Package ‘Rdsdp’

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Title R Interface to DSDP Semidefinite Programming Library

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Description R interface to DSDP semidefinite programming library. The DSDP software is a free open source implementation of an interior-point method for semidefinite programming. It provides primal and dual solutions, exploits low-rank structure and sparsity in the data, and has relatively low memory requirements for an interior-point method.

Imports utils, methods

LazyLoad yes

License GPL-3

URL http://www.mcs.anl.gov/hs/software/DSDP

NeedsCompilation yes

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R topics documented:

Rdsdp *R interface to DSDP semidefinite programming library*

Description

Rdsdp is the R package providing a R interface to DSDP semidefinite programming library. The DSDP package implements a dual-scaling algorithm to find solutions (X, y) to linear and semidefinite optimization problems of the form

$$\text{(P)} \ \inf \ \text{tr}(CX)$$

$$\text{subject to } \mathcal{A}X = b$$

$$X \succeq 0$$

with $(\mathcal{A}X)_i = \text{tr}(A_i X)$ where $X \succeq 0$ means X is positive semidefinite, C and all A_i are symmetric matrices of the same size and b is a vector of length m.

The dual of the problem is

$$\text{(D)} \ \sup \ b^T y$$

$$\text{subject to } \mathcal{A}^* y + S = C$$

$$S \succeq 0$$

where $\mathcal{A}y = \sum_{i=1}^{m} y_i A_i$.

Matrices C and A_i are assumed to be block diagonal structured, and must be specified that way (see Details).

References

- http://www.mcs.anl.gov/hs/software/DSDP/
- Steven J. Benson and Yinyu Ye:
  Algorithm 875: DSDP5 software for semidefinite programming ACM Transactions on Mathematical Software (TOMS) 34(3), 2008
  http://web.stanford.edu/~yyye/DSDP5-Paper.pdf
- Steven J. Benson and Yinyu Ye and Xiong Zhang:
  Solving Large-Scale Sparse Semidefinite Programs for Combinatorial Optimization SIAM Journal on Optimization 10(2):443-461, 2000
  http://web.stanford.edu/~yyye/yyye/largesdp.ps.gz

Rdsdp::dsdp *Solve semidefinite programm with DSDP*

Description

Interface to DSDP semidefinite programming library.

Usage

```
dsdp(A,b,C,K,OPTIONS=NULL)
```

Arguments

- `A` — An object of class `"matrix"` with m rows defining the block diagonal constraint matrices A_i. Each constraint matrix A_i is specified by a row of A as explained in the Details section.
- `b` — A numeric vector of length m containg the right hand side of the constraints.
- `C` — An object of class `"matrix"` with one row or a valid class from the class hierarchy in the `"Matrix"` package. It defines the objective coefficient matrix C with the same structure of `A` as explained above.
- `K` — Describes the sizes of each block of the sdp problem. It is a list with the following elements:
  - **`"s"`:** A vector of integers listing the dimension of positive semidefinite cone blocks.
  - **`"l"`:** A scaler integer indicating the dimension of the linear nonnegative cone block.
- `OPTIONS` — A list of OPTIONS parameters passed to dsdp. It may contain any of the following fields:
  - **print:** `= k` to display output at each k iteration, else = 0 [default 10].
  - **logsummary:** `= 1` print timing information if set to 1.
  - **save:** to set the filename to save solution file in SDPA format.
  - **outputstats:** `= 1` to output full information about the solution statistics in STATS.
  - **gaptol:** tolerance for duality gap as a fraction of the value of the objective functions [default 1e-6].
  - **maxit:** maximum number of iterations allowed [default 1000].

  Please refer to DSDP User Guide for additional OPTIONS parameters available.

Details

All problem matrices are assumed to be of block diagonal structure, the input matrix `A` must be specified as follows:

1. The coefficients for nonnegative cone block are put in the first `K$l` columns of `A`.

2. The coefficients for positive semidefinite cone blocks are put after nonnegative cone block in the the same order as those in `K$s`. The `i`th positive semidefinite cone block takes `(K$s)[i]` times `(K$s)[[i]]` columns, with each row defining a symmetric matrix of size `(K$s)[[i]]`.

This function does not check for symmetry in the problem data.

Value

Returns a list of three objects:

`X` Optimal primal solution X. A vector containing blocks in the same structure as explained above.

`y` Optimal dual solution y. A vector of the same length as argument `b`

`STATS` A list with three to eight fields that describe the solution of the problem:

stype: `PDFeasible` if the solutions to both (D) and (P) are feasible, `Infeasible` if (D) is infeasible, and `Unbounded` if (D) is unbounded.

dobj: objective value of (D).

pobj: objective value of (P).

r: the multiple of the identity element added to $C - \mathcal{A}^* y$ in the final solution to make S positive definite.

mu: the final barrier parameter ν.

pstep: the final step length in (P)

dstep: the final step length in (D)

pnorm: the final value $\|P(\nu)\|$.

The last five fields are optional, and only available when `OPTIONS$outputstats` is set to 1.

References

- Steven J. Benson and Yinyu Ye:
  DSDP5 User Guide — Software for Semidefinite Programming Technical Report ANL/MCS-TM-277, 2005
  http://www.mcs.anl.gov/hs/software/DSDP/DSDP5-Matlab-UserGuide.pdf

Examples

```
K=NULL
K$s=c(2,3)
K$l=2

C=matrix(c(0,0,2,1,1,2,c(3,0,1,
                       0,2,0,
                       1,0,3)),1,15,byrow=TRUE)
A=matrix(c(0,1,0,0,0,0,c(3,0,1,
                         0,4,0,
                         1,0,5),
           1,0,3,1,1,3,rep(0,9)), 2,15,byrow=TRUE)
b <- c(1,2)
```

```
OPTIONS=NULL
OPTIONS$gaptol=0.000001
OPTIONS$logsummary=0
OPTIONS$outputstats=1

result = dsdp(A,b,C,K,OPTIONS)
```

`Rdsdp::dsdp.readsdpa` *Solving semidefinite programs reading from SDPA format files.*

Description

Function to read the semidefinite program input data in SDPA format and solve it.

Usage

```
dsdp.readsdpa(sdpa_filename, options_filename="")
```

Arguments

`sdpa_filename` The location of the SDPA input file.

`options_filename` The location of the OPTIONS file [default ""].

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