------------	--

Description

Directly wrapped around `geomorph:::gpagen`.

Usage

```
fgsProcrustes(x)
```

Arguments

x Ldk object with some \$slidings

Note

Landmarks methods are the less tested in Momocs. Keep in mind that some features are still experimental and that your help is welcome.

Source

See ?gpagen in geomorph package

See Also

Other procrustes functions: [fProcrustes\(\)](#), [fgProcrustes\(\)](#), [pProcrustes\(\)](#)

Examples

```
## Not run:
chaffp <- fgsProcrustes(chaff)
chaffp
chaffp %>% PCA() %>% plot("taxa")

## End(Not run)
```

filter

Subset based on conditions

Description

Return shapes with matching conditions, from the \$fac. See examples and ?dplyr::filter.

Usage

```
filter(.data, ...)
```

Arguments

.data a Coo, Coe, PCA object
... logical conditions

Details

dplyr verbs are maintained. You should probably not filter on PCA objects. The latter are calculated using all individuals and filtering may lead to false conclusions. If you want to highlight some individuals, see examples in [plot_PCA](#).

Value

a Momocs object of the same class.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea
# we retain on dorsal views
filter(olea, view=="VD")
# only dorsal views and Aglan+PicMa varieties
filter(olea, view=="VD", var %in% c("Aglan", "PicMa"))
# we create an id column and retain the 120 first shapes
olea %>% mutate(id=1:length(olea)) %>% filter(id > 120)
```

 flip_PCaxes

Flips PCA axes

Description

Simply multiply by -1, corresponding scores and rotation vectors for PCA objects. PC orientation being arbitrary, this may help to have a better display.

Usage

```
flip_PCaxes(x, axs)
```

Arguments

x	a PCA object
axs	numeric which PC(s) to flip

Examples

```
bp <- bot %>% efourier(6) %>% PCA
bp %>% plot
bp %>% flip_PCaxes(1) %>% plot()
```

flower

Data: Measurement of iris flowers

Description

Data: Measurement of iris flowers

Format

A TraCoe object with 150 measurements of 4 variables (petal + sepal) x (length x width) on 3 species of iris. This dataset is the classical [iris](#) formatted for Momocs.

Source

see linkiris

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

fProcrustes

Full Procrustes alignment between two shapes

Description

Directly borrowed from Claude (2008), called there the fPsup function.

Usage

```
fProcrustes(coo1, coo2)
```

Arguments

coo1 configuration matrix to be superimposed onto the centered preshape of coo2.
coo2 reference configuration matrix.

Value

a list with components:

- coo1 superimposed centered preshape of coo1 onto the centered preshape of coo2
- coo2 centered preshape of coo2
- rotation rotation matrix
- scale scale parameter
- DF full Procrustes distance between coo1 and coo2.

References

Claude, J. (2008). Morphometrics with R. Analysis (p. 316). Springer.

See Also

Other procrustes functions: [fgProcrustes\(\)](#), [fgsProcrustes\(\)](#), [pProcrustes\(\)](#)

get_chull_area	<i>Calculates convex hull area/volume of PCA scores</i>
----------------	---

Description

May be useful to compare shape diversity. Expressed in PCA units that should only be compared within the same PCA.

Usage

```
get_chull_area(x, fac, xax = 1, yax = 2)
```

```
get_chull_volume(x, fac, xax = 1, yax = 2, zax = 3)
```

Arguments

x	a PCA object
fac	(optionnal) column name or ID from the \$fac slot.
xax	the first PC axis to use (1 by default)
yax	the second PC axis (2 by default)
zax	the third PC axis (3 by default only for volume)

Details

get_chull_area is calculated using [coo_chull](#) followed by [coo_area](#); get_chull_volume is calculated using `geometry::convexhulln`

Value

If fac is not provided global area/volume is returned; otherwise a named list for every level of fac

Examples

```
bp <- PCA(efourier(bot, 12))
get_chull_area(bp)
get_chull_area(bp, 1)

get_chull_volume(bp)
get_chull_volume(bp, 1)
```

get_ldk	<i>Retrieves landmarks coordinates</i>
---------	--

Description

See Details for the different behaviors implemented.

Usage

```
get_ldk(Coo)
```

Arguments

Coo an Out, Opn or Ldk object

Details

Different behaviors depending on the class of the object:

- **Ldk**: retrieves landmarks.
- **Ldk** with slidings defined: retrieves only the fixed landmarks, not the sliding ones. See also [get_slidings](#).
- **Out** landmarks from \$ldk and \$coo, if any.
- **Opn**: same as above.

Value

a list of shapes

See Also

Other ldk/slidings methods: [add_ldk\(\)](#), [def_ldk\(\)](#), [def_slidings\(\)](#), [get_slidings\(\)](#), [rearrange_ldk\(\)](#), [slidings_scheme\(\)](#)

Examples

```
# Out example
ldk.h <- get_ldk(hearts)
stack(Ldk(ldk.h))

# on Ldk (no slidings)
get_ldk(wings) # equivalent to wings$coo

# on Ldk (slidings)
get_ldk(chaff)
get_ldk(chaff) %>% Ldk %>% fgProcrustes(tol=0.1) %>% stack
```

 get_pairs

Get paired individual on a Coe, PCA or LDA objects

Description

If you have paired individuals, i.e. before and after a treatment or for repeated measures, and if you have coded it into \$fac, this methods allows you to retrieve the corresponding PC/LD scores, or coefficients for [Coe](#) objects.

Usage

```
get_pairs(x, fac, range)
```

Arguments

x	any Coe , PCA or LDA object.
fac	factor or column name or id corresponding to the pairing factor.
range	numeric the range of coefficients for Coe, or PC (LD) axes on which to return scores.

Value

a list with components x1 all coefficients/scores corresponding to the first level of the fac provided; x2 same thing for the second level; fac the corresponding fac.

Examples

```
bot2 <- bot1 <- coo_scale(coo_center(coo_sample(bot, 60)))
bot1$fac$session <- factor(rep("session1", 40))
# we simulate an measurement error
bot2 <- coo_jitter(bot1, amount=0.01)
bot2$fac$session <- factor(rep("session2", 40))
botc <- combine(bot1, bot2)
botcf <- efourier(botc, 12)

# we gonna plot the PCA with the two measurement sessions and the two types
botcp <- PCA(botcf)
plot(botcp, "type", col=col_summer(2), pch=rep(c(1, 20), each=40), eigen=FALSE)
bot.pairs <- get_pairs(botcp, fac = "session", range=1:2)
segments(bot.pairs$session1[, 1], bot.pairs$session1[, 2],
         bot.pairs$session2[, 1], bot.pairs$session2[, 2],
         col=col_summer(2)[bot.pairs$fac$type])
```

get_slidings	<i>Extracts sliding landmarks coordinates</i>
--------------	---

Description

From an [Ldk](#) object.

Usage

```
get_slidings(Coo, partition)
```

Arguments

Coo	an Ldk object
partition	numeric which one(s) to get.

Value

a list of list(s) of coordinates.

See Also

Other ldk/sliding methods: [add_ldk\(\)](#), [def_ldk\(\)](#), [def_slidings\(\)](#), [get_ldk\(\)](#), [rearrange_ldk\(\)](#), [slidings_scheme\(\)](#)

Examples

```
# for each example below a list with partition containign shapes is returned
# extracts the first partition
get_slidings(chaff, 1) %>% names()
# the first and the fourth
get_slidings(chaff, c(1, 4)) %>% names()
# all of them
get_slidings(chaff) %>% names
# here we want to see it
get_slidings(chaff, 1)[[1]] %>% Ldk %>% stack
```

harm_pow	<i>Calculates harmonic power given a list from e/t/rfourier</i>
----------	---

Description

Given a list with an, bn (and eventually cn and dn), returns the harmonic power.

Usage

```
harm_pow(xf)
```

Arguments

`xf` A list with `an`, `bn` (and `cn`, `dn`) components, typically from a `e/r/tfourier` passed on `coo_`

Value

Returns a vector of harmonic power

Examples

```
ef <- efourier(bot[1], 24)
rf <- rfourier(bot[1], 24)
harm_pow(ef)
harm_pow(rf)

plot(cumsum(harm_pow(ef)[-1]), type='o',
     main='Cumulated harmonic power without the first harmonic',
     ylab='Cumulated harmonic power', xlab='Harmonic rank')
```

hcontrib

Harmonic contribution to shape

Description

Calculates contribution of harmonics to shape. The amplitude of every coefficients of a given harmonic is multiplied by the coefficients provided and the resulting shapes are reconstructed and plotted. Naturally, only works on Fourier-based methods.

Usage

```
hcontrib(Coe, ...)

## S3 method for class 'OutCoe'
hcontrib(
  Coe,
  id,
  harm.r,
  amp.r = c(0, 0.5, 1, 2, 5, 10),
  main = "Harmonic contribution to shape",
  xlab = "Harmonic rank",
  ylab = "Amplification factor",
  ...
)
```

Arguments

<code>Coe</code>	a Coe object (either <code>OutCoe</code> or (soon) <code>OpnCoe</code>)
<code>...</code>	additional parameter to pass to <code>coo_draw</code>
<code>id</code>	the id of a particular shape, otherwise working on the <code>meanshape</code>
<code>harm.r</code>	range of harmonics on which to explore contributions
<code>amp.r</code>	a vector of numeric for multiplying coefficients
<code>main</code>	a title for the plot
<code>xlab</code>	a title for the x-axis
<code>ylab</code>	a title for the y-axis

See Also

Other `Coe_graphics`: [boxplot.OutCoe\(\)](#)

Examples

```
data(bot)
bot.f <- efourier(bot, 12)
hcontrib(bot.f)
hcontrib(bot.f, harm.r=3:10, amp.r=1:8, col="grey20",
  main="A huge panel")
```

hearts

Data: Outline coordinates of hand-drawn hearts

Description

Data: Outline coordinates of hand-drawn hearts

Format

A [Out](#) object with the outline coordinates of 240 hand-drawn hearts by 8 different persons, with 4 landmarks.

Source

We thank the fellows of the Ecology Department of the French Institute of Pondicherry that drawn the hearts, that then have been smoothed, scaled, centered, and downsampled to 80 coordinates per outline.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

img_plot	<i>Plots a .jpg image</i>
----------	---------------------------

Description

A very simple image plotter. If provided with a path, reads the .jpg and plots it. If not provided with an imagematrix, will ask you to choose interactively a .jpeg image.

Usage

```
img_plot(img)
```

```
img_plot0(img)
```

Arguments

img a matrix of an image, such as those obtained with [readJPEG](#).

Details

img_plot is used in import functions such as [import_jpg1](#); img_plot0 does the same job but preserves the par and plots axes.

import_Conte	<i>Extract outlines coordinates from an image silhouette</i>
--------------	--

Description

Provided with an image 'mask' (i.e. black pixels on a white background), and a point form where to start the algorithm, returns the (x; y) coordinates of its outline.

Usage

```
import_Conte(img, x)
```

Arguments

img a matrix of a binary image mask.

x numeric the (x; y) coordinates of a starting point within the shape.

Details

Used internally by [import_jpg1](#) but may be useful for other purposes.

Value

a matrix the (x; y) coordinates of the outline points.

Note

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

If you have an image with more than a single shape, then you may want to try `imager::highlight` function. Momocs may use this at some point.

References

- The original algorithm is due to: Pavlidis, T. (1982). *Algorithms for graphics and image processing*. Computer science press.
- is detailed in: Rohlf, F. J. (1990). An overview of image processing and analysis techniques for morphometrics. In *Proceedings of the Michigan Morphometrics Workshop*. Special Publication No. 2 (pp. 47-60). University of Michigan Museum of Zoology: Ann Arbor.
- and translated in R by: Claude, J. (2008). *Morphometrics with R*. (p. 316). Springer.

See Also

Other import functions: [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

import_jpg

Extract outline coordinates from multiple .jpg files

Description

This function is used to import outline coordinates and is built around [import_jpg1](#).

Usage

```
import_jpg(
  jpg.paths = .lf.auto(),
  auto.notcentered = TRUE,
  fun.notcentered = NULL,
  threshold = 0.5
)
```

Arguments

`jpg.paths` a vector of paths corresponding to the .jpg files to import. If not provided (or NULL), switches to the automatic version. See Details below.

`auto.notcentered` logical if TRUE random locations will be used until. one of them is (assumed) to be within the shape (because of a black pixel); if FALSE a [locator](#) will be called, and you will have to click on a point within the shape.

`fun.notcentered` NULL by default. Is your shapes are not centered and if a random pick of a black pixel is not satisfactory. See [import_jpg1](#) help and examples.

`threshold` the threshold value use to binarize the images. Above, pixels are turned to 1, below to 0.

Details

see [import_jpg1](#) for important informations about how the outlines are extracted, and [import_Conte](#) for the algorithm itself.

If `jpg.paths` is not provided (or NULL), you will have to select any `.jpg` file in the folder that contains all your files. All the outlines should be imported then.

Value

a list of matrices of (x; y) coordinates that can be passed to [Out](#)

Note

Note this function will be deprecated from Momocs when Momacs and Momiit will be fully operational.

Silent message and progress bars (if any) with `options("verbose"=FALSE)`.

See Also

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

Examples

```
## Not run:

lf <- list.files('/foo/jpegs', full.names=TRUE)
coo <- import_jpg(lf)
Out(coo)

coo <- import_jpg()

## End(Not run)
```

import_jpg1

Extract outline coordinates from a single .jpg file

Description

Used to import outline coordinates from `.jpg` files. This function is used for single images and is wrapped by [import_jpg](#). It relies itself on [import_Conte](#)

Usage

```
import_jpg1(
    jpg.path,
    auto.notcentered = TRUE,
    fun.notcentered = NULL,
    threshold = 0.5,
    ...
)
```

Arguments

jpg.path	vector of paths corresponding to the .jpg files to import, such as those obtained with list.files .
auto.notcentered	logical if TRUE random locations will be used until one of them is (assumed) to be within the shape (because it corresponds to a black pixel) and only if the middle point is not black; if FALSE a locator will be called, and you will have to click on a point within the shape.
fun.notcentered	NULL by default but can accept a function that, when passed with an image-matrix and returns a numeric of length two that corresponds to a starting point on the imagematrix for the Conte algorithm. A while instruction wraps it, so the function may be wrong in proposing this starting position. See the examples below for a quick example.
threshold	the threshold value use to binarize the images. Above, pixels are turned to 1, below to 0.
...	arguments to be passed to read.table , eg. 'skip', 'dec', etc.

Details

jpegs can be provided either as RVB or as 8-bit greylevels or monochrome. The function binarizes pixels values using the 'threshold' argument. It will try to start to apply the [import_Conte](#) algorithm from the center of the image and 'looking' downwards for the first black/white 'frontier' in the pixels. This point will be the first of the outlines. The latter may be useful if you align manually the images and if you want to retain this information in the consequent morphometric analyses.

If the point at the center of the image is not within the shape, i.e. is 'white' you have two choices defined by the 'auto.notcentered' argument. If it's TRUE, some random starting points will be tried until on of them is 'black' and within the shape; if FALSE you will be asked to click on a point within the shape.

If some pixels on the borders are not white, this functions adds a 2-pixel border of white pixels; otherwise [import_Conte](#) would fail and return an error.

Finally, remember that if the images are not in your working directory, [list.files](#) must be called with the argument `full.names=TRUE`!

Note that the use of the `fun.notcentered` argument will probably leads to serious headaches and will probably imply the dissection of these functions: [import_Conte](#), [img_plot](#) and `import_jpg` itself

Value

a matrix of (x; y) coordinates that can be passed to Out

Note

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

See Also

[import_jpg](#), [import_Conte](#), [import_txt](#), [lf_structure](#). See also Momocs' vignettes for data import.

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

`import_StereoMorph_curve1`

Import files creates by StereoMorph into Momocs

Description

Helps to read .txt files created by StereoMorph into (x; y) coordinates or Momocs objects. Can be applied to 'curves' or 'ldk' text files.

Usage

```
import_StereoMorph_curve1(path)
```

```
import_StereoMorph_curve(path, names)
```

```
import_StereoMorph_ldk1(path)
```

```
import_StereoMorph_ldk(path, names)
```

Arguments

path	toward a single file or a folder containing .txt files produced by StereoMorph
names	to feed lf_structure

Details

*1 functions import a single .txt file. Their counterpart (no '1') work when path indicates the folder, i.e. 'curves' or 'ldk'. They then return a list of [Open](#) or [Ldk](#) objects, respectively. Please do not hesitate to contact me should you have a particular case or need something.

Note

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

See Also

Other import functions: [import_Conte\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

Other import functions: [import_Conte\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

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Other import functions: [import_Conte\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

import_tps

Import a tps file

Description

And returns a list of coordinates, curves, scale

Usage

```
import_tps(tps.path, curves = TRUE)
```

```
tps2coo(tps, curves = TRUE)
```

Arguments

tps.path	lines, typically from readLines , describing a single shape in tps-like format. You will need to manually build your Coo object from it: eg <code>Out(coo=your_list\$coo)</code> .
curves	logical whether to read curves, if any
tps	lines for a single tps file tps2coo is used in import_tps and may be useful for data import. When provided with lines (eg after readLines) from a tps-like description (with "LM", "CURVES", etc.) returns a list of coordinates, curves, etc.

Value

a list with components: coo a matrix of coordinates; cur a list of matrices; scale the scale as a numeric.

Note

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

See Also

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_txt\(\)](#), [pix2chc\(\)](#)

import_txt

Import coordinates from a .txt file

Description

A wrapper around [read.table](#) that can be used to import outline/landmark coordinates.

Usage

```
import_txt(txt.paths = .lf.auto(), ...)
```

Arguments

`txt.paths` a vector of paths corresponding to the .txt files to import. If not provided (or NULL), switches to the automatic version, just as in [import_jpg](#). See Details there.

`...` arguments to be passed to [read.table](#), eg. 'skip', 'dec', etc.

Details

Columns are not named in the .txt files. You can tune this using the `...` argument. Define the [read.table](#) arguments that allow to import a single file, and then pass them to this function, ie if your .txt file has a header (eg ('x', 'y')), do not forget `header=TRUE`.

Value

a list of `matrix(ces)` of (x; y) coordinates that can be passed to [Out](#), [Opn](#) and [Ldk](#).

Note

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

Silent message and progress bars (if any) with options(`"verbose"`=FALSE).

See Also

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [pix2chc\(\)](#)

inspect	<i>Graphical inspection of shapes</i>
---------	---------------------------------------

Description

Allows to plot shapes, individually, for [Coo](#) ([Out](#), [Opn](#) or [Ldk](#)) objects.

Usage

```
inspect(x, id, ...)
```

Arguments

x	the Coo object
id	the id of the shape to plot, if not provided a random shape is plotted. If passed with 'all' all shapes are plotted, one by one.
...	further arguments to be passed to coo_plot

See Also

Other [Coo_graphics](#): [panel\(\)](#), [stack\(\)](#)

Examples

```
## Not run:  
inspect(bot, 5)  
inspect(bot)  
inspect(bot, 5, pch=3, points=TRUE) # an example of '...' use  
  
## End(Not run)
```

is	<i>Class and component testers</i>
----	------------------------------------

Description

Class testers test if any of the classes of an object *is* of a given class. For instance [is_PCA](#) on a [PCA](#) object (of classes [PCA](#) and [prcomp](#)) will return TRUE. Component testers check if *there_is* a particular component (eg `$fac`, etc.) in an object.

Usage`is_Coo(x)``is_PCA(x)``is_LDA(x)``is_Out(x)``is_Opn(x)``is_Ldk(x)``is_Coe(x)``is_OutCoe(x)``is_OpnCoe(x)``is_LdkCoe(x)``is_TraCoe(x)``is_shp(x)``is_fac(x)``is_ldk(x)``is_slidings(x)``is_links(x)`**Arguments**

`x` the object to test

Value

logical

Examples

```
is_Coo(bot)
is_Out(bot)
is_Ldk(bot)
is_ldk(hearts) # mind the capitals!
```

is_equallyspacedradii *Tests if coordinates likely have equally spaced radii*

Description

Returns TRUE/FALSE whether the sd of angles between all successive radii is below/above thesh

Usage

```
is_equallyspacedradii(coo, thres)
```

Arguments

coo matrix of (x; y) coordinates or any [Coo](#) object.
 thres numeric a threshold (arbitrarily $\pi/90$, eg 2 degrees, by default)

Value

a single or a vector of logical. If NA are returned, some coordinates are likely identical, at least for x or y.

See Also

Other `coo_` utilities: [coo_aligncalliper\(\)](#), [coo_alignminradius\(\)](#), [coo_alignxax\(\)](#), [coo_align\(\)](#), [coo_baseline\(\)](#), [coo_bookstein\(\)](#), [coo_boundingbox\(\)](#), [coo_calliper\(\)](#), [coo_centdist\(\)](#), [coo_center\(\)](#), [coo_centpos\(\)](#), [coo_close\(\)](#), [coo_down\(\)](#), [coo_dxy\(\)](#), [coo_extract\(\)](#), [coo_flipx\(\)](#), [coo_force2close\(\)](#), [coo_interpolate\(\)](#), [coo_is_closed\(\)](#), [coo_jitter\(\)](#), [coo_left\(\)](#), [coo_likely_clockwise\(\)](#), [coo_nb\(\)](#), [coo_perim\(\)](#), [coo_range\(\)](#), [coo_rev\(\)](#), [coo_right\(\)](#), [coo_rotatecenter\(\)](#), [coo_rotate\(\)](#), [coo_sample_prop\(\)](#), [coo_samlerr\(\)](#), [coo_sample\(\)](#), [coo_scale\(\)](#), [coo_shearx\(\)](#), [coo_slice\(\)](#), [coo_slidedirection\(\)](#), [coo_slidegap\(\)](#), [coo_slide\(\)](#), [coo_smoothcurve\(\)](#), [coo_smooth\(\)](#), [coo_template\(\)](#), [coo_trans\(\)](#), [coo_trimbottom\(\)](#), [coo_trimtop\(\)](#), [coo_trim\(\)](#), [coo_untiltx\(\)](#), [coo_up\(\)](#)

Examples

```
bot[1] %>% is_equallyspacedradii
bot[1] %>% coo_samlerr(36) %>% is_equallyspacedradii
# higher tolerance but wrong
bot[1] %>% coo_samlerr(36) %>% is_equallyspacedradii(thres=5*2*pi/360)
# coo_interpolate is a better option
bot[1] %>% coo_interpolate(1200) %>% coo_samlerr(36) %>% is_equallyspacedradii
# Coo method
bot %>% coo_interpolate(360) %>% coo_samlerr(36) %>% is_equallyspacedradii
```

KMEANS

KMEANS on PCA objects

Description

A very basic implementation of k-means. Beware that morphospaces are calculated so far for the 1st and 2nd component.

Usage

```
KMEANS(x, ...)  
  
## S3 method for class 'PCA'  
KMEANS(x, centers, nax = 1:2, pch = 20, cex = 0.5, ...)
```

Arguments

x	PCA object
...	additional arguments to be passed to kmeans
centers	numeric number of centers
nax	numeric the range of PC components to use (1:2 by default)
pch	to draw the points
cex	to draw the points

Value

the same thing as [kmeans](#)

See Also

Other multivariate: [CLUST\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
data(bot)  
bp <- PCA(efourier(bot, 10))  
KMEANS(bp, 2)
```

 KMEDOIDS

KMEDOIDS

Description

A basic implementation of kmedoids on top of [cluster::pam](#). Beware that morphospaces are calculated so far for the 1st and 2nd component.

Usage

```
KMEDOIDS(x, k, metric = "euclidean", ...)

## Default S3 method:
KMEDOIDS(x, k, metric = "euclidean", ...)

## S3 method for class 'Coe'
KMEDOIDS(x, k, metric = "euclidean", ...)

## S3 method for class 'PCA'
KMEDOIDS(x, k, metric = "euclidean", retain, ...)
```

Arguments

x	a Coe or PCA object
k	numeric number of centers
metric	one of euclidean (default) or manhattan, to feed cluster::pam
...	additional arguments to feed cluster::pam
retain	when passing a PCA how many PCs to retain, or a proportion of total variance, see LDA

Value

see [cluster::pam](#). Other components are returned (fac, etc.)

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
data(bot)
bp <- PCA(efourier(bot, 10))
KMEANS(bp, 2)

set.seed(123) # for reproducibility on a dummy matrix
matrix(rnorm(100, 10, 10)) %>%
```

```

KMEDOIDS(5)

# On a Coe
bot_f <- bot %>% efourier()

bot_k <- bot_f %>% KMEDOIDS(2)
# confusion matrix
table(bot_k$fac$type, bot_k$clustering)

# on a PCA
bot_k2 <- bot_f %>% PCA() %>% KMEDOIDS(12, retain=0.9)

# confusion matrix
with(bot_k, table(fac$type, clustering))
# silhouette plot
bot_k %>% plot_silhouette()

# average width as a function of k
k_range <- 2:12
widths <- sapply(k_range, function(k) KMEDOIDS(bot_f, k=k)$silinfo$avg.width)
plot(k_range, widths, type="b")

```

layers

grindr layers for multivariate plots

Description

Useful layers for building custom mutivariate plots using the cheapbabi approach. See examples.

Usage

```

layer_frame(x, center_origin = TRUE, zoom = 0.9)

layer_axes(x, col = "#999999", lwd = 1/2, ...)

layer_ticks(x, col = "#333333", cex = 3/4, lwd = 3/4, ...)

layer_grid(x, col = "#999999", lty = 3, grid = 3, ...)

layer_box(x, border = "#e5e5e5", ...)

layer_fullframe(x, ...)

layer_points(x, pch = 20, cex = 4/log1p(nrow(x$xy)), transp = 0, ...)

layer_ellipses(x, conf = 0.5, lwd = 1, alpha = 0, ...)

layer_ellipsesfilled(x, conf = 0.5, lwd = 1, alpha = 0, ...)

```

```
layer_ellipsesaxes(x, conf = 0.5, lwd = 1, alpha = 0, ...)  
layer_chull(x, ...)  
layer_chullfilled(x, alpha = 0.8, ...)  
layer_stars(x, alpha = 0.5, ...)  
layer_delaunay(x, ...)  
layer_density(  
  x,  
  levels_density = 20,  
  levels_contour = 4,  
  alpha = 1/3,  
  n = 200,  
  density = TRUE,  
  contour = TRUE  
)  
layer_labelpoints(  
  x,  
  col = par("fg"),  
  cex = 2/3,  
  font = 1,  
  abbreviate = FALSE,  
  ...  
)  
layer_labelgroups(  
  x,  
  col = par("fg"),  
  cex = 3/4,  
  font = 2,  
  rect = TRUE,  
  alpha = 1/4,  
  abbreviate = FALSE,  
  ...  
)  
layer_rug(x, size = 1/200, ...)  
layer_histogram_2(x, freq = FALSE, breaks, split = FALSE, transp = 0)  
layer_density_2(x, bw, split = FALSE, rug = TRUE, transp = 0)  
layer_title(x, title = "", cex = 3/4, ...)
```

```

layer_axesnames(x, cex = 3/4, name = "Axis", ...)
layer_eigen(x, nb_max = 5, cex = 1/2, ...)
layer_axesvar(x, cex = 3/4, ...)
layer_legend(x, probs = seq(0, 1, 0.25), cex = 3/4, ...)

```

Arguments

x	a list, typically returned by plot_PCA
center_origin	logical whether to center the origin (default TRUE)
zoom	numeric to change the zoom (default 0.9)
col	color (hexadecimal) to use for drawing components
lwd	linewidth for drawing components
...	additional options to feed core functions for each layer
cex	to use for drawing components
lty	linetype for drawing components
grid	numeric number of grid to draw
border	color (hexadecimal) to use to draw border
pch	to use for drawing components
transp	transparency to use (min: 0 default:0 max:1)
conf	numeric between 0 and 1 for confidence ellipses
alpha	numeric between 0 and 1 for the transparency of components
levels_density	numeric number of levels to use to feed MASS::kde2d
levels_contour	numeric number of levels to use to feed graphics::contour
n	numeric number of grid points to feed MASS::kde2d
density	logical whether to draw density estimate
contour	logical whether to draw contour lines
font	to feed text
abbreviate	logical whether to abbreviate names
rect	logical whether to draw a rectangle below names
size	numeric as a fraction of graphical window (default: 1/200)
freq	logical to feed [hist] (default: FALSE)
breaks	to feed hist (default: calculated on the pooled values)
split	logical whether to split the two distributions into two plots
bw	to feed density (default: stats::bw.nrd0)
rug	logical whether to add rug (default: TRUE)
title	to add to the plot (default "")
name	to use on axes (default "Axis")
nb_max	numeric number of eigen values to display (default 5)
probs	numeric sequence to feed stats::quantile and to indicate where to draw ticks and legend labels

See Also

`grindr_drawers`

Other `grindr`: `drawers`, `layers_morphospace`, `mosaic_engine()`, `papers`, `pile()`, `plot_LDA()`, `plot_NMDS()`, `plot_PCA()`

`layers_morphospace` *Morphospace layers*

Description

Used internally by `plot_PCA`, `plot_LDA`, etc. but may be useful elsewhere.

Usage

```
layer_morphospace_PCA(  
  x,  
  position = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],  
  nb = 12,  
  nr = 6,  
  nc = 5,  
  rotate = 0,  
  size = 0.9,  
  col = "#999999",  
  flipx = FALSE,  
  flipy = FALSE,  
  draw = TRUE  
)
```

```
layer_morphospace_LDA(  
  x,  
  position = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],  
  nb = 12,  
  nr = 6,  
  nc = 5,  
  rotate = 0,  
  size = 0.9,  
  col = "#999999",  
  flipx = FALSE,  
  flipy = FALSE,  
  draw = TRUE  
)
```

Arguments

`x` layered `PCA` or `LDA`. Typically, the object returned by `plot_PCA` and `plot_LDA`

position	one of range, full, circle, xy, range_axes, full_axes to feed morphospace_positions (default: range)
nb	numeric total number of shapes when position="circle" (default: 12)
nr	numeric number of rows to position shapes (default: 6)
nc	numeric number of columns to position shapes (default 5)
rotate	numeric angle (in radians) to rotate shapes when displayed on the morphospace (default: 0)
size	numeric size to use to feed coo_template (default: 0.9)
col	color to draw shapes (default: #999999)
flipx	logical whether to flip shapes against the x-axis (default: FALSE)
flipy	logical whether to flip shapes against the y-axis (default: FALSE)
draw	logical whether to draw shapes (default: TRUE)

See Also

Other grindr: [drawers](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

Other grindr: [drawers](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

LDA

Linear Discriminant Analysis on Coe objects

Description

Calculates a LDA on [Coe](#) on top of [MASS::lda](#).

Usage

```
LDA(x, fac, retain, ...)
```

```
## Default S3 method:
```

```
LDA(x, fac, retain, ...)
```

```
## S3 method for class 'PCA'
```

```
LDA(x, fac, retain = 0.99, ...)
```

Arguments

x	a Coe or a PCA object
fac	the grouping factor (names of one of the \$fac column or column id)
retain	the proportion of the total variance to retain (if retain<1) using scree , or the number of PC axis (if retain>1).
...	additional arguments to feed lda

Value

a 'LDA' object on which to apply [plot.LDA](#), which is a list with components:

- x any [Coe](#) object (or a matrix)
- fac grouping factor used
- removed ids of columns in the original matrix that have been removed since constant (if any)
- mod the raw lda mod from [lda](#)
- mod.pred the predicted model using x and mod
- CV.fac cross-validated classification
- CV.tab cross-validation tabke
- CV.correct proportion of correctly classified individuals
- CV.ce class error
- LDs unstandardized LD scores see [Claude \(2008\)](#)
- mshape mean values of coefficients in the original matrix
- method inherited from the Coe object (if any)

Note

For LDA.PCA, retain can be passed as a vector (eg: 1:5, and retain=1, retain=2, ..., retain=5) will be tried, or as "best" (same as before but retain=1:number_of_pc_axes is used).

Silent message and progress bars (if any) with options("verbose"=FALSE).

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
bot.f <- efourier(bot, 24)
bot.p <- PCA(bot.f)
LDA(bot.p, 'type', retain=0.99) # retains 0.99 of the total variance
LDA(bot.p, 'type', retain=5) # retain 5 axis
bot.l <- LDA(bot.p, 'type', retain=0.99)
plot_LDA(bot.l)
bot.f <- mutate(bot.f, plop=factor(rep(letters[1:4], each=10)))
bot.l <- LDA(PCA(bot.f), 'plop')
plot_LDA(bot.l) # will replace the former soon
```

Ldk	<i>Builds an Ldk object</i>
-----	-----------------------------

Description

In Momocs, Ldk classes objects are lists of configurations of **landmarks**, with optionnal components, on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [fgProcrustes](#)). Ldk objects are primarily [Coo](#) objects. In a sense, morphometrics methods on Ldk objects preserves (x, y) coordinates and LdkCoe are also Ldk objects.

Usage

```
Ldk(coo, fac = dplyr::tibble(), links = NULL, slidings = NULL)
```

Arguments

coo	a list of matrices of (x; y) coordinates, or an array, or an Ldk object or a data.frame (and friends)
fac	(optionnal) a data.frame of factors and/or numerics specifying the grouping structure
links	(optionnal) a 2-columns matrix of 'links' between landmarks, mainly for plotting
slidings	(optionnal) a 3-columns matrix defining (if any) sliding landmarks

Details

All the shapes in x must have the same number of landmarks. If you are trying to make an Ldk object from an Out or an Opn object, try [coo_sample](#) beforehand to homogenize the number of coordinates among shapes. Please note that Ldk methods are as experimental.

implementation of \$slidings is inspired by geomorph

Value

an Ldk object

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [OpnCoe\(\)](#), [Opn\(\)](#), [OutCoe\(\)](#), [Out\(\)](#), [TraCoe\(\)](#)

Examples

```
#Methods on Ldk
methods(class=Ldk)

str(mosquito)
```

ldk_check	<i>Checks 'ldk' shapes</i>
-----------	----------------------------

Description

A simple utility, used internally, mostly by [Ldk](#) methods, in some graphical functions, and notably in [l2a](#). Returns an array of landmarks arranged as $(nb. ldk) \times (x; y) \times (nb. shapes)$, when passed with either a list, a matrix or an array of coordinates. If a list is provided, checks that the number of landmarks is consistent.

Usage

```
ldk_check(ldk)
```

Arguments

ldk a matrix of (x; y) coordinates, a list, or an array.

Value

an array of (x; y) coordinates.

See Also

Other ldk helpers: [def_links\(\)](#), [links_all\(\)](#), [links_delaunay\(\)](#)

Examples

```
#coo_check('Not a shape')
#coo_check(matrix(1:10, ncol=2))
#coo_check(list(x=1:5, y=6:10))
```

ldk_chull	<i>Draws convex hulls around landmark positions</i>
-----------	---

Description

A wrapper that uses [coo_chull](#)

Usage

```
ldk_chull(ldk, col = "grey40", lty = 1)
```

Arguments

ldk an array (or a list) of landmarks
 col a color for drawing the convex hull
 lty an lty for drawing the convex hulls

See Also

[coo_chull](#), [chull](#), [ldk_confell](#), [ldk_contour](#)

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other ldk plotters: [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#)

Examples

```
coo_plot(MSHAPES(wings))
ldk_chull(wings$coo)
```

 ldk_confell

Draws confidence ellipses for landmark positions

Description

Draws confidence ellipses for landmark positions

Usage

```
ldk_confell(
  ldk,
  conf = 0.5,
  col = "grey40",
  ell.lty = 1,
  ax = TRUE,
  ax.lty = 2
)
```

Arguments

ldk an array (or a list) of landmarks
 conf the confidence level (normal quantile, 0.5 by default)
 col the color for the ellipse
 ell.lty an lty for the ellipse
 ax logical whether to draw ellipses axes
 ax.lty an lty for ellipses axes

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other ldk plotters: [ldk_chull\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#)

Examples

```
coo_plot(MSHAPES(wings))
ldk_confell(wings$coo)
```

ldk_contour	<i>Draws kernel density contours around landmark</i>
-------------	--

Description

Using [kde2d](#) in the MASS package.

Usage

```
ldk_contour(ldk, nlevels = 5, grid.nb = 50, col = "grey60")
```

Arguments

ldk	an array (or a list) of landmarks
nlevels	the number of contour lines
grid.nb	the grid.nb
col	a color for drawing the contour lines

See Also

[kde2d](#), [ldk_confell](#), [ldk_chull](#)

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other ldk plotters: [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#)

Examples

```
coo_plot(MSHAPES(wings))
ldk_contour(wings$coo)
```

ldk_labels	<i>Add landmarks labels</i>
------------	-----------------------------

Description

Add landmarks labels

Usage

```
ldk_labels(ldk, d = 0.05, cex = 2/3, ...)
```

Arguments

ldk	a matrix of (x; y) coordinates: where to plot the labels
d	how far from the coordinates, on a (centroid-landmark) segment
cex	the cex for the label
...	additional parameters to feed text

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other ldk plotters: [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_links\(\)](#)

Examples

```
coo_plot(wings[1])
ldk_labels(wings[1])
# closer and smaller
coo_plot(wings[1])
ldk_labels(wings[1], d=0.05, cex=0.5)
```

ldk_links	<i>Draws links between landmarks</i>
-----------	--------------------------------------

Description

Cosmetics only but useful to visualize shape variation.

Usage

```
ldk_links(ldk, links, ...)
```

Arguments

ldk	a matrix of (x; y) coordinates
links	a matrix of links. On the first column the starting-id, on the second column the ending-id (id= the number of the coordinate)
...	additional parameters to fed segments

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [plot_devsegments\(\)](#), [plot_table\(\)](#)

Other ldk plotters: [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#)

lf_structure	<i>bind_db.Coe <- bind_db.Coo Extracts structure from filenames</i>
--------------	--

Description

If filenames are consistently named with the same character serating factors, and with every individual including its belonging levels, e.g.:

- 001_speciesI_siteA_ind1_dorsalview
- 002_speciesI_siteA_ind2_lateralview

etc., this function returns a [data.frame](#) from it that can be passed to [Out](#), [Opn](#), [Ldk](#) objects.

Usage

```
lf_structure(lf, names = character(), split = "_", trim.extension = FALSE)
```

Arguments

lf	a list (its names are used, except if it is a list from import_tps in this case <code>names(lf\$coo)</code> is used) of a list of filenames, as characters, typically such as those obtained with list.files . Alternatively, a path to a folder containing the files. Actually, if lf is of length 1 (a single character), the function assumes it is a path and do a list.files on it.
names	the names of the groups, as a vector of characters which length corresponds to the number of groups.
split	character, the splitting factor used for the file names.
trim.extension	logical. Whether to remove the last for characters in filenames, typically their extension, e.g. '.jpg'.

Details

The number of groups must be consistent across filenames.

Value

data.frame with, for every individual, the corresponding level for every group.

Note

This is, to my view, a good practice to 'store' the grouping structure in filenames, but it is of course not mandatory.

Note also that you can: i) do a [import_jpg](#) and save is a list, say 'foo'; then ii) pass 'names(foo)' to [lf_structure](#). See Momocs' vignette for an illustration.

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

See Also

[import_jpg1](#), [import_Conte](#), [import_txt](#), [lf_structure](#). See also Momocs' vignettes for data import.

Other babel functions: [tie_jpg_txt\(\)](#)

links_all

Creates links (all pairwise combinations) between landmarks

Description

Creates links (all pairwise combinations) between landmarks

Usage

```
links_all(coo)
```

Arguments

coo a matrix (or a list) of (x; y) coordinates

Value

a matrix that can be passed to [ldk_links](#), etc. The columns are the row ids of the original shape.

See Also

Other ldk helpers: [def_links\(\)](#), [ldk_check\(\)](#), [links_delaunay\(\)](#)

Examples

```
w <- wings[1]
coo_plot(w)
links <- links_all(w)
ldk_links(w, links)
```

links_delaunay	<i>Creates links (Delaunay triangulation) between landmarks</i>
----------------	---

Description

Creates links (Delaunay triangulation) between landmarks

Usage

```
links_delaunay(coo)
```

Arguments

coo a matrix (or a list) of (x; y) coordinates

Details

uses [delaunayn](#) in the geometry package.

Value

a matrix that can be passed to [ldk_links](#), etc. The columns are the row ids of the original shape.

See Also

Other ldk helpers: [def_links\(\)](#), [ldk_check\(\)](#), [links_all\(\)](#)

Examples

```
w <- wings[1]
coo_plot(w, poly=FALSE)
links <- links_delaunay(w)
ldk_links(w, links)
```

MANOVA

Multivariate analysis of (co)variance on Coe objects

Description

Performs multivariate analysis of variance on [PCA](#) objects.

Usage

```
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'OpnCoe'
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'OutCoe'
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'PCA'
MANOVA(x, fac, test = "Hotelling", retain = 0.99, drop)
```

Arguments

x	a Coe object
fac	a name of a column in the \$fac slot, or its id, or a formula
test	a test for manova ('Hotelling' by default)
retain	how many harmonics (or polynomials) to retain, for PCA the highest number of PC axis to retain, or the proportion of the variance to capture.
drop	how many harmonics (or polynomials) to drop

Details

Performs a MANOVA/MANCOVA on PC scores. Just a wrapper around [manova](#). See examples for multifactorial manova and [summary.manova](#) for more details and examples.

Value

a list of matrices of (x,y) coordinates.

Note

Needs a review and should be considered as experimental. Silent message and progress bars (if any) with `options("verbose"=FALSE)`.

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
# MANOVA
bot.p <- PCA(efourier(bot, 12))
MANOVA(bot.p, 'type')

op <- PCA(npoly(olea, 5))
MANOVA(op, 'domes')
```

```

m <- manova(op$x[, 1:5] ~ op$fac$domes * op$fac$var)
summary(m)
summary.aov(m)

# MANCOVA example
# we create a numeric variable, based on centroid size
bot %<>% mutate(cs=coo_centsize(.))
# same pipe
bot %>% efourier %>% PCA %>% MANOVA("cs")

```

MANOVA_PW

*Pairwise Multivariate analyses of variance***Description**

A wrapper for pairwise [MANOVAs](#) on [Coe](#) objects. Calculates a MANOVA for every pairwise combination of the factor provided.

Usage

```

MANOVA_PW(x, ...)

## S3 method for class 'PCA'
MANOVA_PW(x, fac, retain = 0.99, ...)

```

Arguments

x	a PCA object
...	more arguments to feed MANOVA
fac	a name (or its id) of a grouping factor in \$fac or a factor or a formula.
retain	the number of PC axis to retain (1:retain) or the proportion of variance to capture (0.99 par default).

Value

a list with the following components is returned (invisibly because \$manovas may be very long, see examples):

- manovas a list containing all the raw manovas
- summary
- stars.tab a table with 'significance stars', discutable but largely used: '' if $\Pr(>F) < 0.001$; '' of < 0.01 ; '' if < 0.05 ; '.' if < 0.10 and '-' if above.

Note

Needs a review and should be considered as experimental. If the fac passed has only two levels, there is only pair and it is equivalent to [MANOVA](#). MANOVA_PW.PCA works with the regular [manova](#).

See Also

[MANOVA](#), [manova](#).

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
# we create a fake factor with 4 levels
bot$fac$fake <- factor(rep(letters[1:4], each=10))
bot.p <- PCA(efourier(bot, 8))
MANOVA_PW(bot.p, 'fake') # or MANOVA_PW(bot.p, 2)

# an example on open outlines
op <- PCA(npoly(olea))
MANOVA_PW(op, 'domes')
# to get the results
res <- MANOVA_PW(op, 'domes')
res$manovas
res$stars.tab
res$summary
```

MDS

(Metric) multidimensional scaling

Description

A wrapper around [stats::cmdscale](#).

Usage

```
MDS(x, method = "euclidean", k = 2, ...)
```

Arguments

x	any Coe object
method	a dissimilarity index to feed method in stats::dist (default: euclidean)
k	numeric number of dimensions to feed stats::cmdscale (default: 2)
...	additional parameters to feed stats::cmdscale

Details

For Details, see [vegan::metaMDS](#)

Value

what is returned by [stats::dist](#) plus \$fac. And prepend MDS class to it.

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
x <- bot %>% efourier %>% MDS
x
```

measure	<i>Measures shape descriptors</i>
---------	-----------------------------------

Description

Calculates shape descriptors on Coo and other objects. Any function that returns a scalar when fed coordinates can be passed and naturally those of Momocs (pick some there apropos("coo_")). Functions without arguments (eg [coo_area](#)) have to be passed without brackets but functions with arguments (eg [d](#)) have to be passed "entirely". See examples.

Usage

```
measure(x, ...)
```

Arguments

`x` any Coo object, or a list of shapes, or a shape as a matrix.
`...` a list of functions. See examples.

Value

a [TraCoe](#) object, or a raw data.frame

See Also

Other premodern: [coo_truss\(\)](#)

Examples

```
bm <- measure(bot, coo_area, coo_perim)
bm
bm$coe

# how to use arguments, eg with the d() function
measure(wings, coo_area, d(1, 3), d(4, 5))

# alternatively, to get a data_frame
```

```
measure(bot$coo, coo_area, coo_perim)

# and also, to get a data_frame (one row)
measure(bot[1], coo_area, coo_perim)
```

molars

Data: Outline coordinates of 360 molars

Description

Courtesy of Julien Corny and Florent Detroit.

Format

A **Out** object containing 79 equilinearly spaced (x; y) coordinates for 360 crown outlines, of modern human molars, along with their type (`$type`) - 90 first upper molars (UM1), 90 second upper molars (UM2), 90 first lower molars (LM1), 90 second lower molars (LM2) - and the individual (`ind`) they come from (the data of the 360 molars are taken from 180 individuals).

Source

Corny, J., & Detroit, F. (2014). Technical Note: Anatomic identification of isolated modern human molars: testing Procrustes aligned outlines as a standardization procedure for elliptic fourier analysis. *American Journal of Physical Anthropology*, 153(2), 314-22. doi:10.1002/ajpa.22428 see <https://onlinelibrary.wiley.com/doi/abs/10.1002/ajpa.22428>

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

Momocs

Momocs

Description

The goal of Momocs is to provide a complete, convenient, reproducible and open-source toolkit for 2D morphometrics. It includes most common 2D morphometrics approaches on outlines, open outlines, configurations of landmarks, traditional morphometrics, and facilities for data preparation, manipulation and visualization with a consistent grammar throughout. It allows reproducible, complex morphometric analyses and other morphometrics approaches should be easy to plug in, or develop from, on top of this canvas.

Details

To cite Momocs in publications: `citation("Momocs")`.

Cheers

We are very grateful to (in alphabetical order): Sean Asselin, Laurent Bouby, Matt Bulbert, Simon Cramer, Julia Cooke, April Dinwiddie, Carl Lipo, Cedric Gaucherel, Catherine Girard, QGouil (GitHub), Christian Steven Hoggard, Sarah Ivorra, Glynis Jones, Nathalie Keller, Ricardo Kriebel, Remi Laffont, Fabien Lafuma, Matthias Mace, Stas Malavin, Neus Martinez, Ben Marwick, Sabrina Renaud, Marcelo Reginato, Evan Saitta, Bill Sellers, David Siddons, Eleanor Stillman, Theodore Stammer, Tom Stubbs, Norbert Telmon, Jean-Frederic Terral, Bill Venables, Daniele Ventura, Michael Wallace, Asher Wishkerman, John Wood for their helpful ideas and bug reports.

References

- Bonhomme V, Picq S, Gaucherel C, Claude J. 2014. Momocs: Outline Analysis Using R. *Journal of Statistical Software* **56**. <https://www.jstatsoft.org/v56/i13>.
- Claude J. 2008. *Morphometrics with R*. Springer-Verlag, New-York.

See Also

- **Homepage:** <https://github.com/MomX/Momocs>
- **Issues:** <https://github.com/MomX/Momocs/issues>
- **Tutorial:** `browseVignettes("Momocs")` or <http://momx.github.io/Momocs/>
- **Email:** `bonhomme.vincent@gmail.com` to contribute to dev, ask for something, propose collaboration, share your data, etc.

`morphospace_positions` *Calculates nice positions on a plane for drawing shapes*

Description

Calculates nice positions on a plane for drawing shapes

Usage

```
morphospace_positions(  
  xy,  
  pos.shp = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],  
  nb.shp = 12,  
  nr.shp = 6,  
  nc.shp = 5,  
  circle.r.shp  
)
```

Arguments

xy	a matrix of points typically from a PCA or other multivariate method on which morphospace can be calculated
pos.shp	how shapes should be positioned: range of xy, full extent of the plane, circle as a rosewind, on xy values provided, range_axes on the range of xy but on the axes, full_axes same thing but on (0.85) range of the axes. You can also directly pass a matrix (or a data.frame) with columns named ("x", "y").
nb.shp	the total number of shapes
nr.shp	the number of rows to position shapes
nc.shp	the number of cols to position shapes
circle.r.shp	if circle, its radius

Details

See [plot.PCA](#) for self-speaking examples

mosaic_engine	<i>Plots mosaics of shapes.</i>
---------------	---------------------------------

Description

Will soon replace [panel](#). See examples and vignettes.

Usage

```
mosaic_engine(
  coo_list,
  dim,
  asp = 1,
  byrow = TRUE,
  fromtop = TRUE,
  sample = 60,
  relatively = FALSE,
  template_size = 0.92
)

mosaic(x, ...)

## S3 method for class 'Out'
mosaic(
  x,
  f,
  relatively = FALSE,
  pal = pal_qual,
  sample = 60,
```



```
    paper_fun = paper_white,  
    draw_fun = draw_outlines,  
    legend = TRUE,  
    dim = NA,  
    asp = 1,  
    byrow = TRUE,  
    fromtop = TRUE,  
    ...  
  )  
  
## S3 method for class 'Opn'  
mosaic(  
  x,  
  f,  
  relatively = FALSE,  
  pal = pal_qual,  
  sample = 60,  
  paper_fun = paper_white,  
  draw_fun = draw_curves,  
  legend = TRUE,  
  dim = NA,  
  asp = 1,  
  byrow = TRUE,  
  fromtop = TRUE,  
  ...  
)  
  
## S3 method for class 'Ldk'  
mosaic(  
  x,  
  f,  
  relatively = FALSE,  
  pal = pal_qual,  
  sample = 60,  
  paper_fun = paper_white,  
  draw_fun = draw_landmarks,  
  legend = TRUE,  
  dim = NA,  
  asp = 1,  
  byrow = TRUE,  
  fromtop = TRUE,  
  ...  
)
```

Arguments

coo_list	list of shapes
dim	numeric of length 2, the desired dimensions for rows and columns

asp	numeric the yx ratio used to calculate dim (1 by default).
byrow	logical whether to order shapes by rows
fromtop	logical whether to order shapes from top
sample	numeric number of points to coo_sample
relatively	logical if TRUE use coo_template_relatively or, if FALSE (by default) coo_template . In other words, whether to preserve size or not.
template_size	numeric to feed coo_template(_relatively) . Only useful to add padding around shapes when the default value (0.95) is lowered.
x	any Coo object
...	additional arguments to feed the main drawer if the number of shapes is > 1000 (default: 64). If non-numeric (eg FALSE) do not sample.
f	factor specification to feed fac_dispatcher
pal	one of palettes
paper_fun	a papers function (default: paper)
draw_fun	one of drawers for <code>pile.list</code>
legend	logical whether to draw a legend (will be improved in further versions)

Value

a list of templated and translated shapes

See Also

Other `grindr`: [drawers](#), [layers_morphospace](#), [layers](#), [papers](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

Examples

```
# On Out ---
bot %>% mosaic
bot %>% mosaic(~type)

# As with other grindr functions you can continue the pipe
bot %>% mosaic(~type, asp=0.5) %>% draw_firstpoint

# On Opn ---- same grammar
olea %>% mosaic(~view+var, paper_fun=paper_dots)

# On Ldk
mosaic(wings, ~group, pal=pal_qual_Dark2, pch=3)

# On Out with different sizes
# would work on other Coo too
shapes2 <- shapes
sizes <- runif(30, 1, 2)
shapes2 %>% mosaic(relatively=FALSE)
shapes2 %>% mosaic(relatively=TRUE) %>% draw_centroid()
```

mosquito

Data: Outline coordinates of mosquito wings.

Description

Data: Outline coordinates of mosquito wings.

Format

A [Out](#) object with the 126 mosquito wing outlines used Rohlf and Archie (1984). Note that the links defined here are quite approximate.

Source

Rohlf F, Archie J. 1984. A comparison of Fourier methods for the description of wing shape in mosquitoes (Diptera: Culicidae). *Systematic Biology*: 302-317.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

mouse

Data: Outline coordinates of mouse molars

Description

Data: Outline coordinates of mouse molars

Format

A [Out](#) object 64 coordinates of 30 wood molar outlines.

Source

Renaud S, Dufour AB, Hardouin EA, Ledevin R, Auffray JC (2015): Once upon multivariate analyses: When they tell several stories about biological evolution. *PLoS One* 10:1-18 <https://journals.plos.org/plosone/article?id=10.1371/journal.pone.0132801>

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

MSHAPES

*Mean shape calculation for Coo, Coe, etc.***Description**

Quite a versatile function that calculates mean (or median, or whatever function) on list or an array of shapes, an Ldk object. It can also be used on Coe objects. In that case, the reverse transformation (from coefficients to shapes) is calculated, (within groups defined with the `fac` argument if provided) and the Coe object is *also* returned (in `$Coe`) along with a list of shapes (in `$shp`) and can then be passed to `plot_MSHAPES`.

Usage

```
MSHAPES(x, fac = NULL, FUN = mean, nb.pts = 120, ...)
```

Arguments

<code>x</code>	a list, array, Ldk, LdkCoe, OutCoe or OpnCoe or PCA object
<code>fac</code>	factor specification for <code>fac_dispatcher</code>
<code>FUN</code>	a function to compute the mean shape (<code>mean</code> by default, by <code>median</code> can be considered)
<code>nb.pts</code>	numeric the number of points for calculated shapes (only Coe objects)
<code>...</code>	useless here.

Value

the averaged shape; on Coe objects, a list with two components: `$Coe` object of the same class, and `$shp` a list of matrices of (x, y) coordinates. On `PCA` and `LDA` objects, the `FUN` (typically mean or median) of scores on PCs or LDs. This method used on the latter objects may be moved to another function at some point.

See Also

Other multivariate: `CLUST()`, `KMEANS()`, `KMEDOIDS()`, `LDA()`, `MANOVA_PW()`, `MANOVA()`, `MDS()`, `NMDS()`, `PCA()`, `classification_metrics()`

Examples

```
#### on shapes
MSHAPES(wings)
MSHAPES(wings$coo)
MSHAPES(coo_sample(bot, 24)$coo)
stack(wings)
coo_draw(MSHAPES(wings))

bot.f <- efourier(bot, 12)
MSHAPES(bot.f) # the mean (global) shape
```

```
ms <- MSHAPES(bot.f, 'type')
ms$Coe
class(ms$Coe)
ms <- ms$shp
coo_plot(ms$beer)
coo_draw(ms$whisky, border='forestgreen')
```

mutate	<i>Add new variables</i>
--------	--------------------------

Description

Add new variables to the \$fac. See examples and `?dplyr::mutate`.

Usage

```
mutate(.data, ...)
```

Arguments

<code>.data</code>	a Coe, Coe, PCA object
<code>...</code>	comma separated list of unquoted expressions

Details

dplyr verbs are maintained.

Value

a Momocs object of the same class.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea
mutate(olea, id=factor(1:length(olea)))
```

 NMDS

*Non metric multidimensional scaling***Description**

A wrapper around [vegan::metaMDS](#).

Usage

```
NMDS(x, distance = "bray", k = 2, try = 20, trymax = 20, ...)
```

Arguments

x	any Coe object
distance	a dissimilarity index to feed vegan::vegdist (default: bray)
k	numeric number of dimensions to feed vegan::metaMDS (default: 2)
try	numeric minimum number of random starts to feed vegan::metaMDS (default: 20)
trymax	numeric minimum number of random starts to feed vegan::metaMDS (default: 20)
...	additional parameters to feed vegan::metaMDS

Details

For Details, see [vegan::metaMDS](#)

Value

what is returned by [vegan::metaMDS](#) plus \$fac. And prepend NMDS class to it.

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [PCA\(\)](#), [classification_metrics\(\)](#)

Examples

```
x <- bot %>% efourier %>% NMDS

# Shepard diagram # before a Momocs wrapper
# vegan::stressplot(x)
```

 npoly

 Calculate natural polynomial fits on open outlines

Description

Calculates natural polynomial coefficients, through a linear model fit (see [lm](#)), from a matrix of (x; y) coordinates or an [Opn](#) object

Usage

```
npoly(x, ...)

## Default S3 method:
npoly(x, degree, ...)

## S3 method for class 'Opn'
npoly(
  x,
  degree,
  baseline1 = c(-0.5, 0),
  baseline2 = c(0.5, 0),
  nb.pts = 120,
  ...
)

## S3 method for class 'list'
npoly(x, ...)
```

Arguments

x	a matrix (or a list) of (x; y) coordinates or an Opn object
...	useless here
degree	polynomial degree for the fit (the Intercept is also returned)
baseline1	numeric the (x; y) coordinates of the first baseline by default ($x = -0.5; y = 0$)
baseline2	numeric the (x; y) coordinates of the second baseline by default ($x = 0.5; y = 0$)
nb.pts	number of points to sample and on which to calculate polynomials

Value

when applied on a single shape, a list with components:

- `coeff` the coefficients (including the intercept)
- `ortho` whether orthogonal or natural polynomials were fitted
- `degree` degree of the fit (could be retrieved through `coeff` though)

- `baseline1` the first baseline point (so far the first point)
- `baseline2` the second baseline point (so far the last point)
- `r2` the r^2 from the fit
- `mod` the raw `lm` model

otherwise, an `OpnCoe` object.

See Also

Other polynomials: `opoly_i()`, `opoly()`

Examples

```
data(olea)
o <- olea[1]
op <- opoly(o, degree=4)
op
# shape reconstruction
opi <- opoly_i(op)
coo_plot(o)
coo_draw(opi, border="red")
# R2 for degree 1 to 10
r <- numeric()
for (i in 1:10) { r[i] <- npoly(o, degree=i)$r2 }
plot(2:10, r[2:10], type='b', pch=20, col='red', main='R2 / degree')
```

nsfishes

Data: Outline coordinates of North Sea fishes

Description

Data: Outline coordinates of North Sea fishes

Format

A `Out` object containing the outlines coordinates for 218 fishes from the North Sea along with taxonomical cofactors.

Source

Caillon F, Frelat R, Mollmann C, Bonhomme V (submitted)

See Also

Other datasets: `apodemus`, `bot`, `chaff`, `charring`, `flower`, `hearts`, `molars`, `mosquito`, `mouse`, `oak`, `olea`, `shapes`, `trilo`, `wings`

oak

Data: Configuration of landmarks of oak leaves

Description

From Viscosi and Cardini (2001).

Format

A [Ldk](#) object containing 11 (x; y) landmarks from 176 oak leaves wings, from

Source

Viscosi, V., & Cardini, A. (2011). Leaf morphology, taxonomy and geometric morphometrics: a simplified protocol for beginners. *PLoS One*, 6(10), e25630. doi:10.1371/journal.pone.0025630

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

olea

Data: Outline coordinates of olive seeds open outlines.

Description

Data: Outline coordinates of olive seeds open outlines.

Format

An [Opn](#) object with the outline coordinates of olive seeds.

Source

We thank Jean-Frederic Terral and Sarah Ivorra (UMR CBAE, Montpellier, France) from allowing us to share the data.

You can have a look to the original paper: Terral J-F, Alonso N, Capdevila RB i, Chatti N, Fabre L, Fiorentino G, Marival P, Jorda GP, Pradat B, Rovira N, et al. 2004. Historical biogeography of olive domestication (*Olea europaea* L.) as revealed by geometrical morphometry applied to biological and archaeological material. *Journal of Biogeography* **31**: 63-77.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [shapes](#), [trilo](#), [wings](#)

Opn	<i>Builds an Opn object</i>
-----	-----------------------------

Description

In Momocs, Opn classes objects are lists of **open** outlines, with optionnal components, on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [npoly](#)) can be applied. Opn objects are primarily [Coo](#) objects.

Usage

```
Opn(x, fac = dplyr::tibble(), ldk = list())
```

Arguments

x	list of matrices of (x; y) coordinates, or an array, or a data.frame (and friends)
fac	(optionnal) a data.frame of factors and/or numerics specifying the grouping structure
ldk	(optionnal) list of landmarks as row number indices

Value

an Opn object

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [Ldk\(\)](#), [OpnCoe\(\)](#), [OutCoe\(\)](#), [Out\(\)](#), [TraCoe\(\)](#)

Examples

```
#Methods on Opn
methods(class=Opn)
# we load some open outlines. See ?olea for credits
olea
panel(olea)
# orthogonal polynomials
op <- opoly(olea, degree=5)
# we print the Coe
op
# Let's do a PCA on it
op.p <- PCA(op)
plot(op.p, 'domes')
plot(op.p, 'var')
# and now an LDA after a PCA
olda <- LDA(PCA(op), 'var')
# for CV table and others
olda
plot_LDA(olda)
```

OpnCoe

*Builds an OpnCoe object***Description**

In Momocs, OpnCoe classes objects are wrapping around lists of morphometric coefficients, along with other informations, on which generic methods such as plotting methods (e.g. [boxplot](#)) and specific methods can be applied. OpnCoe objects are primarily [Coe](#) objects.

Usage

```
OpnCoe(
  coe = matrix(),
  fac = dplyr::tibble(),
  method = character(),
  baseline1 = numeric(),
  baseline2 = numeric(),
  mod = list(),
  r2 = numeric()
)
```

Arguments

coe	matrix of morphometric coefficients
fac	(optionnal) a data.frame of factors, specifying the grouping structure
method	used to obtain these coefficients
baseline1	($x; y$) coordinates of the first baseline point
baseline2	($x; y$) coordinates of the second baseline point
mod	an R lm object, used to reconstruct shapes
r2	numeric, the r-squared from every model

Value

an OpnCoe object

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [Ldk\(\)](#), [Opn\(\)](#), [OutCoe\(\)](#), [Out\(\)](#), [TraCoe\(\)](#)

Examples

```
# all OpnCoe classes
methods(class='OpnCoe')
```

 opoly

Calculate orthogonal polynomial fits on open outlines

Description

Calculates orthogonal polynomial coefficients, through a linear model fit (see [lm](#)), from a matrix of (x; y) coordinates or a [Opn](#) object

Usage

```
opoly(x, ...)

## Default S3 method:
opoly(x, degree, ...)

## S3 method for class 'Opn'
opoly(
  x,
  degree,
  baseline1 = c(-0.5, 0),
  baseline2 = c(0.5, 0),
  nb.pts = 120,
  ...
)

## S3 method for class 'list'
opoly(x, ...)
```

Arguments

x	a matrix (or a list) of (x; y) coordinates
...	useless here
degree	polynomial degree for the fit (the Intercept is also returned)
baseline1	numeric the (x; y) coordinates of the first baseline by default ($x = -0.5; y = 0$)
baseline2	numeric the (x; y) coordinates of the second baseline by default ($x = 0.5; y = 0$)
nb.pts	number of points to sample and on which to calculate polynomials

Value

a list with components when applied on a single shape:

- `coeff` the coefficients (including the intercept)
- `ortho` whether orthogonal or natural polynomials were fitted
- `degree` degree of the fit (could be retrieved through `coeff` though)

- baseline1 the first baseline point (so far the first point)
- baseline2 the second baseline point (so far the last point)
- r2 the r2 from the fit
- mod the raw lm model

otherwise an [OpnCoe](#) object.

Note

Orthogonal polynomials are sometimes called Legendre's polynomials. They are preferred over natural polynomials since adding a degree do not change lower orders coefficients.

See Also

Other polynomials: [npoly\(\)](#), [opoly_i\(\)](#)

Examples

```
data(olea)
o <- olea[1]
op <- opoly(o, degree=4)
op
# shape reconstruction
opi <- opoly_i(op)
coo_plot(o)
coo_draw(opi)
lines(opi, col='red')
# R2 for degree 1 to 10
r <- numeric()
for (i in 1:10) { r[i] <- opoly(o, degree=i)$r2 }
plot(2:10, r[2:10], type='b', pch=20, col='red', main='R2 / degree')
```

opoly_i

Calculates shape from a polynomial model

Description

Returns a matrix of (x; y) coordinates when passed with a list obtained with [opoly](#) or [npoly](#).

Usage

```
opoly_i(pol, nb.pts = 120, reregister = TRUE)
```

```
npoly_i(pol, nb.pts = 120, reregister = TRUE)
```

Arguments

<code>pol</code>	a pol list such as created by npoly or opoly
<code>nb.pts</code>	the number of points to predict. By default (and cannot be higher) the number of points in the original shape.
<code>reregister</code>	logical whether to reregister the shape with the original baseline.

Value

a matrix of (x; y) coordinates.

See Also

Other polynomials: [npoly\(\)](#), [opoly\(\)](#)

Examples

```
data(olea)
o <- olea[5]
coo_plot(o)
for (i in 2:7){
  x <- opoly_i(opoly(o, i))
  coo_draw(x, border=col_summer(7)[i], points=FALSE) }
```

Out

Builds an Out object

Description

In Momocs, Out-classes objects are lists of closed **outlines**, with optional components, and on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [efourier](#)) can be applied. Out objects are primarily [Coo](#) objects.

Usage

```
Out(x, fac = dplyr::tibble(), ldk = list())
```

Arguments

<code>x</code>	a list of matrices of (x; y) coordinates, or an array or an Out object or an Ldk object, or a data.frame (and friends)
<code>fac</code>	(optional) a data.frame of factors and/or numerics specifying the grouping structure
<code>ldk</code>	(optional) list of landmarks as row number indices

Value

an Out object

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [Ldk\(\)](#), [OpnCoe\(\)](#), [Opn\(\)](#), [OutCoe\(\)](#), [TraCoe\(\)](#)

Examples

```
methods(class=Out)
```

OutCoe

Builds an OutCoe object

Description

In Momocs, OutCoe classes objects are wrapping around lists of morphometric coefficients, along with other informations, on which generic methods such as plotting methods (e.g. [boxplot](#)) and specific methods can be applied. OutCoe objects are primarily [Coe](#) objects.

Usage

```
OutCoe(coe = matrix(), fac = dplyr::tibble(), method, norm)
```

Arguments

coe	matrix of harmonic coefficients
fac	(optional) a data.frame of factors, specifying the grouping structure
method	used to obtain these coefficients
norm	the normalisation used to obtain these coefficients

Details

These methods can be applied on Out objects:

Value

an OutCoe object

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [Ldk\(\)](#), [OpnCoe\(\)](#), [Opn\(\)](#), [Out\(\)](#), [TraCoe\(\)](#)

Examples

```
# all OutCoe methods
methods(class='OutCoe')
```

palettes

Color palettes

Description

All colorblind friendly RColorBrewer palettes recreated without the number of colors limitation and with transparency support thanks to `pal_alpha` that can be used alone. Also, all viridis palettes (see the [package on CRAN](#)), yet color ramps are borrowed and Momocs does not depend on it. Also, `pal_qual_solarized` based on Solarized: <https://ethanschoonover.com/solarized/> and `pal_seq_grey` only shades of grey from grey10 to grey90.

Usage

```
pal_alpha(cols, transp = 0)
pal_manual(cols, transp = 0)
pal_qual_solarized(n, transp = 0)
pal_seq_grey(n, transp = 0)
pal_div_BrBG(n, transp = 0)
pal_div_PiYG(n, transp = 0)
pal_div_PRGn(n, transp = 0)
pal_div_PuOr(n, transp = 0)
pal_div_RdBu(n, transp = 0)
pal_div_RdYlBu(n, transp = 0)
pal_qual_Dark2(n, transp = 0)
pal_qual_Paired(n, transp = 0)
pal_qual_Set2(n, transp = 0)
pal_seq_Blues(n, transp = 0)
pal_seq_BuGn(n, transp = 0)
pal_seq_BuPu(n, transp = 0)
pal_seq_GnBu(n, transp = 0)
```



```
pal_seq_Greens(n, transp = 0)
pal_seq_Greys(n, transp = 0)
pal_seq_Oranges(n, transp = 0)
pal_seq_OrRd(n, transp = 0)
pal_seq_PuBu(n, transp = 0)
pal_seq_PuBuGn(n, transp = 0)
pal_seq_PuRd(n, transp = 0)
pal_seq_Purples(n, transp = 0)
pal_seq_RdPu(n, transp = 0)
pal_seq_Reds(n, transp = 0)
pal_seq_YlGn(n, transp = 0)
pal_seq_YlGnBu(n, transp = 0)
pal_seq_YlOrBr(n, transp = 0)
pal_seq_YlOrRd(n, transp = 0)
pal_seq_magma(n, transp = 0)
pal_seq_inferno(n, transp = 0)
pal_seq_plasma(n, transp = 0)
pal_seq_viridis(n, transp = 0)
pal_qual(n, transp = 0)
pal_seq(n, transp = 0)
pal_div(n, transp = 0)
```

Arguments

cols	color(s) as hexadecimal values
transp	numeric between 0 and 1 (0, eg opaque, by default)
n	numeric number of colors

Details

Default color palettes are currently:

- `pal_qual=pal_qual_Set2`
- `pal_seq=pal_seq_viridis`
- `pal_div=pal_div_RdBu`

Note

RColorBrewer palettes are not happy when `n` is lower than 3 and above a given number for each palette. If this is the case, these functions will create a color palette with [colorRampPalette](#) and return colors even so.

Examples

```
pal_div_BrBG(5) %>% barplot(rep(1, 5), col=.)
pal_div_BrBG(5, 0.5) %>% barplot(rep(1, 5), col=.)
```

panel

Family picture of shapes

Description

Plots all the outlines, side by side, from a [Coo](#) ([Out](#), [Opn](#) or [Ldk](#)) objects.

Usage

```
panel(x, ...)

## S3 method for class 'Out'
panel(
  x,
  dim,
  cols,
  borders,
  fac,
  palette = col_summer,
  coo_sample = 120,
  names = NULL,
  cex.names = 0.6,
  points = TRUE,
  points.pch = 3,
  points.cex = 0.2,
  points.col,
  ...
)
```

```

## S3 method for class 'Opn'
panel(
  x,
  cols,
  borders,
  fac,
  palette = col_summer,
  coo_sample = 120,
  names = NULL,
  cex.names = 0.6,
  points = TRUE,
  points.pch = 3,
  points.cex = 0.2,
  points.col,
  ...
)

## S3 method for class 'Ldk'
panel(
  x,
  cols,
  borders,
  fac,
  palette = col_summer,
  names = NULL,
  cex.names = 0.6,
  points = TRUE,
  points.pch = 3,
  points.cex = 0.2,
  points.col = "#333333",
  ...
)

```

Arguments

x	The Coo object to plot.
...	additional arguments to feed generic plot
dim	for coo_listpanel : a numeric of length 2 specifying the dimensions of the panel
cols	A vector of colors for drawing the outlines. Either a single value or of length exactly equal to the number of coordinates.
borders	A vector of colors for drawing the borders. Either a single value or of length exactly equals to the number of coordinates.
fac	a factor within the \$fac slot for colors
palette	a color palette
coo_sample	if not NULL the number of point per shape to display (to plot quickly)
names	whether to plot names or not. If TRUE uses shape names, or something for fac_dispatcher

<code>cex.names</code>	a cex for the names
<code>points</code>	logical (for Ldk) whether to draw points
<code>points.pch</code>	(for Ldk) and a pch for these points
<code>points.cex</code>	(for Ldk) and a cex for these points
<code>points.col</code>	(for Ldk) and a col for these points

Note

If you want to reorder shapes according to a factor, use [arrange](#).

See Also

Other `Coo_graphics`: [inspect\(\)](#), [stack\(\)](#)

Examples

```
panel(mosquito, names=TRUE, cex.names=0.5)
panel(olea)
panel(bot, c(4, 10))
# an illustration of the use of fac
panel(bot, fac='type', palette=col_spring, names=TRUE)
```

papers

grindr papers for shape plots

Description

Papers on which to use [drawers](#) for building custom shape plots using the `grindr` approach. See examples and vignettes.

Usage

```
paper(coo, ...)

paper_white(coo)

paper_grid(coo, grid = c(10, 5), cols = c("#ffa500", "#e5e5e5"), ...)

paper_chess(coo, n = 50, col = "#E5E5E5")

paper_dots(coo, pch = 20, n = 50, col = "#7F7F7F")
```

Arguments

coo	a single shape or any Coo object
...	more arguments to feed the plotting function within each paper function
grid	numeric of length 2 to (roughly) specify the number of majors lines, and the number of minor lines within two major ones
cols	colors (hexadecimal preferred) to use for grid drawing
n	numeric number of squares for the chessboard
col	color (hexadecimal) to use for chessboard drawing
pch	to use for dots

Note

This approach will (soon) replace [coo_plot](#) and friends in further versions. All comments are welcome.

See Also

Other grindr: [drawers](#), [layers_morphospace](#), [layers](#), [mosaic_engine\(\)](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

 PCA

Principal component analysis on Coe objects

Description

Performs a PCA on [Coe](#) objects, using [prcomp](#).

Usage

```

PCA(x, scale., center, fac)

## S3 method for class 'OutCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'OpnCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'LdkCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'TraCoe'
PCA(x, scale. = TRUE, center = TRUE, fac)

## Default S3 method:
PCA(x, scale. = TRUE, center = TRUE, fac = dplyr::tibble())

as_PCA(x, fac)

```

Arguments

x	a Coe object or an appropriate object (eg prcomp) for <code>as_PCA</code>
scale.	logical whether to scale the input data
center	logical whether to center the input data
fac	any factor or <code>data.frame</code> to be passed to <code>as_PCA</code> and for use with plot.PCA

Details

By default, methods on [Coe](#) object do not scale the input data but center them. There is also a generic method (eg for traditional morphometrics) that centers and scales data.

Value

a 'PCA' object on which to apply [plot.PCA](#), among others. This list has several components, most of them inherited from the `prcomp` object:

1. `sdev` the standard deviations of the principal components (i.e., the square roots of the eigenvalues of the covariance/correlation matrix, though the calculation is actually done with the singular values of the data matrix)
2. `eig` the cumulated proportion of variance along the PC axes
3. `rotation` the matrix of variable loadings (i.e., a matrix whose columns contain the eigenvectors). The function `princomp` returns this in the element `loadings`.
4. `center`, `scale` the centering and scaling used
5. `x` PCA scores (the value of the rotated data (the centred (and scaled if requested) data multiplied by the rotation matrix))
6. other components are inherited from the `Coe` object passed to `PCA`, eg `fac`, `mshape`, `method`, `baseline1` and `baseline2`, etc. They are documented in the corresponding `*Coe` file.

See Also

Other multivariate: [CLUST\(\)](#), [KMEANS\(\)](#), [KMEDOIDS\(\)](#), [LDA\(\)](#), [MANOVA_PW\(\)](#), [MANOVA\(\)](#), [MDS\(\)](#), [MSHAPES\(\)](#), [NMDS\(\)](#), [classification_metrics\(\)](#)

Examples

```
bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)
bot.p
plot(bot.p, morpho=FALSE)
plot(bot.p, 'type')

op <- npoly(olea, 5)
op.p <- PCA(op)
op.p
plot(op.p, 1, morpho=TRUE)

wp <- fgProcrustes(wings, tol=1e-4)
wpp <- PCA(wp)
```

```
wpp
plot(wpp, 1)

# "foreign prcomp"
head(iris)
iris.p <- prcomp(iris[, 1:4])
iris.p <- as_PCA(iris.p, iris[, 5])
class(iris.p)
plot(iris.p, 1)
```

PCcontrib

Shape variation along PC axes

Description

Calculates and plots shape variation along Principal Component axes.

Usage

```
PCcontrib(PCA, ...)

## S3 method for class 'PCA'
PCcontrib(PCA, nax, sd.r = c(-2, -1, -0.5, 0, 0.5, 1, 2), gap = 1, ...)
```

Arguments

PCA	a PCA object
...	additional parameter to pass to coo_draw
nax	the range of PCs to plot (1 to 99pc total variance by default)
sd.r	a single or a range of mean +/- sd values (eg: c(-1, 0, 1))
gap	for combined-Coe, an adjustment variable for gap between shapes. (bug)Default to 1 (whish should never superimpose shapes), reduce it to get a more compact plot.

Value

(invisibly) a list with gg the ggplot object and shp the list of shapes.

Examples

```
bot.p <- PCA(efourier(bot, 12))
PCcontrib(bot.p, nax=1:3)
## Not run:
library(ggplot2)
gg <- PCcontrib(bot.p, nax=1:8, sd.r=c(-5, -3, -2, -1, -0.5, 0, 0.5, 1, 2, 3, 5))
gg$gg + geom_polygon(fill="slategrey", col="black") + ggtitle("A nice title")

## End(Not run)
```

perm

Permutes and breed Coe (and others) objects

Description

This methods applies permutations column-wise on the coe of any [Coe](#) object but relies on a function that can be used on any matrix. For a Coe object, it uses [sample](#) on every column (or row) with (or without) replacement.

Usage

```
perm(x, ...)  
  
## Default S3 method:  
perm(x, margin = 2, size, replace = TRUE, ...)  
  
## S3 method for class 'Coe'  
perm(x, size, replace = TRUE, ...)
```

Arguments

x	the object to permute
...	useless here
margin	numeric whether 1 or 2 (rows or columns)
size	numeric the required size for the final object, same size by default.
replace	logical, whether to use sample with replacement

See Also

Other farming: [breed\(\)](#)

Examples

```
m <- matrix(1:12, nrow=3)  
m  
perm(m, margin=2, size=5)  
perm(m, margin=1, size=10)  
  
bot.f <- efourier(bot, 12)  
bot.m <- perm(bot.f, 80)  
bot.m
```

pile

Graphical pile of shapes

Description

Pile all shapes in the same graphical window. Useful to check their normalization in terms of size, position, rotation, first point, etc. It is, essentially, a shortcut around `paper + drawers` of the `grindr` family.

Usage

```
pile(coo, f, sample, subset, pal, paper_fun, draw_fun, transp, ...)
```

```
## Default S3 method:
```

```
pile(  
  coo,  
  f,  
  sample,  
  subset,  
  pal = pal_qual,  
  paper_fun = paper,  
  draw_fun = draw_curves,  
  transp = 0,  
  ...  
)
```

```
## S3 method for class 'list'
```

```
pile(  
  coo,  
  f,  
  sample = 64,  
  subset = 1000,  
  pal = pal_qual,  
  paper_fun = paper,  
  draw_fun = draw_curves,  
  transp = 0,  
  ...  
)
```

```
## S3 method for class 'array'
```

```
pile(  
  coo,  
  f,  
  sample = 64,  
  subset = 1000,  
  pal = pal_qual,  
  paper_fun = paper,  
  ...  
)
```

```
    draw_fun = draw_landmarks,
    transp = 0,
    ...
)

## S3 method for class 'Out'
pile(
  coo,
  f,
  sample = 64,
  subset = 1000,
  pal = pal_qual,
  paper_fun = paper,
  draw_fun = draw_outlines,
  transp = 0,
  ...
)

## S3 method for class 'Opn'
pile(
  coo,
  f,
  sample = 64,
  subset = 1000,
  pal = pal_qual,
  paper_fun = paper,
  draw_fun = draw_curves,
  transp = 0,
  ...
)

## S3 method for class 'Ldk'
pile(
  coo,
  f,
  sample = 64,
  subset = 1000,
  pal = pal_qual,
  paper_fun = paper,
  draw_fun = draw_landmarks,
  transp = 0,
  ...
)
```

Arguments

coo	a single shape or any Coo object
f	factor specification

sample	numeric number of points to coo_sample if the number of shapes is > 1000 (default: 64). If non-numeric (eg FALSE) do not sample.
subset	numeric only draw this number of (randomly chosen) shapes if the number of shapes is > 1000 (default: 1000) If non-numeric (eg FALSE) do not sample.
pal	palette among palettes (default: pal_qual)
paper_fun	a papers function (default: paper)
draw_fun	one of drawers for <code>pile.list</code>
transp	numeric for transparency (default:adjusted, min:0, max=0)
...	more arguments to feed the core drawer, depending on the object

Details

Large Coos are sampled, both in terms of the number of shapes and of points to drawn.

Note

A variation of this plot was called `stack` before Momocs 1.2.5

See Also

Other `grindr`: [drawers](#), [layers_morphospace](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

Examples

```
# all Coos are supported with sensible defaults
pile(bot) # outlines
pile(olea, ~var, pal=pal_qual_Dark2, paper_fun=paper_grid) # curves
pile(wings) # landmarks

# you can continue the pipe with compatible drawers
pile(bot, trans=0.9) %>% draw_centroid

# if you are not happy with this, build your own !
# eg see Momocs::pile.Out (no quotes)

my_pile <- function(x, col_labels="red", transp=0.5){
  x %>% paper_chess(n=100) %>%
    draw_landmarks(transp=transp) %>%
    draw_labels(col=col_labels)
}

# using it
wings %>% my_pile(transp=3/4)

# and as gridr functions propagate, you can even continue:
wings %>% my_pile() %>% draw_centroid(col="blue", cex=5)

# method on lists
bot$coo %>% pile
```

```
# it can be tuned when we have a list of landmarks with:
wings$coo %>% pile(draw_fun=draw_landmarks)

# or on arrays (turn for draw_landmarks)
wings$coo %>% l2a %>% #we now have an array
  pile
```

pix2chc

Convert (x; y) coordinates to chaincoded coordinates

Description

Useful to convert (x; y) coordinates to chain-coded coordinates.

Usage

```
pix2chc(coo)
```

```
chc2pix(chc)
```

Arguments

coo	(x; y) coordinates passed as a matrix
chc	chain coordinates

Note

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

References

Kuhl, F. P., & Giardina, C. R. (1982). Elliptic Fourier features of a closed contour. *Computer Graphics and Image Processing*, 18(3), 236-258.

See Also

[chc2pix](#)

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#)

Other import functions: [import_Conte\(\)](#), [import_StereoMorph_curve1\(\)](#), [import_jpg1\(\)](#), [import_jpg\(\)](#), [import_tps\(\)](#), [import_txt\(\)](#)

Examples

```
pix2chc(shapes[1]) %T>% print %>% # from pix to chc
chc2pix() # and back
```

Description

The Momocs' [LDA](#) plotter with many graphical options.

Usage

```
## S3 method for class 'LDA'
plot(
  x,
  fac = x$fac,
  xax = 1,
  yax = 2,
  points = TRUE,
  col = "#000000",
  pch = 20,
  cex = 0.5,
  palette = col_solarized,
  center.origin = FALSE,
  zoom = 1,
  xlim = NULL,
  ylim = NULL,
  bg = par("bg"),
  grid = TRUE,
  nb.grids = 3,
  morphospace = FALSE,
  pos.shp = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],
  amp.shp = 1,
  size.shp = 1,
  nb.shp = 12,
  nr.shp = 6,
  nc.shp = 5,
  rotate.shp = 0,
  flipx.shp = FALSE,
  flipy.shp = FALSE,
  pts.shp = 60,
  border.shp = col_alpha("#000000", 0.5),
  lwd.shp = 1,
  col.shp = col_alpha("#000000", 0.95),
  stars = FALSE,
  ellipses = FALSE,
  conf.ellipses = 0.5,
  ellipsesax = TRUE,
  conf.ellipsesax = c(0.5, 0.9),
  lty.ellipsesax = 1,
```

```

lwd.ellipsesax = sqrt(2),
chull = FALSE,
chull.lty = 1,
chull.filled = FALSE,
chull.filled.alpha = 0.92,
density = FALSE,
lev.density = 20,
contour = FALSE,
lev.contour = 3,
n.kde2d = 100,
deLaunay = FALSE,
loadings = FALSE,
labelpoints = FALSE,
col.labelpoints = par("fg"),
cex.labelpoints = 0.6,
abbreviate.labelpoints = TRUE,
labelgroups = TRUE,
cex.labelgroups = 0.8,
rect.labelgroups = FALSE,
abbreviate.labelgroups = FALSE,
color.legend = FALSE,
axisnames = TRUE,
axisvar = TRUE,
unit = FALSE,
eigen = TRUE,
rug = TRUE,
title = substitute(x),
box = TRUE,
old.par = TRUE,
...
)

```

Arguments

x	an object of class "LDA", typically obtained with LDA
fac	name or the column id from the \$fac slot, or a formula combining column names from the \$fac slot (cf. examples). A factor or a numeric of the same length can also be passed on the fly.
xax	the first PC axis
yax	the second PC axis
points	logical whether to plot points
col	a color for the points (either global, for every level of the fac or for every individual, see examples)
pch	a pch for the points (either global, for every level of the fac or for every individual, see examples)
cex	the size of the points

palette	a palette
center.origin	logical whether to center the plot onto the origin
zoom	to keep your distances
xlim	numeric of length two ; if provided along with ylim, the x and y lims to use
ylim	numeric of length two ; if provided along with xlim, the x and y lims to use
bg	color for the background
grid	logical whether to draw a grid
nb.grids	and how many of them
morphospace	logical whether to add the morphological space
pos.shp	passed to morphospace_positions , one of "range", "full", "circle", "xy", "range_axes", "full_axes". Or directly a matrix of positions. See morphospace_positions
amp.shp	amplification factor for shape deformation
size.shp	the size of the shapes
nb.shp	(pos.shp="circle") the number of shapes on the compass
nr.shp	(pos.shp="full" or "range) the number of shapes per row
nc.shp	(pos.shp="full" or "range) the number of shapes per column
rotate.shp	angle in radians to rotate shapes (if several methods, a vector of angles)
flipx.shp	same as above, whether to apply <code>coo_flipx</code>
flipy.shp	same as above, whether to apply <code>coo_flipy</code>
pts.shp	the number of points fro drawing shapes
border.shp	the border color of the shapes
lwd.shp	the line width for these shapes
col.shp	the color of the shapes
stars	logical whether to draw "stars"
ellipses	logical whether to draw confidence ellipses
conf.ellipses	numeric the quantile for the (bivariate gaussian) confidence ellipses
ellipsesax	logical whether to draw ellipse axes
conf.ellipsesax	one or more numeric, the quantiles for the (bivariate gaussian) ellipses axes
lty.ellipsesax	if yes, the lty with which to draw these axes
lwd.ellipsesax	if yes, one or more numeric for the line widths
chull	logical whether to draw a convex hull
chull.lty	if yes, its linetype
chull.filled	logical whether to add filled convex hulls
chull.filled.alpha	numeric alpha transparency
density	whether to add a 2d density kernel estimation (based on kde2d)

lev.density	if yes, the number of levels to plot (through image)
contour	whether to add contour lines based on 2d density kernel
lev.contour	if yes, the (approximate) number of lines to draw
n.kde2d	the number of bins for kde2d , ie the 'smoothness' of density kernel
delaunay	logical whether to add a delaunay 'mesh' between points
loadings	logical whether to add loadings for every variables
labelspoints	if TRUE rownames are used as labels, a colname from \$fac can also be passed
col.labelspoints	a color for these labels, otherwise inherited from fac
cex.labelspoints	a cex for these labels
abbreviate.labelspoints	logical whether to abbreviate
labelsgroups	logical whether to add labels for groups
cex.labelsgroups	if yes, a numeric for the size of the labels
rect.labelsgroups	logical whether to add a rectangle behind groups names
abbreviate.labelsgroups	logical, whether to abbreviate group names
color.legend	logical whether to add a (cheap) color legend for numeric fac
axisnames	logical whether to add PC names
axisvar	logical whether to draw the variance they explain
unit	logical whether to add plane unit
eigen	logical whether to draw a plot of the eigen values
rug	logical whether to add rug to margins
title	character a name for the plot
box	whether to draw a box around the plotting region
old.par	whether to restore the old par . Set it to FALSE if you want to reuse the graphical window.
...	useless here, just to fit the generic plot

Details

Widely inspired by the "layers" philosophy behind graphical functions of the [ade4](#) R package.

Note

Morphospaces are deprecated so far. 99% of the code is shared with [plot.PCA](#) waiting for a general rewriting of a multivariate plotter. See <https://github.com/vbonhomme/Momocs/issues/121>

See Also

[LDA](#), [plot_CV](#), [plot_CV2](#), [plot.PCA](#).

plot.PCA

Plots Principal Component Analysis

Description

The Momocs' [PCA](#) plotter with morphospaces and many graphical options.

Usage

```
## S3 method for class 'PCA'
plot(
  x,
  fac,
  xax = 1,
  yax = 2,
  points = TRUE,
  col = "#000000",
  pch = 20,
  cex = 0.5,
  palette = col_solarized,
  center.origin = FALSE,
  zoom = 1,
  xlim = NULL,
  ylim = NULL,
  bg = par("bg"),
  grid = TRUE,
  nb.grids = 3,
  morphospace = TRUE,
  pos.shp = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],
  amp.shp = 1,
  size.shp = 1,
  nb.shp = 12,
  nr.shp = 6,
  nc.shp = 5,
  rotate.shp = 0,
  flipx.shp = FALSE,
  flipy.shp = FALSE,
  pts.shp = 60,
  border.shp = col_alpha("#000000", 0.5),
  lwd.shp = 1,
  col.shp = col_alpha("#000000", 0.95),
  stars = FALSE,
  ellipses = FALSE,
  conf.ellipses = 0.5,
  ellipsesax = FALSE,
  conf.ellipsesax = c(0.5, 0.9),
  lty.ellipsesax = 1,
```

```

lwd.ellipsesax = sqrt(2),
chull = FALSE,
chull.lty = 1,
chull.filled = TRUE,
chull.filled.alpha = 0.92,
density = FALSE,
lev.density = 20,
contour = FALSE,
lev.contour = 3,
n.kde2d = 100,
deLaunay = FALSE,
loadings = FALSE,
labelpoints = FALSE,
col.labelpoints = par("fg"),
cex.labelpoints = 0.6,
abbreviate.labelpoints = TRUE,
labelgroups = TRUE,
cex.labelgroups = 0.8,
rect.labelgroups = FALSE,
abbreviate.labelgroups = FALSE,
color.legend = FALSE,
axisnames = TRUE,
axisvar = TRUE,
unit = FALSE,
eigen = TRUE,
rug = TRUE,
title = substitute(x),
box = TRUE,
old.par = TRUE,
...
)

```

Arguments

x	PCA, typically obtained with PCA
fac	name or the column id from the \$fac slot, or a formula combining column names from the \$fac slot (cf. examples). A factor or a numeric of the same length can also be passed on the fly.
xax	the first PC axis
yax	the second PC axis
points	logical whether to plot points
col	a color for the points (either global, for every level of the fac or for every individual, see examples)
pch	a pch for the points (either global, for every level of the fac or for every individual, see examples)
cex	the size of the points

palette	a palette
center.origin	logical whether to center the plot onto the origin
zoom	to keep your distances
xlim	numeric of length two ; if provided along with ylim, the x and y lims to use
ylim	numeric of length two ; if provided along with xlim, the x and y lims to use
bg	color for the background
grid	logical whether to draw a grid
nb.grids	and how many of them
morphospace	logical whether to add the morphological space
pos.shp	passed to morphospace_positions , one of "range", "full", "circle", "xy", "range_axes", "full_axes". Or directly a matrix of positions. See morphospace_positions
amp.shp	amplification factor for shape deformation
size.shp	the size of the shapes
nb.shp	(pos.shp="circle") the number of shapes on the compass
nr.shp	(pos.shp="full" or "range) the number of shapes per row
nc.shp	(pos.shp="full" or "range) the number of shapes per column
rotate.shp	angle in radians to rotate shapes (if several methods, a vector of angles)
flipx.shp	same as above, whether to apply <code>coo_flipx</code>
flipy.shp	same as above, whether to apply <code>coo_flipy</code>
pts.shp	the number of points fro drawing shapes
border.shp	the border color of the shapes
lwd.shp	the line width for these shapes
col.shp	the color of the shapes
stars	logical whether to draw "stars"
ellipses	logical whether to draw confidence ellipses
conf.ellipses	numeric the quantile for the (bivariate gaussian) confidence ellipses
ellipsesax	logical whether to draw ellipse axes
conf.ellipsesax	one or more numeric, the quantiles for the (bivariate gaussian) ellipses axes
lty.ellipsesax	if yes, the lty with which to draw these axes
lwd.ellipsesax	if yes, one or more numeric for the line widths
chull	logical whether to draw a convex hull
chull.lty	if yes, its linetype
chull.filled	logical whether to add filled convex hulls
chull.filled.alpha	numeric alpha transparency
density	whether to add a 2d density kernel estimation (based on kde2d)

lev.density	if yes, the number of levels to plot (through image)
contour	whether to add contour lines based on 2d density kernel
lev.contour	if yes, the (approximate) number of lines to draw
n.kde2d	the number of bins for kde2d , ie the 'smoothness' of density kernel
delaunay	logical whether to add a delaunay 'mesh' between points
loadings	logical whether to add loadings for every variables
labelspoints	if TRUE rownames are used as labels, a colname from \$fac can also be passed
col.labelspoints	a color for these labels, otherwise inherited from fac
cex.labelspoints	a cex for these labels
abbreviate.labelspoints	logical whether to abbreviate
labelsgroups	logical whether to add labels for groups
cex.labelsgroups	if yes, a numeric for the size of the labels
rect.labelsgroups	logical whether to add a rectangle behind groups names
abbreviate.labelsgroups	logical, whether to abbreviate group names
color.legend	logical whether to add a (cheap) color legend for numeric fac
axisnames	logical whether to add PC names
axisvar	logical whether to draw the variance they explain
unit	logical whether to add plane unit
eigen	logical whether to draw a plot of the eigen values
rug	logical whether to add rug to margins
title	character a name for the plot
box	whether to draw a box around the plotting region
old.par	whether to restore the old par . Set it to FALSE if you want to reuse the graphical window.
...	useless here, just to fit the generic plot

Details

Widely inspired by the "layers" philosophy behind graphical functions of the [ade4](#) R package.

Note

NAs in \$fac are handled quite experimentally. More importantly, as of early 2018, I plan to complete a rewrite of `plot.PCA` and other multivariate plotters.

See Also

[plot.LDA](#)

Examples

```

## Not run:
bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)

### Morphospace options
plot(bot.p, pos.shp="full")
plot(bot.p, pos.shp="range")
plot(bot.p, pos.shp="xy")
plot(bot.p, pos.shp="circle")
plot(bot.p, pos.shp="range_axes")
plot(bot.p, pos.shp="full_axes")

plot(bot.p, morpho=FALSE)

### Passing factors to plot.PCA
# 3 equivalent methods
plot(bot.p, "type")
plot(bot.p, 1)
plot(bot.p, ~type)

# let's create a dummy factor of the correct length
# and another added to the $fac with mutate
# and a numeric of the correct length
f <- factor(rep(letters[1:2], 20))
z <- factor(rep(LETTERS[1:2], 20))
bot %<>% mutate(cs=coo_centsize(.), z=z)
bp <- bot %>% efourier %>% PCA
# so bp contains type, cs (numeric) and z; not f
# yet f can be passed on the fly
plot(bp, f)
# numeric fac are allowed
plot(bp, "cs", cex=3, color.legend=TRUE)
# formula allows combinations of factors
plot(bp, ~type+z)

### other morphometric approaches works the same
# open curves
op <- npoly(olea, 5)
op.p <- PCA(op)
op.p
plot(op.p, ~ domes + var, morpho=TRUE) # use of formula

# landmarks
wp <- fgProcrustes(wings, tol=1e-4)
wpp <- PCA(wp)
wpp
plot(wpp, 1)

# traditional measurements
flower %>% PCA %>% plot(1)

```

```

# plot.PCA can be used after a PCA
PCA(iris[, 1:4], fac=iris$Species) %>% plot(1)

### Cosmetic options
# window
plot(bp, 1, zoom=2)
plot(bp, zoom=0.5)
plot(bp, center.origin=FALSE, grid=FALSE)

# colors
plot(bp, col="red") # globally
plot(bp, 1, col=c("#00FF00", "#0000FF")) # for every level
# a color vector of the right length
plot(bp, 1, col=rep(c("#00FF00", "#0000FF"), each=20))
# a color vector of the right length, mixign Rcolor names (not a good idea though)
plot(bp, 1, col=rep(c("#00FF00", "forestgreen"), each=20))

# ellipses
plot(bp, 1, conf.ellipsesax=2/3)
plot(bp, 1, ellipsesax=FALSE)
plot(bp, 1, ellipsesax=TRUE, ellipses=TRUE)

# stars
plot(bp, 1, stars=TRUE, ellipsesax=FALSE)

# convex hulls
plot(bp, 1, chull=TRUE)
plot(bp, 1, chull.lty=3)

# filled convex hulls
plot(bp, 1, chull.filled=TRUE)
plot(bp, 1, chull.filled.alpha = 0.8, chull.lty = 1) # you can omit chull.filled=TRUE

# density kernel
plot(bp, 1, density=TRUE, contour=TRUE, lev.contour=10)

# delaunay
plot(bp, 1, delaunay=TRUE)

# loadings
flower %>% PCA %>% plot(1, loadings=TRUE)

# point/group labelling
plot(bp, 1, labelspoint=TRUE) # see options for abbreviations
plot(bp, 1, labelsgroup=TRUE) # see options for abbreviations

# clean axes, no rug, no border, random title
plot(bp, axisvar=FALSE, axisnames=FALSE, rug=FALSE, box=FALSE, title="random")

# no eigen
plot(bp, eigen=FALSE) # eigen cause troubles to graphical window
# eigen may causes troubles to the graphical window. you can try old.par = TRUE

```

```
## End(Not run)
```

```
plot_CV          Plots a cross-validation table as an heatmap
```

Description

Either with frequencies (or percentages) plus marginal sums, and values as heatmaps. Used in Momocs for plotting cross-validation tables but may be used for any table (likely with freq=FALSE).

Usage

```
plot_CV(
  x,
  freq = FALSE,
  rm0 = FALSE,
  pc = FALSE,
  fill = TRUE,
  labels = TRUE,
  axis.size = 10,
  axis.x.angle = 45,
  cell.size = 2.5,
  signif = 2,
  ...
)

## Default S3 method:
plot_CV(
  x,
  freq = FALSE,
  rm0 = FALSE,
  pc = FALSE,
  fill = TRUE,
  labels = TRUE,
  axis.size = 10,
  axis.x.angle = 45,
  cell.size = 2.5,
  signif = 2,
  ...
)

## S3 method for class 'LDA'
plot_CV(
  x,
  freq = TRUE,
  rm0 = TRUE,
```

```

pc = TRUE,
fill = TRUE,
labels = TRUE,
axis.size = 10,
axis.x.angle = 45,
cell.size = 2.5,
signif = 2,
...
)

```

Arguments

x	a (cross-validation table) or an LDA object
freq	logical whether to display frequencies (within an actual class) or counts
rm0	logical whether to remove zeros
pc	logical whether to multiply proportion by 100, ie display percentages
fill	logical whether to fill cell according to count/freq
labels	logical whether to add text labels on cells
axis.size	numeric to adjust axis labels
axis.x.angle	numeric to rotate x-axis labels
cell.size	numeric to adjust text labels on cells
signif	numeric to round frequencies using signif
...	useless here

Value

a ggplot object

See Also

[LDA](#), [plot.LDA](#), and (pretty much the same) [plot_table](#).

Examples

```

h <- hearts %>%
  fgProcrustes(0.01) %>% coo_slide(ldk=2) %T>% stack %>%
  efourier(6, norm=FALSE) %>% LDA(~aut)

h %>% plot_CV()
h %>% plot_CV(freq=FALSE, rm0=FALSE, fill=FALSE)
# you can customize the returned gg with some ggplot2 functions
h %>% plot_CV(labels=FALSE, fill=TRUE, axis.size=5) + ggplot2::ggtitle("A confusion matrix")

# or build your own using the prepared data_frame:
df <- h %>% plot_CV() %$% data
df

```



```
# you can even use it as a cross-table plotter
bot$fac %>% table %>% plot_CV()
```

plot_CV2	<i>Plots a cross-correlation table</i>
----------	--

Description

Or any contingency/confusion table. A simple graphic representation based on variable width and/or color for arrows or segments, based on the relative frequencies.

Usage

```
plot_CV2(x, ...)

## S3 method for class 'LDA'
plot_CV2(x, ...)

## S3 method for class 'table'
plot_CV2(
  x,
  links.FUN = arrows,
  col = TRUE,
  col0 = "black",
  col.breaks = 5,
  palette = col_heat,
  lwd = TRUE,
  lwd0 = 5,
  gap.dots = 0.2,
  pch.dots = 20,
  gap.names = 0.25,
  cex.names = 1,
  legend = TRUE,
  ...
)
```

Arguments

x	an LDA object, a table or a squared matrix
...	useless here.
links.FUN	a function to draw the links: eg segments (by default), arrows , etc.
col	logical whether to vary the color of the links
col0	a color for the default link (when col = FALSE)
col.breaks	the number of different colors
palette	a color palette, eg col_summer , col_hot , etc.

lwd	logical whether to vary the width of the links
lwd0	a width for the default link (when lwd = FALSE)
gap.dots	numeric to set space between the dots and the links
pch.dots	a pch for the dots
gap.names	numeric to set the space between the dots and the group names
cex.names	a cex for the names
legend	logical whether to add a legend

Note

When freq=FALSE, the fill colors are not weighted within actual classes and should not be displayed if classes sizes are not balanced.

See Also

[LDA](#), [plot.LDA](#), [plot_CV](#).

Examples

```
# Below various table that you can try. We will use the last one for the examples.
## Not run:
#pure random
a <- sample(rep(letters[1:4], each=10))
b <- sample(rep(letters[1:4], each=10))
tab <- table(a, b)

# veryhuge + some structure
a <- sample(rep(letters[1:10], each=10))
b <- sample(rep(letters[1:10], each=10))
tab <- table(a, b)
diag(tab) <- round(runif(10, 10, 20))

tab <- matrix(c(8, 3, 1, 0, 0,
               2, 7, 1, 2, 3,
               3, 5, 9, 1, 1,
               1, 1, 2, 7, 1,
               0, 9, 1, 4, 5), 5, 5, byrow=TRUE)
tab <- as.table(tab)

## End(Not run)
# good prediction
tab <- matrix(c(8, 1, 1, 0, 0,
               1, 7, 1, 0, 0,
               1, 2, 9, 1, 0,
               1, 1, 1, 7, 1,
               0, 0, 0, 1, 8), 5, 5, byrow=TRUE)
tab <- as.table(tab)

plot_CV2(tab)
```

```

plot_CV2(tab, arrows) # if you prefer arrows
plot_CV2(tab, lwd=FALSE, lwd0=1, palette=col_india) # if you like india but not lwds
plot_CV2(tab, col=FALSE, col0='pink') # only lwd
plot_CV2(tab, col=FALSE, lwd0=10, cex.names=2) # if you're getting old
plot_CV2(tab, col=FALSE, lwd=FALSE) # pretty but useless
plot_CV2(tab, col.breaks=2) # if you think it's either good or bad
plot_CV2(tab, pch=NA) # if you do not like dots
plot_CV2(tab, gap.dots=0) # if you want to 'fill the gap'
plot_CV2(tab, gap.dots=1) # or not

#trilo examples
trilo.f <- efourier(trilo, 8)
trilo.l <- LDA(PCA(trilo.f), 'onto')
trilo.l
plot_CV2(trilo.l)

# olea example
op <- opoly(olea, 5)
opl <- LDA(PCA(op), 'var')
plot_CV2(opl)

```

plot_devsegments

Draws colored segments from a matrix of coordinates.

Description

Given a matrix of (x; y) coordinates, draws segments between every points defined by the row of the matrix and uses a color to display an information.

Usage

```
plot_devsegments(coo, cols, lwd = 1)
```

Arguments

coo	A matrix of coordinates.
cols	A vector of color of length = nrow(coo).
lwd	The lwd to use for drawing segments.

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_table\(\)](#)

Examples

```

# we load some data
guinness <- coo_sample(bot[9], 100)

# we calculate the diff between 48 harm and one with 6 harm.
out.6 <- efourier_i(efourier(guinness, nb.h=6), nb.pts=120)

# we calculate deviations, you can also try 'edm'
dev <- edm_nearest(out.6, guinness) / coo_centsize(out.6)

# we prepare the color scale
d.cut <- cut(dev, breaks=20, labels=FALSE, include.lowest=TRUE)
cols <- paste0(col_summer(20)[d.cut], 'CC')

# we draw the results
coo_plot(guinness, main='Guinness fitted with 6 harm.', points=FALSE)
par(xpd=NA)
plot_devsegments(out.6, cols=cols, lwd=4)
coo_draw(out.6, lty=2, points=FALSE, col=NA)
par(xpd=FALSE)

```

plot_LDA

LDA plot using grindr layers

Description

Quickly visualize [LDA](#) objects and build custom plots using the [layers](#). See examples.

Usage

```

plot_LDA(
  x,
  axes = c(1, 2),
  palette = pal_qual,
  points = TRUE,
  points_transp = 1/4,
  morphospace = FALSE,
  morphospace_position = "range",
  chull = TRUE,
  chullfilled = FALSE,
  labelgroups = FALSE,
  legend = TRUE,
  title = "",
  center_origin = TRUE,
  zoom = 0.9,
  eigen = TRUE,
  box = TRUE,

```

```

    iftwo_layer = layer_histogram_2,
    iftwo_split = FALSE,
    axesnames = TRUE,
    axesvar = TRUE
  )

```

Arguments

x	LDA object
axes	numeric of length two to select PCs to use (c(1, 2) by default)
palette	color palette to use col_summer by default
points	logical whether to draw this with layer_points
points_transp	numeric to feed layer_points (default:0.25)
morphospace	logical whether to draw this using layer_morphospace_PCA
morphospace_position	to feed layer_morphospace_PCA (default: "range")
chull	logical whether to draw this with layer_chull
chullfilled	logical whether to draw this with layer_chullfilled
labelgroups	logical whether to draw this with layer_labelgroups
legend	logical whether to draw this with layer_legend
title	character if specified, fee layer_title (default to "")
center_origin	logical whether to center origin
zoom	numeric zoom level for the frame (default: 0.9)
eigen	logical whether to draw this using layer_eigen
box	logical whether to draw this using layer_box
iftwo_layer	function (no quotes) for drawing LD1 when there are two levels. So far, one of layer_histogram_2 (default) or layer_density_2
iftwo_split	to feed split argument in layer_histogram_2 or layer_density_2
axesnames	logical whether to draw this using layer_axesnames
axesvar	logical whether to draw this using layer_axesvar

Note

This approach will replace [plot.LDA](#). This is part of [grindr](#) approach that may be packaged at some point. All comments are welcome.

See Also

Other [grindr](#): [drawers](#), [layers_morphospace](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [pile\(\)](#), [plot_NMDS\(\)](#), [plot_PCA\(\)](#)

Examples

```

### First prepare an LDA object

# Some outlines with bot
bl <- bot %>%
  # cheap alignment before efourier
  coo_align() %>% coo_center %>% coo_slidedirection("left") %>%
  # add a fake column
  mutate(fake=sample(letters[1:5], 40, replace=TRUE)) %>%
  # EFT
  efourier(6, norm=FALSE) %>%
  # LDA
  LDA(~fake)

bl %>% plot_LDA %>% layer_morphospace_LDA

# Below inherited from plot_PCA and to adapt here.
#plot_PCA(bp)
#plot_PCA(bp, ~type)
#plot_PCA(bp, ~fake)

# Some curves with olea
#op <- olea %>%
#mutate(s=coo_area(.)) %>%
#filter(var != "Cypre") %>%
#chop(~view) %>% lapply(opoly, 5, nb.pts=90) %>%
#combine %>% PCA
#op$fac$s %<>% as.character() %>% as.numeric()

#op %>% plot_PCA(title="hi there!")

### Now we can play with layers
# and for instance build a custom plot
# it should start with plot_PCA()

#my_plot <- function(x, ...){

#x %>%
#  plot_PCA(...) %>%
#  layer_points %>%
#  layer_ellipsesaxes %>%
#  layer_rug
# }

# and even continue after this function
# op %>% my_plot(~var, axes=c(1, 3)) %>%
#  layer_title("hi there!") %>%
#  layer_stars()

# You get the idea.

```

plot_MSHAPES *Pairwise comparison of a list of shapes*

Description

"Confusion matrix" of a list of shapes. See examples.

Usage

```
plot_MSHAPES(x, draw_fun, size, palette)
```

Arguments

x	a list of shapes (eg as returned by MSHAPES)
draw_fun	one of draw_outline , draw_curves , draw_landmarks . When the result of MSHAPES is passed, detected based on \$Coe, otherwise default to draw_curves .
size	numeric shrinking factor for shapes (and coo_template ; 3/4 by default)
palette	on of palettes

Note

Directly inspired by Chitwood et al. (2016) in *New Phytologist*

Examples

```
x <- bot %>% efourier(6) %>% MSHAPES(~type)

# custom colors
x %>% plot_MSHAPES(palette=pal_manual(c("darkgreen", "orange")))

# also works on list of shapes, eg:
leaves <- shapes %>% slice(grep("leaf", names(shapes))) %>% coo
class(leaves)
leaves %>% plot_MSHAPES()

# or
shapes %>%
# subset and degrade
slice(1:12) %>% coo_sample(60) %>% # grab the coo
  coo %>%
  plot_MSHAPES()
```

`plot_NMDS`*NMDS plot using `grindr` layers*

Description

Quickly visualize [MDS](#) and [NMDS](#) objects and build custom plots using the [layers](#). See examples.

Usage

```
plot_NMDS(  
  x,  
  f = NULL,  
  axes = c(1, 2),  
  points = TRUE,  
  points_transp = 1/4,  
  chull = TRUE,  
  chullfilled = FALSE,  
  labelgroups = FALSE,  
  legend = TRUE,  
  title = "",  
  box = TRUE,  
  axesnames = TRUE,  
  palette = pal_qual  
)
```

```
plot_MDS(  
  x,  
  f = NULL,  
  axes = c(1, 2),  
  points = TRUE,  
  points_transp = 1/4,  
  chull = TRUE,  
  chullfilled = FALSE,  
  labelgroups = FALSE,  
  legend = TRUE,  
  title = "",  
  box = TRUE,  
  axesnames = TRUE,  
  palette = pal_qual  
)
```

Arguments

<code>x</code>	the result of MDS or NMDS
<code>f</code>	factor specification to feed fac_dispatcher
<code>axes</code>	numeric of length two to select PCs to use (c(1, 2) by default)

points	logical whether to draw this with layer_points
points_transp	numeric to feed layer_points (default:0.25)
chull	logical whether to draw this with layer_chull
chullfilled	logical whether to draw this with layer_chullfilled
labelgroups	logical whether to draw this with layer_labelgroups
legend	logical whether to draw this with layer_legend
title	character if specified, fee layer_title (default to "")
box	logical whether to draw this using layer_box
axesnames	logical whether to draw this using layer_axesnames
palette	color palette to use col_summer by default

See Also

Other grindr: [drawers](#), [layers_morphospace](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_PCA\(\)](#)

Examples

```
### First prepare an NMDS object
x <- bot %>% efourier %>% NMDS

plot_NMDS(x)
plot_NMDS(x, ~type) %>% layer_stars() %>% layer_labelpoints()

### Same on MDS object
x <- bot %>% efourier %>% MDS

plot_MDS(x)
plot_MDS(x, ~type) %>% layer_stars() %>% layer_labelpoints()
```

plot_PCA

PCA plot using grindr layers

Description

Quickly visualize [PCA](#) objects and friends and build custom plots using the [layers](#). See examples.

Usage

```
plot_PCA(
  x,
  f = NULL,
  axes = c(1, 2),
  palette = NULL,
  points = TRUE,
```

```

points_transp = 1/4,
morphospace = TRUE,
morphospace_position = "range",
chull = TRUE,
chullfilled = FALSE,
labelpoints = FALSE,
labelgroups = FALSE,
legend = TRUE,
title = "",
center_origin = TRUE,
zoom = 0.9,
eigen = TRUE,
box = TRUE,
axesnames = TRUE,
axesvar = TRUE
)

```

Arguments

x	a PCA object
f	factor specification to feed fac_dispatcher
axes	numeric of length two to select PCs to use (c(1, 2) by default)
palette	color palette to use col_summer by default
points	logical whether to draw this with layer_points
points_transp	numeric to feed layer_points (default:0.25)
morphospace	logical whether to draw this using layer_morphospace_PCA
morphospace_position	to feed layer_morphospace_PCA (default: "range")
chull	logical whether to draw this with layer_chull
chullfilled	logical whether to draw this with layer_chullfilled
labelpoints	logical whether to draw this with layer_labelpoints
labelgroups	logical whether to draw this with layer_labelgroups
legend	logical whether to draw this with layer_legend
title	character if specified, fee layer_title (default to "")
center_origin	logical whether to center origin
zoom	numeric zoom level for the frame (default: 0.9)
eigen	logical whether to draw this using layer_eigen
box	logical whether to draw this using layer_box
axesnames	logical whether to draw this using layer_axesnames
axesvar	logical whether to draw this using layer_axesvar

Note

This approach will replace [plot.PCA](#) (and `plot.lda` in further versions. This is part of `grindr` approach that may be packaged at some point. All comments are welcome.

See Also

Other grindr: [drawers](#), [layers_morphospace](#), [layers](#), [mosaic_engine\(\)](#), [papers](#), [pile\(\)](#), [plot_LDA\(\)](#), [plot_NMDS\(\)](#)

Examples

```
### First prepare two PCA objects.

# Some outlines with bot
bp <- bot %>% mutate(fake=sample(letters[1:5], 40, replace=TRUE)) %>%
efourier(6) %>% PCA
plot_PCA(bp)
plot_PCA(bp, ~type)
plot_PCA(bp, ~fake)

# Some curves with olea
op <- olea %>%
mutate(s=coo_area()) %>%
filter(var != "Cypre") %>%
chop(~view) %>% opoly(5, nb.pts=90) %>%
combine %>% PCA
op$fac$s %<>% as.character() %>% as.numeric()

op %>% plot_PCA(title="hi there!")

### Now we can play with layers
# and for instance build a custom plot
# it should start with plot_PCA()

my_plot <- function(x, ...){
  x %>%
    plot_PCA(...) %>%
    layer_points %>%
    layer_ellipsesaxes %>%
    layer_rug
}

# and even continue after this function
op %>% my_plot(~var, axes=c(1, 3)) %>%
  layer_title("hi there!")

# grindr allows (almost nice) tricks like highlighting:

# bp %>% .layerize_PCA(~fake) %>%
#   layer_frame %>% layer_axes() %>%
#   layer_morphospace_PCA() -> x

# highlight <- function(x, ..., col_F="#CCCCCC", col_T="#FC8D62FF"){
#   args <- list(...)
#   x$colors_groups <- c(col_F, col_T)
#   x$colors_rows <- c(col_F, col_T)[(x$f %in% args)+1]
```

```
# x
# }
# x %>% highlight("a", "b") %>% layer_points()

# You get the idea.
```

plot_silhouette	<i>Silhouette plot</i>
-----------------	------------------------

Description

Only used, so far, after [KMEDOIDS](#).

Usage

```
plot_silhouette(x, palette = pal_qual)
```

Arguments

x	object returned by KMEDOIDS
palette	one of palettes

Value

a ggplot plot

Examples

```
olea %>% opoly(5) %>%
  KMEDOIDS(4) %>%
  plot_silhouette(pal_qual_solarized)
```

plot_table	<i>Plots confusion matrix of sample sizes within \$fac</i>
------------	--

Description

An utility that plots a confusion matrix of sample size (or a barplot) for every object with a \$fac. Useful to visually how large are sample sizes, how (un)balanced are designs, etc.

Usage

```
plot_table(x, fac1, fac2 = fac1, rm0 = FALSE)
```

Arguments

x	any object with a \$fac slot (Coo, Coe, PCA, etc.)
fac1	the name or id of the first factor
fac2	the name of id of the second factor
rm0	logical whether to print zeros

Value

a ggplot2 object

See Also

Other plotting functions: [coo_arrows\(\)](#), [coo_draw\(\)](#), [coo_listpanel\(\)](#), [coo_lolli\(\)](#), [coo_plot\(\)](#), [coo_ruban\(\)](#), [ldk_chull\(\)](#), [ldk_confell\(\)](#), [ldk_contour\(\)](#), [ldk_labels\(\)](#), [ldk_links\(\)](#), [plot_devsegments\(\)](#)

Examples

```
plot_table(olea, "var")
plot_table(olea, "domes", "var")
gg <- plot_table(olea, "domes", "var", rm0 = TRUE)
gg
library(ggplot2)
gg + coord_equal()
gg + scale_fill_gradient(low="green", high = "red")
gg + coord_flip()
```

pProcrustes

Partial Procrustes alignment between two shapes

Description

Directly borrowed from Claude (2008), and called pPsup there.

Usage

```
pProcrustes(coo1, coo2)
```

Arguments

coo1	Configuration matrix to be superimposed onto the centered preshape of coo2.
coo2	Reference configuration matrix.

Value

a list with components

- `coo1` superimposed centered preshape of `coo1` onto the centered preshape of `coo2`
- `coo2` centered preshape of `coo2`
- `rotation` rotation matrix
- DP partial Procrustes distance between `coo1` and `coo2`
- rho trigonometric Procrustes distance.

References

Claude, J. (2008). Morphometrics with R. Analysis (p. 316). Springer.

See Also

Other procrustes functions: [fProcrustes\(\)](#), [fgProcrustes\(\)](#), [fgsProcrustes\(\)](#)

Ptolemy

Ptolemaic ellipses and illustration of efourier

Description

Calculate and display Ptolemaic ellipses which illustrates intuitively the principle behind elliptical Fourier analysis.

Usage

```
Ptolemy(
  coo,
  t = seq(0, 2 * pi, length = 7)[-1],
  nb.h = 3,
  nb.pts = 360,
  palette = col_heat,
  zoom = 5/4,
  legend = TRUE,
  ...
)
```

Arguments

<code>coo</code>	a matrix of (x; y) coordinates
<code>t</code>	A vector of angles (in radians) on which to display ellipses
<code>nb.h</code>	integer. The number of harmonics to display
<code>nb.pts</code>	integer. The number of points to use to display shapes
<code>palette</code>	a color palette

zoom numeric a zoom factor for [coo_plot](#)
 legend logical. Whether to plot the legend box
 ... additional parameters to feed [coo_plot](#)

References

This method has been inspired by the figures found in the followings papers. Kuhl FP, Giardina CR. 1982. Elliptic Fourier features of a closed contour. *Computer Graphics and Image Processing* **18**: 236-258. Crampton JS. 1995. Elliptical Fourier shape analysis of fossil bivalves: some practical considerations. *Lethaia* **28**: 179-186.

See Also

An intuitive explanation of elliptic Fourier analysis can be found in the **Details** section of the [efourier](#) function.

[exemplifying functions](#)

Examples

```
cat <- shapes[4]
Ptolemy(cat, main="An EFT cat")
```

rearrange_ldk	<i>Rearrange, (select and reorder) landmarks to retain</i>
---------------	--

Description

Helps reorder and retain landmarks by simply changing the order in which they are recorded in the Coo objects. Note that for Out and Opn objects, this rearranges the \$ldk component. For Ldk, it rearranges the \$coo directly.

Usage

```
rearrange_ldk(Coo, new_ldk_ids)
```

Arguments

Coo any appropriate Coo object (typically an Ldk) with landmarks inside
 new_ldk_ids a vector of numeric with the ldk to retain *and* in the right order (see below)

See Also

Other ldk/slidings methods: [add_ldk\(\)](#), [def_ldk\(\)](#), [def_slidings\(\)](#), [get_ldk\(\)](#), [get_slidings\(\)](#), [slidings_scheme\(\)](#)

Examples

```
# Out example
hearts %>% slice(1) %T>% stack %$$ ldk
hearts %>% rearrange_ldk(c(4, 1)) %>%
  slice(1) %T>%stack %$$ ldk

# Ldk example
wings %>% slice(1) %T>% stack %$$ coo
wings %>% rearrange_ldk(c(1, 3, 12:15)) %>%
  slice(1) %T>% stack %$$ coo
```

```
reLDA           "Redo" a LDA on new data
```

Description

Basically a wrapper around [predict.lda](#) from the package MASS. Uses a LDA model to classify new data.

Usage

```
reLDA(newdata, LDA)

## Default S3 method:
reLDA(newdata, LDA)

## S3 method for class 'PCA'
reLDA(newdata, LDA)

## S3 method for class 'Coe'
reLDA(newdata, LDA)
```

Arguments

```
newdata      to use, a PCA or any Coe object
LDA          a LDA object
```

Value

a list with components (from `?predict.lda`).

- class factor of classification
- posterior posterior probabilities for the classes
- x the scores of test cases
- res data.frame of the results
- CV.tab a confusion matrix of the results
- CV.correct proportion of the diagonal of CV.tab
- newdata the data used to calculate passed to predict.lda

Note

Uses the same number of PC axis as the LDA object provided. You should probably use [rePCA](#) in conjunction with [reLDA](#) to get 'homologous' scores.

Examples

```
# We select the first 10 individuals in bot,
# for whisky and beer bottles. It will be our referential.
bot1 <- slice(bot, c(1:10, 21:30))
# Same thing for the other 10 individuals.
# It will be our unknown dataset on which we want
# to calculate classes.
bot2 <- slice(bot, c(11:20, 31:40))

# We calculate efourier on these two datasets
bot1.f <- efourier(bot1, 8)
bot2.f <- efourier(bot2, 8)

# Here we obtain our LDA model: first, a PCA, then a LDA
bot1.p <- PCA(bot1.f)
bot1.l <- LDA(bot1.p, "type")

# we redo the same PCA since we worked with scores
bot2.p <- rePCA(bot1.p, bot2.f)

# we finally "predict" with the model obtained before
bot2.l <- reLDA(bot2.p, bot1.l)
bot2.l
```

 rename

Rename columns by name

Description

Rename variables, from the \$fac. See examples and [dplyr::rename](#).

Usage

```
rename(.data, ...)
```

Arguments

.data	a Coe, Coe, PCA object
...	comma separated list of unquoted expressions

Details

dplyr verbs are maintained.

Value

a Momocs object of the same class.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea
rename(olea, variety=var, domesticated=domes) # rename var column
```

rePCA

"Redo" a PCA on a new Coe

Description

Basically reapply rotation to a new Coe object.

Usage

```
rePCA(PCA, Coe)
```

Arguments

PCA	a PCA object
Coe	a Coe object

Note

Quite experimental. Dimensions of the matrices and methods must match.

Examples

```
b <- filter(bot, type=="beer")
w <- filter(bot, type=="whisky")

bf <- efourier(b, 8)
bp <- PCA(bf)

wf <- efourier(w, 8)

# and we use the "beer" PCA on the whisky coefficients
wp <- rePCA(bp, wf)

plot(wp)
```

```
plot(bp, eig=FALSE)
points(wp$x[, 1:2], col="red", pch=4)
```

rescale

Rescale coordinates from pixels to real length units

Description

Most of the time, (x, y) coordinates are recorded in pixels. If we want to have them in mm, cm, etc. we need to convert them and to rescale them. This functions does the job for the two cases: i) either an homogeneous rescaling factor, e.g. if all pictures were taken using the very same magnification or ii) with various magnifications. More in the Details section

Usage

```
rescale(x, scaling_factor, scale_mapping, magnification_col, ...)
```

Arguments

x	any Coo object
scaling_factor	numeric an homogeneous scaling factor. If all you (x, y) coordinates have the same scale
scale_mapping	either a data.frame or a path to read such a data.frame. It MUST contain three columns in that order: magnification found in \$fac, column "magnification_col", pixels, real length unit. Column names do not matter but must be specified, as read.table reads with header=TRUE Every different magnification level found in \$fac, column "magnification_col" must have its row.
magnification_col	the name or id of the \$fac column to look for magnification levels for every image
...	additional arguments (besides header=TRUE) to pass to read.table if 'scale_mapping' is a path

Details

The i) case above is straightforward, if 1cm is 500pix long on all your pictures, just call `rescale(your_Coo, scaling_factor=1/500)` and all coordinates will be in cm.

The ii) second case is more subtle. First you need to code in your `/linkCoo` object, in the `fac` slot, a column named, say "mag", for magnification. Imagine you have 4 magnifications: 0.5, 1, 2 and 5, we have to indicate for each magnification, how many pixels stands for how many units in the real world.

This information is passed as a data.frame, built externally or in R, that must look like this:

```

mag  pix  cm
0.5  1304  10
1    921   10
2    816   5
5    1020  5

```

.

We have to do that because, for optical reasons, the ratio `pix/real_unit`, is not a linear function of the magnification.

All shapes will be centered to apply (the single or the different) `scaling_factor`.

Note

This function is simple but quite complex to detail. Feel free to contact me should you have any problem with it. You can just access its code (type `rescale`) and reply it yourself.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

rfourier

Radii variation Fourier transform (equally spaced radii)

Description

`rfourier` computes radii variation Fourier analysis from a matrix or a list of coordinates where points are equally spaced radii.

Usage

```

rfourier(x, ...)

## Default S3 method:
rfourier(x, nb.h, smooth.it = 0, norm = FALSE, ...)

## S3 method for class 'Out'
rfourier(x, nb.h = 40, smooth.it = 0, norm = TRUE, thres = pi/90, ...)

## S3 method for class 'list'
rfourier(x, ...)

```

Arguments

x	A list or matrix of coordinates or an Out object
...	useless here
nb.h	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.
smooth.it	integer. The number of smoothing iterations to perform.
norm	logical. Whether to scale the outlines so that the mean length of the radii used equals 1.
thres	numeric a tolerance to feed is_equallyspacedradii

Details

see the JSS paper for the maths behind. The methods for Out objects tests if coordinates have equally spaced radii using [is_equallyspacedradii](#). A message is printed if this is not the case.

Value

A list with following components:

- an vector of $a_{1 \rightarrow n}$ harmonic coefficients
- bn vector of $b_{1 \rightarrow n}$ harmonic coefficients
- ao ao harmonic coefficient.
- r vector of radii lengths.

Note

Silent message and progress bars (if any) with options("verbose"=FALSE).
Directly borrowed for Claude (2008), and called `fourier1` there.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other rfourier: [rfourier_i\(\)](#), [rfourier_shape\(\)](#)

Examples

```
data(bot)
coo <- coo_center(bot[1]) # centering is almost mandatory for rfourier family
coo_plot(coo)
rf <- rfourier(coo, 12)
rf
rfi <- rfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

# Out method
bot %>% rfourier()
```

`rfourier_i`*Inverse radii variation Fourier transform*

Description

`rfourier_i` uses the inverse radii variation (equally spaced radii) transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with `rfourier`.

Usage

```
rfourier_i(rf, nb.h, nb.pts = 120)
```

Arguments

<code>rf</code>	A list with <code>ao</code> , <code>an</code> and <code>bn</code> components, typically as returned by <code>rfourier</code> .
<code>nb.h</code>	integer. The number of harmonics to calculate/use.
<code>nb.pts</code>	integer. The number of points to calculate.

Details

See the JSS paper for the maths behind.

Value

A list with components:

<code>x</code>	vector of x-coordinates.
<code>y</code>	vector of y-coordinates.
<code>angle</code>	vector of angles used.
<code>r</code>	vector of radii calculated.

Note

Directly borrowed for Claude (2008), and called `ifourier1` there.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other `rfourier`: `rfourier_shape()`, `rfourier()`

Examples

```

data(bot)
coo <- coo_center(bot[1]) # centering is almost mandatory for rfourier family
coo_plot(coo)
rf <- rfourier(coo, 12)
rf
rfi <- rfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

```

rfourier_shape	<i>Calculates and draw 'rfourier' shapes.</i>
----------------	---

Description

rfourier_shape calculates a 'Fourier radii variation shape' given Fourier coefficients (see [Details](#)) or can generate some 'rfourier' shapes.

Usage

```
rfourier_shape(an, bn, nb.h, nb.pts = 80, alpha = 2, plot = TRUE)
```

Arguments

an	numeric. The a_n Fourier coefficients on which to calculate a shape.
bn	numeric. The b_n Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see Details).
plot	logical. Whether to plot or not the shape.

Details

rfourier_shape can be used by specifying nb.h and alpha. The coefficients are then sampled in an uniform distribution $(-\pi; \pi)$ and this amplitude is then divided by $harmonicrank^\alpha$. If alpha is lower than 1, consecutive coefficients will thus increase. See [rfourier](#) for the mathematical background.

Value

A matrix of (x; y) coordinates.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other rfourier: [rfourier_i\(\)](#), [rfourier\(\)](#)

Examples

```
data(bot)
rf <- rfourier(bot[1], 24)
rfourier_shape(rf$an, rf$bn) # equivalent to rfourier_i(rf)
rfourier_shape() # not very interesting

rfourier_shape(nb.h=12) # better
rfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)

# Butterflies of the vignette' cover
panel(Out(a2l(replicate(100,
rfourier_shape(nb.h=6, alpha=0.4, nb.pts=200, plot=FALSE))))))
```

 rm_asym

Removes asymmetric and symmetric variation on OutCoe objects

Description

Only for those obtained with [efourier](#), otherwise a message is returned. `rm_asym` sets all B and C coefficients to 0; `rm_sym` sets all A and D coefficients to 0.

Usage

```
rm_asym(OutCoe)

## Default S3 method:
rm_asym(OutCoe)

## S3 method for class 'OutCoe'
rm_asym(OutCoe)

rm_sym(OutCoe)

## Default S3 method:
rm_sym(OutCoe)

## S3 method for class 'OutCoe'
rm_sym(OutCoe)
```

Arguments

OutCoe an OutCoe object

Value

an OutCoe object

References

Below: the first mention, and two applications.

#'

- Iwata, H., Niikura, S., Matsuura, S., Takano, Y., & Ukai, Y. (1998). Evaluation of variation of root shape of Japanese radish (*Raphanus sativus* L.) based on image analysis using elliptic Fourier descriptors. *Euphytica*, 102, 143-149.
- Iwata, H., Nesumi, H., Ninomiya, S., Takano, Y., & Ukai, Y. (2002). The Evaluation of Genotype x Environment Interactions of Citrus Leaf Morphology Using Image Analysis and Elliptic Fourier Descriptors. *Breeding Science*, 52(2), 89-94. doi:10.1270/jsbbs.52.89
- Yoshioka, Y., Iwata, H., Ohsawa, R., & Ninomiya, S. (2004). Analysis of petal shape variation of *Primula sieboldii* by elliptic fourier descriptors and principal component analysis. *Annals of Botany*, 94(5), 657-64. doi:10.1093/aob/mch190

See Also

[symmetry](#) and the note there.

Examples

```
botf <- efourier(bot, 12)
botSym <- rm_asym(botf)
boxplot(botSym)
botSymp <- PCA(botSym)
plot(botSymp)
plot(botSymp, amp.shp=5)

# Asymmetric only
botAsym <- rm_sym(botf)
boxplot(botAsym)
botAsymp <- PCA(botAsym)
plot(botAsymp)
# strange shapes because the original shape was mainly symmetric and would need its
# symmetric (eg its average) for a proper reconstruction. Should only be used like that:
plot(botAsymp, morpho=FALSE)
```

rm_harm

Removes harmonics from Coe objects

Description

Useful to drop harmonics on Coe objects. Should only work for Fourier-based approaches since it looks for [A-D][1-drop] pattern.

Usage

```
rm_harm(x, drop = 1)
```

Arguments

x	Coe object
drop	numeric number of harmonics to drop

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
data(bot)
bf <- efourier(bot)
colnames(rm_harm(bf, 1)$coe)
```

rm_missing	<i>Remove shapes with missing data in fac</i>
------------	---

Description

Any row (or within a given column if by is specified) containing NA in \$fac and the corresponding shapes in \$coo, lines in \$coe or other objects will also be dropped.

Usage

```
rm_missing(x, by)
```

Arguments

x	the object on which to NA
by	which column of the \$fac should objects have complete views

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```

bot$fac$type[3] <- NA
bot$fac$fake[9] <- NA

bot %>% length()
bot %>% rm_missing() %>% length
bot %>% rm_missing("fake") %>% length()

```

rm_uncomplete	<i>Remove shapes with incomplete slices</i>
---------------	---

Description

Imagine you take three views of every object you study. Then, you can [slice](#), [filter](#) or [chop](#) your entire dataset, do morphometrics on it, then want to [combine](#) it. But if you have forgotten one view, or if it was impossible to obtain, for one or more objects, combine will not work. This function helps you to remove those ugly ducklings. See examples

Usage

```
rm_uncomplete(x, id, by)
```

Arguments

x	the object on which to remove uncomplete "by"
id	of the objects, within the \$fac slot
by	which column of the \$fac should objects have complete views

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```

# we load olea
data(olea)
# we select the var Aglan since it is the only one complete
ol <- filter(olea, var == "Aglan")
# everything seems fine
table(ol$view, ol$ind)
# indeed
rm_uncomplete(ol, id="ind", by="view")

# we mess the ol object by removing a single shape
ol.pb <- slice(ol, -1)
table(ol.pb$view, ol.pb$ind)

```

```
# the counterpart has been removed with a notice
ol.ok <- rm_uncomplete(ol.pb, "ind", "view")
# now you can combine them
table(ol.ok$view, ol.ok$ind)
```

 rw_fac

Renames levels on Momocs objects

Description

rw_fac stands for 'rewriting rule'. Typically useful to correct typos at the import, or merge some levels within covariates. Drops levels silently.

Usage

```
rw_fac(x, fac, from, to)
```

Arguments

x	any Momocs object
fac	the id of the name of the \$fac column to look for (fac_dispatcher not yet supported)
from	which level(s) should be renamed; passed as a single or several characters
to	which name should be used to rename this/these levels

Value

a Momocs object of the same type

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
# single renaming
rw_fac(bot, "type", "whisky", "agua_de_fuego")$type # 1 instead of "type" is fine too
# several renaming
bot2 <- mutate(bot, fake=factor(rep(letters[1:4], 10)))
rw_fac(bot2, "fake", c("a", "e"), "ae")$fake
```

sample_frac	<i>Sample a fraction of shapes</i>
-------------	------------------------------------

Description

Sample a fraction of shapes from a Momocs object. See examples and `?dplyr::sample_n`.

Usage

```
sample_frac(tbl, size, replace, fac, ...)
```

Arguments

tbl	a Momocs object (Coo, Coe)
size	numeric (0 < numeric <= 1) the fraction of shapes to select
replace	logical whether sample should be done with or without replacement
fac	a column name if a <code>\$fac</code> is defined; size is then applied within levels of this factor
...	additional arguments to <code>dplyr::sample_frac</code> and to maintain generic compatibility

Note

the resulting fraction is rounded with [ceiling](#).

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
# samples 50% of the bottles no matter their type
sample_frac(bot, 0.5)
# 80% bottles of beer and of whisky
table(sample_frac(bot, 0.8, fac="type")$fac)
# bootstrap the same number of bootles of each type but with replacement
table(names(sample_frac(bot, 1, replace=TRUE)))
```

sample_n	<i>Sample n shapes</i>
----------	------------------------

Description

Sample n shapes from a Momocs object. See examples and `?dplyr::sample_n`.

Usage

```
sample_n(tbl, size, replace, fac, ...)
```

Arguments

tbl	a Momocs object (Coo, Coe)
size	numeric how many shapes should we sample
replace	logical whether sample should be done with or without replacement
fac	a column name if a \$fac is defined; size is then applied within levels of this factor
...	additional arguments to <code>dplyr::sample_n</code> and to maintain generic compatibility

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [select\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
# samples 5 bottles no matter their type
sample_n(bot, 5)
# 5 bottles of beer and of whisky
table(sample_n(bot, 5, fac="type")$type)
# many repetitions
table(names(sample_n(bot, 400, replace=TRUE)))
```

scree	<i>How many axes to retain this much of variance or trace ?</i>
-------	---

Description

A set of functions around PCA/LDA eigen/trace. `scree` calculates their proportion and cumulated proportion; `scree_min` returns the minimal number of axis to use to retain a given proportion; `scree_plot` displays a screeplot.

Usage

```
scree(x, nax)

## S3 method for class 'PCA'
scree(x, nax)

## S3 method for class 'LDA'
scree(x, nax)

scree_min(x, prop)

scree_plot(x, nax)
```

Arguments

<code>x</code>	a PCA object
<code>nax</code>	numeric range of axes to consider. All by default for <code>scree_min</code> , display until 0.99 for <code>scree_plot</code>
<code>prop</code>	numeric how many axes are enough to gather this proportion of variance. Default to 1, all axes are returned default to 1: all axis are returned

Value

`scree` returns a data.frame, `scree_min` a numeric, `scree_plot` a ggplot.

Examples

```
# On PCA
bp <- PCA(efourier(bot))
scree(bp)
scree_min(bp, 0.99)
scree_min(bp, 1)

scree_plot(bp)
scree_plot(bp, 1:5)

# on LDA, it uses svd
bl <- LDA(PCA(opoly(olea)), "var")
```

```
scree(bl)
```

```
select          Select columns by name
```

Description

Select variables by name, from the \$fac. Selected variables can also be renamed on the fly. See examples and `?dplyr::select`.

Usage

```
select(.data, ...)
```

Arguments

<code>.data</code>	a Coe, Coe, PCA object
<code>...</code>	comma separated list of unquoted expressions

Details

dplyr verbs are maintained.

Value

a Momocs object of the same class.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [slice\(\)](#), [subsetize\(\)](#)

Examples

```
olea
select(olea, var, view) # drops domes and ind
select(olea, variety=var, domesticated_status=domes, view)
# combine with filter with magrittr pipes
# only dorsal views, and 'var' and 'domes' columns
filter(olea, view=="VD") %>% select(var, domes)
head(olea$fac)
# select some columns
select(olea, domes, view)
# remove some columns
select(olea, -ind)
# rename on the fly and select some columns
select(olea, foo=domes)
```

sfourier	<i>Radii variation Fourier transform (equally spaced curvilinear abscissa)</i>
----------	--

Description

sfourier computes radii variation Fourier analysis from a matrix or a list of coordinates where points are equally spaced along the curvilinear abscissa.

Usage

```
sfourier(x, nb.h)

## Default S3 method:
sfourier(x, nb.h)

## S3 method for class 'Out'
sfourier(x, nb.h)

## S3 method for class 'list'
sfourier(x, nb.h)
```

Arguments

x	A list or matrix of coordinates or an Out object
nb.h	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.

Value

A list with following components:

- an vector of $a_{1 \rightarrow n}$ harmonic coefficients
- bn vector of $b_{1 \rightarrow n}$ harmonic coefficients
- ao ao harmonic coefficient
- r vector of radii lengths

Note

The implementation is still quite experimental (as of Dec. 2016)

References

Renaud S, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

See Also

Other sfourier: [sfourier_i\(\)](#), [sfourier_shape\(\)](#)

Examples

```
molars[4] %>%
  coo_center %>% coo_scale %>% coo_interpolate(1080) %>%
  coo_slidedirection("right") %>%
  coo_sample(360) %T>% coo_plot(zoom=2) %>%
  sfourier(16) %>%
  sfourier_i() %>%
  coo_draw(bor="red", points=TRUE)
```

 sfourier_i

Inverse radii variation Fourier transform

Description

sfourier_i uses the inverse radii variation (equally spaced curvilinear abscissa) transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [sfourier](#).

Usage

```
sfourier_i(rf, nb.h, nb.pts = 120, dtheta = FALSE)
```

Arguments

rf	A list with ao, an and bn components, typically as returned by sfourier.
nb.h	integer. The number of harmonics to calculate/use.
nb.pts	integer. The number of points to calculate.
dtheta	logical. Whether to use the dtheta correction method. FALSE by default. When TRUE, tries to correct the angular difference between reconstructed points; otherwise equal angles are used.

Value

A list with components:

x	vector of x-coordinates.
y	vector of y-coordinates.
angle	vector of angles used.
r	vector of radii calculated.

References

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

See Also

Other sfourier: [sfourier_shape\(\)](#), [sfourier\(\)](#)

Examples

```

coo <- coo_center(bot[1]) # centering is almost mandatory for sfourier family
coo_plot(coo)
rf <- sfourier(coo, 12)
rf
rfi <- sfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

```

sfourier_shape	<i>Calculates and draw 'sfourier' shapes.</i>
----------------	---

Description

`sfourier_shape` calculates a 'Fourier radii variation shape' given Fourier coefficients (see [Details](#)) or can generate some 'sfourier' shapes.

Usage

```
sfourier_shape(an, bn, nb.h, nb.pts = 80, alpha = 2, plot = TRUE)
```

Arguments

an	numeric. The a_n Fourier coefficients on which to calculate a shape.
bn	numeric. The b_n Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see Details).
plot	logical. Whether to plot or not the shape.

Details

`sfourier_shape` can be used by specifying `nb.h` and `alpha`. The coefficients are then sampled in an uniform distribution $(-\pi; \pi)$ and this amplitude is then divided by $harmonicrank^\alpha$. If `alpha` is lower than 1, consecutive coefficients will thus increase. See [sfourier](#) for the mathematical background.

Value

A matrix of (x; y) coordinates.

References

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

See Also

Other sfourier: [sfourier_i\(\)](#), [sfourier\(\)](#)

Examples

```
rf <- sfourier(bot[1], 24)
sfourier_shape(rf$an, rf$bn) # equivalent to sfourier_i(rf)
sfourier_shape() # not very interesting

sfourier_shape(nb.h=12) # better
sfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)

# Butterflies of the vignette' cover
panel(Out(a2l(replicate(100,
sfourier_shape(nb.h=6, alpha=0.4, nb.pts=200, plot=FALSE))))))
```

shapes

Data: Outline coordinates of various shapes

Description

Data: Outline coordinates of various shapes

Format

An [Out](#) object with the outline coordinates of some various shapes.

Source

Borrowed default shapes from (c) Adobe Photoshop. Do not send me to jail.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [trilo](#), [wings](#)

slice	<i>Subset based on positions</i>
-------	----------------------------------

Description

Select rows by position, based on `$fac`. See examples and `?dplyr::slice`.

Usage

```
slice(.data, ...)
```

Arguments

<code>.data</code>	a Coo, Coe, PCA object
<code>...</code>	logical conditions

Details

`dplyr` verbs are maintained.

Value

a Momocs object of the same class.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [subsetize\(\)](#)

Examples

```
olea
slice(olea, 1) # if you only want the coordinates, try bot[1]
slice(olea, 1:20)
slice(olea, 21:30)
```

slidings_scheme	<i>Extracts partitions of sliding coordinates</i>
-----------------	---

Description

Helper function that deduces (likely to be a reminder) partition scheme from \$slidings of Ldk objects.

Usage

```
slidings_scheme(Coo)
```

Arguments

Coo an Ldk object

Value

a list with two components: n the number of partition; id their position. Or a NULL if no slidings are defined

See Also

Other ldk/slidings methods: [add_ldk\(\)](#), [def_ldk\(\)](#), [def_slidings\(\)](#), [get_ldk\(\)](#), [get_slidings\(\)](#), [rearrange_ldk\(\)](#)

Examples

```
# no slidings defined a NULL is returned with a message
slidings_scheme(wings)

# slidings defined
slidings_scheme(chaff)
```

stack	<i>Family picture of shapes</i>
-------	---------------------------------

Description

Plots all the outlines, on the same graph, from a Coo ([Out](#), [Opn](#) or [Ldk](#)) object.

Usage

```
## S3 method for class 'Coo'
stack(
  x,
  cols,
  borders,
  fac,
  palette = col_summer,
  coo_sample = 120,
  points = FALSE,
  first.point = TRUE,
  centroid = TRUE,
  ldk = TRUE,
  ldk_pch = 3,
  ldk_col = "#FF000055",
  ldk_cex = 0.5,
  ldk_links = FALSE,
  ldk_confell = FALSE,
  ldk_contour = FALSE,
  ldk_chull = FALSE,
  ldk_labels = FALSE,
  xy.axis = TRUE,
  title = substitute(x),
  ...
)

## S3 method for class 'Ldk'
stack(
  x,
  cols,
  borders,
  first.point = TRUE,
  centroid = TRUE,
  ldk = TRUE,
  ldk_pch = 20,
  ldk_col = col_alpha("#000000", 0.5),
  ldk_cex = 0.3,
  meanshape = FALSE,
  meanshape_col = "#FF0000",
  ldk_links = FALSE,
  ldk_confell = FALSE,
  ldk_contour = FALSE,
  ldk_chull = FALSE,
  ldk_labels = FALSE,
  slidings = TRUE,
  slidings_pch = "",
  xy.axis = TRUE,
  title = substitute(x),
```

```
    ...
  )
```

Arguments

<code>x</code>	The Coo object to plot.
<code>cols</code>	A vector of colors for drawing the outlines. Either a single value or of length exactly equals to the number of coordinates.
<code>borders</code>	A vector of colors for drawing the borders. Either a single value or of length exactly equals to the number of coordinates.
<code>fac</code>	a factor within the <code>\$fac</code> slot for colors
<code>palette</code>	a color palette to use when <code>fac</code> is provided
<code>coo_sample</code>	if not NULL the number of point per shape to display (to plot quickly)
<code>points</code>	logical whether to draw or not points
<code>first.point</code>	logical whether to draw or not the first point
<code>centroid</code>	logical whether to draw or not the centroid
<code>ldk</code>	logical. Whether to display landmarks (if any).
<code>ldk_pch</code>	pch for these landmarks
<code>ldk_col</code>	color for these landmarks
<code>ldk_cex</code>	cex for these landmarks
<code>ldk_links</code>	logical whether to draw links (of the mean shape)
<code>ldk_confell</code>	logical whether to draw conf ellipses
<code>ldk_contour</code>	logical whether to draw contour lines
<code>ldk_chull</code>	logical whether to draw convex hull
<code>ldk_labels</code>	logical whether to draw landmark labels
<code>xy.axis</code>	whether to draw or not the x and y axes
<code>title</code>	a title for the plot. The name of the Coo by default
<code>...</code>	further arguments to be passed to coo_plot
<code>meanshape</code>	logical whether to add meanshape related stuff (below)
<code>meanshape_col</code>	a color for everything meanshape
<code>slidings</code>	logical whether to draw slidings semi landmarks
<code>slidings_pch</code>	pch for semi landmarks

See Also

Other Coo_graphics: [inspect\(\)](#), [panel\(\)](#)

Examples

```
## Not run:
stack(bot)
bot.f <- efourier(bot, 12)
stack(bot.f)
stack(mosquito, borders='#1A1A1A22', first.point=FALSE)
stack(hearts)
stack(hearts, ldk=FALSE)
stack(hearts, borders='#1A1A1A22', ldk=TRUE, ldk_col=col_summer(4), ldk_pch=20)
stack(hearts, fac="aut", palette=col_sari)

chaffal <- fgProcrustes(chaff)
stack(chaffal, slidings=FALSE)
stack(chaffal, meanshape=TRUE, meanshape_col="blue")

## End(Not run)
```

subsetize

Subsetize various Momocs objects

Description

Subsetize is a wrapper around dplyr's verbs and should NOT be used directly.

Usage

```
subsetize(x, subset, ...)
```

Arguments

x	a Coo or a Coe object.
subset	logical taken from the \$fac slot, or indices. See examples.
...	useless here but maintains consistence with the generic subset.

See Also

Other handling functions: [arrange\(\)](#), [at_least\(\)](#), [chop\(\)](#), [combine\(\)](#), [dissolve\(\)](#), [fac_dispatcher\(\)](#), [filter\(\)](#), [mutate\(\)](#), [rename\(\)](#), [rescale\(\)](#), [rm_harm\(\)](#), [rm_missing\(\)](#), [rm_uncomplete\(\)](#), [rw_fac\(\)](#), [sample_frac\(\)](#), [sample_n\(\)](#), [select\(\)](#), [slice\(\)](#)

Examples

```
# Do not use subset directly
```

symmetry

Calculates symmetry indices on OutCoe objects

Description

For [OutCoe](#) objects obtained with [efourier](#), calculates several indices on the matrix of coefficients: AD, the sum of absolute values of harmonic coefficients A and D; BC same thing for B and C; amp the sum of the absolute value of all harmonic coefficients and sym which is the ratio of AD over amp. See references below for more details.

Usage

```
symmetry(OutCoe)
```

Arguments

OutCoe [efourier](#) objects

Value

a matrix with 4 columns described above.

Note

What we call symmetry here is bilateral symmetry. By comparing coefficients resulting from [efourier](#), with AD responsible for amplitude of the Fourier functions, and BC for their phase, it results in the plane and for fitted/reconstructed shapes that symmetry. As long as your shapes are aligned along their bilateral symmetry axis, you can use the approach coined by Iwata et al., and here implemented in Momocs.

References

Below: the first mention, and two applications.

#'

- Iwata, H., Niikura, S., Matsuura, S., Takano, Y., & Ukai, Y. (1998). Evaluation of variation of root shape of Japanese radish (*Raphanus sativus* L.) based on image analysis using elliptic Fourier descriptors. *Euphytica*, 102, 143-149.
- Iwata, H., Nesumi, H., Ninomiya, S., Takano, Y., & Ukai, Y. (2002). The Evaluation of Genotype x Environment Interactions of Citrus Leaf Morphology Using Image Analysis and Elliptic Fourier Descriptors. *Breeding Science*, 52(2), 89-94. doi:10.1270/jsbbs.52.89
- Yoshioka, Y., Iwata, H., Ohsawa, R., & Ninomiya, S. (2004). Analysis of petal shape variation of *Primula sieboldii* by elliptic fourier descriptors and principal component analysis. *Annals of Botany*, 94(5), 657-64. doi:10.1093/aob/mch190

See Also

[rm_asym](#) and [rm_sym](#).

Examples

```
bot.f <- efourier(bot, 12)
res <- symmetry(bot.f)
hist(res[, 'sym'])
```

 tfourier

Tangent angle Fourier transform

Description

tfourier computes tangent angle Fourier analysis from a matrix or a list of coordinates.

Usage

```
tfourier(x, ...)

## Default S3 method:
tfourier(x, nb.h, smooth.it = 0, norm = FALSE, ...)

## S3 method for class 'Out'
tfourier(x, nb.h = 40, smooth.it = 0, norm = TRUE, ...)

## S3 method for class 'list'
tfourier(x, ...)
```

Arguments

x	A list or matrix of coordinates or an Out
...	useless here
nb.h	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.
smooth.it	integer. The number of smoothing iterations to perform
norm	logical. Whether to scale and register new coordinates so that the first point used is sent on the origin.

Value

A list with the following components:

- ao ao harmonic coefficient
- an vector of $a_{1 \rightarrow n}$ harmonic coefficients
- bn vector of $b_{1 \rightarrow n}$ harmonic coefficients
- phi vector of variation of the tangent angle
- t vector of distance along the perimeter expressed in radians
- perimeter numeric. The perimeter of the outline

- thetao numeric. The first tangent angle
- x1 The x-coordinate of the first point
- y1 The y-coordinate of the first point.

Note

Silent message and progress bars (if any) with options("verbose"=FALSE).

Directly borrowed for Claude (2008), and called `fourier2` there.

References

Zahn CT, Roskies RZ. 1972. Fourier Descriptors for Plane Closed Curves. *IEEE Transactions on Computers* **C-21**: 269-281.

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other tfourier: [tfourier_i\(\)](#), [tfourier_shape\(\)](#)

Examples

```

coo <- bot[1]
coo_plot(coo)
tf <- tfourier(coo, 12)
tf
tfi <- tfourier_i(tf)
coo_draw(tfi, border='red', col=NA) # the outline is not closed...
coo_draw(tfourier_i(tf, force2close=TRUE), border='blue', col=NA) # we force it to close.

```

tfourier_i

Inverse tangent angle Fourier transform

Description

`tfourier_i` uses the inverse tangent angle Fourier transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [tfourier](#).

Usage

```

tfourier_i(
  tf,
  nb.h,
  nb.pts = 120,
  force2close = FALSE,
  rescale = TRUE,
  perim = 2 * pi,
  thetao = 0
)

```

Arguments

tf	a list with ao, an and bn components, typically as returned by tfourier
nb.h	integer. The number of harmonics to calculate/use
nb.pts	integer. The number of points to calculate
force2close	logical. Whether to force the outlines calculated to close (see coo_force2close).
rescale	logical. Whether to rescale the points calculated so that their perimeter equals <code>perim</code> .
perim	The perimeter length to rescale shapes.
thetao	numeric. Radius angle to the reference (in radians)

Details

See [tfourier](#) for the mathematical background.

Value

A list with components:

x	vector of x-coordinates.
y	vector of y-coordinates.
phi	vector of interpolated changes on the tangent angle.
angle	vector of position on the perimeter (in radians).

Note

Directly borrowed for Claude (2008), and called `ifourier2` there.

References

Zahn CT, Roskies RZ. 1972. Fourier Descriptors for Plane Closed Curves. *IEEE Transactions on Computers* **C-21**: 269-281.

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other tfourier: [tfourier_shape\(\)](#), [tfourier\(\)](#)

Examples

```
tfourier(bot[1], 24)
tfourier_shape()
```

tfourier_shape *Calculates and draws 'tfourier' shapes.*

Description

tfourier_shape calculates a 'Fourier tangent angle shape' given Fourier coefficients (see Details) or can generate some 'tfourier' shapes.

Usage

```
tfourier_shape(an, bn, ao = 0, nb.h, nb.pts = 80, alpha = 2, plot = TRUE)
```

Arguments

an	numeric. The a_n Fourier coefficients on which to calculate a shape.
bn	numeric. The b_n Fourier coefficients on which to calculate a shape.
ao	ao Harmonic coefficient.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see Details).
plot	logical. Whether to plot or not the shape.

Value

A matrix of (x; y) coordinates.

References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

See Also

Other tfourier: [tfourier_i\(\)](#), [tfourier\(\)](#)

Examples

```
tf <- tfourier(bot[1], 24)
tfourier_shape(tf$an, tf$bn) # equivalent to rfourier_i(rf)
tfourier_shape()
tfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)
panel(Out(a2l(replicate(100,
  coo_force2close(tfourier_shape(nb.h=6, alpha=2, nb.pts=200, plot=FALSE)))))) # biological shapes
```

tie_jpg_txt	<i>Binds .jpg outlines from .txt landmarks taken on them</i>
-------------	--

Description

Given a list of files (lf) that includes matching filenames with .jpg (black masks) and .txt (landmark positions on them as .txt), returns an Out with \$ldk defined. Typically be useful if you use ImageJ to define landmarks on your outlines.

Usage

```
tie_jpg_txt(lf)
```

Arguments

lf	a list of filenames
----	---------------------

Note

Not optimized (images are read twice). Please do not hesitate to contact me should you have a particular case or need something.

See Also

Other babel functions: [lf_structure\(\)](#)

tps2d	<i>Thin Plate Splines for 2D data</i>
-------	---------------------------------------

Description

tps2d is the core function for Thin Plate Splines. It is used internally for all TPS graphical functions. tps_apply is the very same function but with arguments properly named (I maintain tps2d as it is for historical reasons) when we want to apply a transformation grid.

Usage

```
tps2d(grid0, fr, to)
```

```
tps_apply(fr, to, new)
```

Arguments

grid0	a matrix of coordinates on which to calculate deformations
fr	the reference shape
to	the target shape
new	the shape on which to apply the shp1->shp2 calibrated tps transformation

Value

a shape.

See Also

Other thin plate splines: [tps_arr\(\)](#), [tps_grid\(\)](#), [tps_iso\(\)](#), [tps_raw\(\)](#)

Examples

```
shapes <- shapes %>%
  coo_scale() %>% coo_center() %>%
  coo_slidedirection("up") %>%
  coo_sample(64)

leaf1 <- shapes[14]
leaf2 <- shapes[15]

# tps grid on the two leafs2
tps_grid(leaf1, leaf2)
# apply the (leaf1 -> leaf2) tps tranformation onto leaf1
# (that thus get closer to leaf2)
tps_apply(leaf1, leaf2, leaf1) %>% coo_draw(bor="purple")
```

 tps_arr

Deformation 'vector field' using Thin Plate Splines

Description

tps_arr(ows) calculates deformations between two configurations and illustrate them using arrows.

Usage

```
tps_arr(
  fr,
  to,
  amp = 1,
  grid = TRUE,
  over = 1.2,
  palette = col_summer,
  arr.nb = 200,
  arr.levels = 100,
  arr.len = 0.1,
  arr.ang = 20,
  arr.lwd = 0.75,
  arr.col = "grey50",
  poly = TRUE,
```



```

shp = TRUE,
shp.col = rep(NA, 2),
shp.border = col_qual(2),
shp.lwd = c(2, 2),
shp.lty = c(1, 1),
legend = TRUE,
legend.text,
...
)

```

Arguments

fr	the reference $(x; y)$ coordinates
to	the target $(x; y)$ coordinates
amp	an amplification factor of differences between fr and to
grid	whether to calculate and plot changes across the graphical window TRUE or just within the starting shape (FALSE)
over	numeric that indicates how much the thin plate splines extends over the shapes
palette	a color palette such those included in Momocs or produced with colorRamp-Palette
arr.nb	numeric The number of arrows to calculate
arr.levels	numeric. The number of levels for the color of arrows
arr.len	numeric for the length of arrows
arr.ang	numeric for the angle for arrows' heads
arr.lwd	numeric for the lwd for drawing arrows
arr.col	if palette is not used the color for arrows
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. whether to draw shapes
shp.col	two colors for filling the shapes
shp.border	two colors for drawing the borders
shp.lwd	two lwd for drawing shapes
shp.lty	two lty fro drawing the shapes
legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed coo_draw

Value

Nothing.

See Also

Other thin plate splines: [tps2d\(\)](#), [tps_grid\(\)](#), [tps_iso\(\)](#), [tps_raw\(\)](#)

Examples

```

botF <- efourier(bot)
x <- MSHAPES(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_arr(fr, to, arr.nb=200, palette=col_sari, amp=3)
tps_arr(fr, to, arr.nb=200, palette=col_sari, amp=3, grid=FALSE)

```

tps_grid

Deformation grids using Thin Plate Splines

Description

tps_grid calculates and plots deformation grids between two configurations.

Usage

```

tps_grid(
  fr,
  to,
  amp = 1,
  over = 1.2,
  grid.size = 15,
  grid.col = "grey80",
  poly = TRUE,
  shp = TRUE,
  shp.col = rep(NA, 2),
  shp.border = col_qual(2),
  shp.lwd = c(1, 1),
  shp.lty = c(1, 1),
  legend = TRUE,
  legend.text,
  ...
)

```

Arguments

fr	the reference ($x; y$) coordinates
to	the target ($x; y$) coordinates
amp	an amplification factor of differences between fr and to
over	numeric that indicates how much the thin plate splines extends over the shapes
grid.size	numeric to specify the number of grid cells on the longer axis on the outlines
grid.col	color for drawing the grid
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. Whether to draw shapes

shp.col	Two colors for filling the shapes
shp.border	Two colors for drawing the borders
shp.lwd	Two lwd for drawing shapes
shp.lty	Two lty fro drawing the shapes
legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed coo_draw

Value

Nothing

See Also

Other thin plate splines: [tps2d\(\)](#), [tps_arr\(\)](#), [tps_iso\(\)](#), [tps_raw\(\)](#)

Examples

```
botF <- efourier(bot)
x <- MSHAPES(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_grid(fr, to, amp=3, grid.size=10)
```

 tps_iso

Deformation isolines using Thin Plate Splines.

Description

tps_iso calculates deformations between two configurations and map them with or without iso-lines.

Usage

```
tps_iso(
  fr,
  to,
  amp = 1,
  grid = FALSE,
  over = 1.2,
  palette = col_spring,
  iso.nb = 1000,
  iso.levels = 12,
  cont = TRUE,
  cont.col = "black",
  poly = TRUE,
```

```

shp = TRUE,
shp.border = col_qual(2),
shp.lwd = c(2, 2),
shp.lty = c(1, 1),
legend = TRUE,
legend.text,
...
)

```

Arguments

fr	The reference $(x; y)$ coordinates
to	The target $(x; y)$ coordinates
amp	An amplification factor of differences between fr and to
grid	whether to calculate and plot changes across the graphical window TRUE or just within the starting shape (FALSE)
over	A numeric that indicates how much the thin plate splines extends over the shapes
palette	A color palette such those included in Momocs or produced with colorRamp-Palette
iso.nb	A numeric. The number of points to use for the calculation of deformation
iso.levels	numeric. The number of levels for mapping the deformations
cont	logical. Whether to draw contour lines
cont.col	A color for drawing the contour lines
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. Whether to draw shapes
shp.border	Two colors for drawing the borders
shp.lwd	Two lwd for drawing shapes
shp.lty	Two lty fro drawing the shapes
legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed coo_draw

Value

No returned value

See Also

Other thin plate splines: [tps2d\(\)](#), [tps_arr\(\)](#), [tps_grid\(\)](#), [tps_raw\(\)](#)

Examples

```

botF <- efourier(bot)
x <- MSHAPES(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_iso(fr, to, iso.nb=200, amp=3)
tps_iso(fr, to, iso.nb=200, amp=3, grid=TRUE)

```

tps_raw

*Vanilla Thin Plate Splines***Description**

tps_raw calculates deformation grids and returns position of sampled points on it.

Usage

```
tps_raw(fr, to, amp = 1, over = 1.2, grid.size = 15)
```

Arguments

fr	the reference ($x; y$) coordinates
to	the target ($x; y$) coordinates
amp	an amplification factor of differences between fr and to
over	numeric that indicates how much the thin plate splines extends over the shapes
grid.size	numeric to specify the number of grid cells on the longer axis on the outlines

Value

a list with two components: grid the xy coordinates of sampled points along the grid; dim the dimension of the grid.

See Also

Other thin plate splines: [tps2d\(\)](#), [tps_arr\(\)](#), [tps_grid\(\)](#), [tps_iso\(\)](#)

Examples

```

## Not run:
ms <- MSHAPES(efourier(bot, 10), "type")
b <- ms$shp$beer
w <- ms$shp$whisky
g <- tps_raw(b, w)
ldk_plot(g$grid)

# a wavy plot
ldk_plot(g$grid, pch=NA)

```

```
cols_ids <- 1:g$dim[1]
for (i in 1:g$dim[2]) lines(g$grid[cols_ids + (i-1)*g$dim[1], ])

## End(Not run)
```

TraCoe *Traditional morphometrics class*

Description

Defines the builder for traditional measurement class in Momocs. Is intended to ease calculations, data handling and multivariate statistics just ad the other Momocs' classes

Usage

```
TraCoe(coe = matrix(), fac = dplyr::tibble())
```

Arguments

coe a matrix of measurements
 fac a data.frame for covariates

See Also

Other classes: [Coe\(\)](#), [Coo\(\)](#), [Ldk\(\)](#), [OpnCoe\(\)](#), [Opn\(\)](#), [OutCoe\(\)](#), [Out\(\)](#)

Examples

```
# let's (more or less) rebuild the flower dataset
fl <- TraCoe(iris[, 1:4], dplyr::tibble(sp=iris$Species))
fl %>% PCA() %>% plot("sp")
```

trilo *Data: Outline coordinates of cephalic outlines of trilobite*

Description

Data: Outline coordinates of cephalic outlines of trilobite

Format

A [Out](#) object 64 coordinates of 50 cephalic outlines from different ontogenetic stages of trilobite.

Source

Arranged from: <https://folk.universitetetioslo.no/> (used to be in ohammer website but seems to be deprecated now). The original data included 51 outlines and 5 ontogenetic stages, but one of them has just a single outline thas has been removed.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [wings](#)

verify	<i>Validates Coo objects</i>
--------	------------------------------

Description

No validation for S3 objects, so this method is a (cheap) attempt at checking [Coo](#) objects, [Out](#), [Opn](#) and [Ldk](#) objects.

Usage

```
verify(Coo)
```

Arguments

Coo	any Coo object
-----	----------------

Details

Implemented before all morphometric methods and handling verbs. To see what is checked, try eg `Momocs:::verify.Coo`

Value

a Coo object.

Examples

```
## Not run:
verify(bot)
bot[12] <- NA
verify(bot)

verify(hearts)
hearts$ldk[[4]] <- c(1, 2)
verify(hearts)

## End(Not run)
```

which_out	<i>Identify outliers</i>
-----------	--------------------------

Description

A simple wrapper around `dnorm` that helps identify outliers. In particular, it may be useful on `Coe` object (in this case a PCA is first calculated) and also on `Ldk` for detecting possible outliers on freshly digitized/imported datasets.

Usage

```
which_out(x, conf, nax, ...)
```

Arguments

<code>x</code>	object, either <code>Coe</code> or a numeric on which to search for outliers
<code>conf</code>	confidence for <code>dnorm</code> (1e-3 by default)
<code>nax</code>	number of axes to retain (only for <code>Coe</code>), if <1 retain enough axes to retain this proportion of the variance
<code>...</code>	additional parameters to be passed to PCA (only for <code>Coe</code>)

Note

experimental. `dnorm` parameters used are `median(x)`, `sd(x)`

Examples

```
# on a numeric
x <- rnorm(10)
x[4] <- 99
which_out(x)

# on a Coe
bf <- bot %>% efourier(6)
bf$coe[c(1, 6), 1] <- 5
which_out(bf)

# on Ldk
w_no <- w_ok <- wings
w_no$coo[[2]][1, 1] <- 2
w_no$coo[[6]][2, 2] <- 2
which_out(w_ok, conf=1e-12) # with low conf, no outliers
which_out(w_no, conf=1e-12) # as expected

# a way to illustrate, filter outliers
# conf has been chosen deliberately low to show some outliers
x_f <- bot %>% efourier
x_p <- PCA(x_f)
```



```
# which are outliers (conf is ridiculously low here)
which_out(x_p$x[, 1], 0.5)
cols <- rep("black", nrow(x_p$x))
outliers <- which_out(x_p$x[, 1], 0.5)
cols[outliers] <- "red"
plot(x_p, col=cols)
# remove them for Coe, rePCA, replot
x_f %>% slice(-outliers) %>% PCA %>% plot

# or directly with which_out.Coe
# which relies on a PCA
outliers <- x_f %>% which_out(0.5, nax=0.95) %>% na.omit()
x_f %>% slice(-outliers) %>% PCA %>% plot
```

wings

Data: Landmarks coordinates of mosquito wings

Description

Data: Landmarks coordinates of mosquito wings

Format

A [Ldk](#) object containing 18 (x; y) landmarks from 127 mosquito wings, from

Source

Rohlf and Slice 1990.

See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#)

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